

BSDEs with weak terminal conditions

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Joint work with R. Elie and A. Réveillac

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Problem formulation

- Given Ψ and m , find the minimal solution (Y, Z) to

$$Y_t \geq Y_T + \int_t^T g(s, Y_s, Z_s) ds - \int_t^T Z_s dW_s, \quad t \in [0, T]$$

satisfying

$$E[\Psi(Y_T)] \geq m.$$

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- “Weak terminal condition” : no fixed terminal condition, but a constraint in expectation.
- Can look at it forward : stochastic target problem under controlled loss (B., Elie and Touzi 2009)

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- ⇒ Generalize previous results of B., Elie and Touzi (09) and Föllmer and Leukert (99,00).

Generalization and Standard assumptions

□ Given $\mu \in L^0(\mathcal{F}_T, [0, 1])$, let $\Gamma(\tau, \mu)$ denote the set of super-solutions Y of

$$Y_{t \vee \tau} \geq Y_T + \int_{t \vee \tau}^T g(s, Y_s, Z_s) ds - \int_{t \vee \tau}^T Z_s dW_s, \quad t \in [0, T]$$

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- Assumptions on Ψ : For \mathbb{P} - a.e. $\omega \in \Omega$, $y \in \mathbb{R} \mapsto \Psi(\omega, y)$ is non-decreasing and valued in $[0, 1] \cup \{-\infty\}$, its right-inverse $\Phi : \Omega \times [0, 1] \mapsto [0, 1]$ is measurable.

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- Assumptions on g : Predictable for fixed (y, z) and uniformly Lipschitz in (y, z) .

Problem reduction

□ Let $\mathbf{A}_{\tau, \mu}$ be the set elements $\alpha \in \mathbf{H}_2$ such that

$$M^{(\tau, \mu), \alpha} := \mu + \int_{\tau}^{\tau \vee \cdot} \alpha_s dW_s \text{ takes values in } [0, 1]$$

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and let $(Y^{(\tau, \mu), \alpha}, Z^{(\tau, \mu), \alpha})$ be the solution of

$$Y_{t \vee \tau} = \Phi(M_T^{(\tau, \mu), \alpha}) + \int_{t \vee \tau}^T g(s, Y_s, Z_s) ds - \int_{t \vee \tau}^T Z_s dW_s, \quad t \in [0, T]$$

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□ **Proposition :**

$$Y \in \Gamma(\tau, \mu) \Leftrightarrow Y = Y^{(\tau, \mu), \alpha} \text{ for some } \alpha \in \mathbf{A}_{\tau, \mu}$$

and

$$\text{essinf } \Gamma(\tau, \mu) = \mathcal{Y}_{\tau}(\mu) := \text{essinf} \{ Y_{\tau}^{(\tau, \mu), \alpha}, \alpha \in \mathbf{A}_{\tau, \mu} \}$$

Representation for the minimal supersolution

□ Given $m_o \in [0, 1]$ fixed, we can look at the minimal condition under each path $M^\alpha := M^{(0, m_o), \alpha}$, $\alpha \in \mathbf{A}_{0, m_o} =: \mathbf{A}_0$:

$$\mathcal{Y}^\alpha := \mathcal{Y} \cdot (M^\alpha)$$

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□ **Theorem** : For $\alpha \in \mathbf{A}_0$, \mathcal{Y}^α is indistinguishable from a $\text{l\`a}d\text{l\`a}g$ g -submartingale, and

(i) $\mathcal{Y}_{\tau_1}^\alpha = \text{ess inf}_{\bar{\alpha} \in \mathbf{A}_{\tau_1}^\alpha} \mathcal{E}_{\tau_1, \tau_2}^g[\mathcal{Y}_{\tau_2}^{\bar{\alpha}}]$, for each $\tau_1 \leq \tau_2 \in \mathcal{T}$.

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Under the additional assumption that

$m \in [0, 1] \mapsto \Phi(\omega, m)$ is continuous for \mathbb{P} -a.e. $\omega \in \Omega$,

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- (ii) \mathcal{Y}^α is indistinguishable from a càdlàg g -submartingale, for each $\alpha \in \mathbf{A}_0$.

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- (ii) \mathcal{Y}^α is indistinguishable from a càdlàg g -submartingale, for each $\alpha \in \mathbf{A}_0$.
- (iii) There exists a (unique non-anticipating) family $(\mathcal{Z}^\alpha, \mathcal{K}^\alpha)_{\alpha \in \mathbf{A}_0} \subset \mathbf{H}_2 \times \mathbf{K}_2$ s.t.

$$\mathcal{Y}^\alpha = \Phi(M_T^\alpha) + \int_0^T g(s, \mathcal{Y}_s^\alpha, \mathcal{Z}_s^\alpha) ds - \int_0^T \mathcal{Z}_s^\alpha dW_s + \mathcal{K}^\alpha - \mathcal{K}_T^\alpha$$

$$\mathcal{K}_{\tau_1}^\alpha = \operatorname{ess\,inf}_{\bar{\alpha} \in \mathbf{A}_{\tau_1}^\alpha} E[\mathcal{K}_{\tau_2}^{\bar{\alpha}} | \mathcal{F}_{\tau_1}], \quad \forall \tau_1 \leq \tau_2 \in \mathcal{T}.$$

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- Rem : Similar representation as for 2BSDEs (cf. Soner, Touzi and Zhang 2011).

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- Rem : It g and Φ are convex a.s., then the essinf over α is achieved by some $\hat{\alpha}$ and $\mathcal{Y}^{\hat{\alpha}} = \text{essinf } \Gamma(\cdot, M^{\hat{\alpha}})$.

Continuity in the μ -parameter

A modulus of continuity :

$$Err_t(\eta) := \text{esssup} \left\{ \mathcal{R}_t(M, M') : M, M' \in \mathbf{L}_0([0, 1]), E_t[|M - M'|^2] \leq \eta \right\},$$

in which

$$\mathcal{R}_t(M, M') := |\mathcal{E}_t^g[\Phi(M)] - \mathcal{E}_t^g[\Phi(M')]|.$$

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□ **Proposition** : Fix $t < T$, $\mu_1, \mu_2 \in \mathbf{L}_0([0, 1], \mathcal{F}_t)$. Then,

$$|\mathcal{Y}_t(\mu_1) - \mathcal{Y}_t(\mu_2)| \leq Err_t(\Delta(\mu_1, \mu_2)) + Err_t(\Delta(\mu_2, \mu_1)),$$

where

$$\Delta(\mu_i, \mu_j) := \left(1 - \frac{\mu_i}{\mu_j}\right) \mathbf{1}_{\{\mu_i < \mu_j\}} + \frac{\mu_i - \mu_j}{1 - \mu_j} \mathbf{1}_{\{\mu_i > \mu_j\}}, \quad i, j = 1, 2.$$

Continuity in the μ -parameter

Moreover, on $\{\mu_1 = 0\}$:

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and, on $\{\mu_1 = 1\}$:

$$\begin{aligned} & |\mathcal{Y}_t(\mu_1) - \mathcal{Y}_t(\mu_2)| \\ & \leq \text{esssup} \{ \mathcal{R}_t(1, M) : M \in \mathbf{L}_0([0, 1]) , E_t[|1 - M|^2] \leq 1 - \mu_2 \} . \end{aligned}$$

Convexity and convexification in the μ -parameter

Definition [\mathcal{F}_t -convexity]

- (i) $D \subset \mathbf{L}_\infty(\mathbb{R}, \mathcal{F}_t)$ is \mathcal{F}_t -convex if $\lambda\mu_1 + (1 - \lambda)\mu_2 \in D$, $\forall \mu_1, \mu_2 \in D$ and $\lambda \in \mathbf{L}_0([0, 1], \mathcal{F}_t)$.
- (ii) Let D be a \mathcal{F}_t -convex subset of $\mathbf{L}_\infty(\mathbb{R}, \mathcal{F}_t)$. A map $\mathcal{J} : D \mapsto \mathbf{L}_2(\mathbb{R}, \mathcal{F}_t)$ is said to be \mathcal{F}_t -convex if

$$\text{Epi}(\mathcal{J}) := \{(\mu, Y) \in D \times \mathbf{L}_2(\mathbb{R}, \mathcal{F}_t) : Y \geq \mathcal{J}(\mu)\}$$

is \mathcal{F}_t -convex.

- (iii) Let $\text{Epi}^c(\mathcal{Y}_t) = \mathcal{F}_t\text{-conv}(\text{Epi}(\mathcal{Y}_t))$ and $\overline{\text{Epi}^c}(\mathcal{Y}_t)$ its closure in \mathbf{L}_2 . Then,

$$\mathcal{Y}_t^c(\mu) := \text{essinf}\{Y \in \mathbf{L}_2(\mathbb{R}, \mathcal{F}_t) : (\mu, Y) \in \overline{\text{Epi}^c}(\mathcal{Y}_t)\}$$

is the \mathcal{F}_t -convex envelope of \mathcal{Y}_t .

Convexity and convexification in the μ -parameter

□ **Proposition** : Assume that $\mathcal{Y} = \mathcal{Y}_{\cdot,+}$. Then, the map

$$\mu \in \mathbf{L}_0([0, 1], \mathcal{F}_t) \mapsto \mathcal{Y}_{t*}(\mu)$$

is \mathcal{F}_t -convex, for all $t < T$, where

$$\mathcal{Y}_{t*}(\mu) := \lim_{\varepsilon \rightarrow 0} \text{essinf} \{ \mathcal{Y}_t(\mu') : |\mu' - \mu| \leq \varepsilon, \mu' \in \mathbf{L}_0([0, 1], \mathcal{F}_t) \},$$

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□ **Rem** : Note that

- $\mathcal{Y} = \mathcal{Y}_{\cdot,+}$ when Φ is a.s. continuous.

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□ **Proposition** : Assume Φ deterministic and its convex envelope $\hat{\Phi}$ continuous on $[0, 1]$. Then,

$$\mathcal{Y}_{T-}^{\alpha} = \hat{\Phi}(M_T^{\alpha}) \quad \text{and} \quad \mathcal{Y}_{\tau}^{\alpha} = \text{ess inf}_{\alpha' \in \mathbf{A}_{\tau}^{\alpha}} \mathcal{E}_{\tau}^g \left[\hat{\Phi}(M_T^{\alpha'}) \right],$$

for all $\alpha \in \mathbf{A}_0$ and $\tau \in \mathcal{T}$ such that $\tau < T$.

Duality and optimal control in standard form

- **Assumption** : Φ and g are a.s. convex + technical assumptions...

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- Fenchel transforms :

$$\tilde{\Phi}(\omega, l) := \sup_{m \in [0,1]} (ml - \Phi(\omega, m))$$

and

$$\tilde{g}(\omega, t, u, v) := \sup_{(y,z) \in \mathbb{R} \times \mathbb{R}^d} \left(yu + z^\top v - g(\omega, t, y, z) \right).$$

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- $\Lambda =$ predictable λ s.t. $\lambda_t(\omega) \in \text{dom}(\tilde{g}(\omega, t, \cdot))$ Leb \times \mathbb{P} -a.e.

Duality and optimal control in standard form

□ Dual optimal control problem :

Set for $\lambda = (\nu, \vartheta)$

$$L_t^\lambda = 1 + \int_0^t L_s^\lambda \nu_s ds + \int_0^t L_s^\lambda \vartheta_s dW_s$$

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and

$$\mathcal{X}_0(I) := \inf_{\lambda \in \Lambda} X_0^{I, \lambda}$$

where

$$X_0^{I, \lambda} := E \left[\int_0^T L_s^\lambda \tilde{g}(s, \lambda_s) ds + L_T^\lambda \tilde{\Phi}(I/L_T^\lambda) \right].$$

Duality and optimal control in standard form

□ **Theorem** : Under “good” assumptions (in particular existence in one of the two problems) :

$$\mathcal{Y}_0(m) = \sup_{l>0} (ml - \mathcal{X}_0(l))$$

and

$$\mathcal{X}_0(l) = \sup_{m>0} (ml - \mathcal{Y}_0(m))$$

+ standard explicit relations between the optimizers.

Duality and optimal control in standard form

□ **Rem** : In the quantile hedging problem for the BS model :

$$\Phi(\omega, m) = mg(S_T(\omega)) , \quad g(\omega, y, z) = z\mu/\sigma.$$

In particular,

$$\tilde{\Phi}(\omega, l) = [l - g(S_T(\omega))]^+ , \quad \tilde{g}(\omega, u, v) = +\infty \mathbf{1}_{\{(u,v) \neq (0, \mu/\sigma)\}}$$

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It follows that

$$\mathcal{X}_0(l) = E [L_T^o [l/L_T^o - g(S_T(\omega))]^+]$$

with

$$L_t^o = 1 + \int_0^t L_s^o(\mu/\sigma) dW_s.$$

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