

Mathematical basis for evolution PDEs
La Habana CIMPA school - 2013
Lesson 2 - Transport equation : characteristics method
and DiPerna-Lions renormalization theory

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1 Introduction (June 25th, 26th and 27th, 2013)

We consider the evolution PDE (transport equation)

$$(1.1) \quad \partial_t f = \Lambda f = -a(x) \cdot \nabla f(x) \quad \text{in } (0, \infty) \times \mathbb{R}^d,$$

that we complement by an initial condition

$$f(0, x) = f_0(x) \quad \text{in } \mathbb{R}^d.$$

We assume that the drift force field satisfies

$$a \in C^1(\mathbb{R}^d) \cap W^{1,\infty}(\mathbb{R}^d)$$

(a globally Lipschitz would be suitable) and that the initial datum satisfies

$$(1.2) \quad f_0 \in L^p(\mathbb{R}^d), \quad 1 \leq p \leq \infty.$$

We prove that there exists a unique solution in the renormalization sense to the transport equation (1.1) associated to the initial datum f_0 .

2 Characteristics method and existence of solutions

2.1 Smooth initial datum.

As a first step we consider $f_0 \in C_c^1(\mathbb{R}^d; \mathbb{R})$.

Thanks to the Cauchy-Lipschitz theorem on ODE, we know that for any $x \in \mathbb{R}^d$ the equation

$$\dot{x}(t) = a(x(t)), \quad x(0) = x,$$

admits a unique solution $t \mapsto x(t) = \Phi_t(x) \in C^1(\mathbb{R}; \mathbb{R}^d)$. Moreover, for any $t \geq 0$, the vectors valued function $\Phi_t : \mathbb{R}^d \rightarrow \mathbb{R}^d$ is a C^1 -diffeomorphism and the application $\mathbb{R}_+ \times \mathbb{R}^d \rightarrow \mathbb{R}^d$, $(t, x) \mapsto \Phi_t(x)$ is globally Lipschitz.

The characteristics method makes possible to build a solution to the transport equation (1.1) thanks to the solutions (characteristics) of the above ODE problem.

We start with a simple case. Assuming $f_0 \in C^1(\mathbb{R}^d; \mathbb{R})$, we define the function $f \in C^1(\mathbb{R} \times \mathbb{R}^d; \mathbb{R})$

$$(2.1) \quad \forall t \geq 0, \forall x \in \mathbb{R}^d \quad f(t, x) := f_0(\Phi_t^{-1}(x)).$$

From the associated implicit equation $f(t, \Phi_t(x)) = f_0(x)$, we deduce

$$\begin{aligned} 0 &= \frac{d}{dt}[f(t, \Phi_t(x))] = (\partial_t f)(t, \Phi_t(x)) + \dot{\Phi}_t(x) \cdot (\nabla_x f)(t, \Phi_t(x)) \\ &= (\partial_t f + a(x) \cdot \nabla_x f)(t, \Phi_t(x)). \end{aligned}$$

The above equation holding true for any $t > 0$ and $x \in \mathbb{R}^d$ and the function Φ_t mapping \mathbb{R}^d onto \mathbb{R}^d , we deduce that $f \in C^1((0, T) \times \mathbb{R}^d)$ satisfies the transport equation (1.1) in the sense of the classical differential calculus.

If furthermore $f_0 \in C_c^1(\mathbb{R}^d)$, by using that $|\Phi_t(x) - x| \leq Lt$ for any $x \in \mathbb{R}^d$, $t \geq 0$ we deduce that $f(t) \in C_c^1(\mathbb{R}^d)$ for any $t \geq 0$, with $\text{supp } f(t) \subset \text{supp } f_0 + B(0, Lt)$. In other words, transport occurs with finite speed : that makes a great difference with the instantaneous positivity of solution (related of a “infinite speed” of propagation of particles) known for the heat equation and more generally for parabolic equations.

Exercise 2.1 *Make explicit the construction and formulas in the three following cases :*

(1) $a(x) = a \in \mathbb{R}^d$ is a constant vector.

(2) $a(x) = x$

(3) $a(x) = v$, $f_0 = f_0(x, v) \in C^1(\mathbb{R}^d \times \mathbb{R}^d)$ and we look for a solution $f = f(t, x, v) \in C^1((0, \infty) \times \mathbb{R}^d \times \mathbb{R}^d)$.

(4) Prove that (S_t) is a group on $C(\mathbb{R}^d)$, where

$$(2.2) \quad \forall f_0 \in C(\mathbb{R}^d), \forall t \in \mathbb{R}, \forall x \in \mathbb{R}^d \quad (S_t f_0)(x) = f(t, x) := f_0(\Phi_t^{-1}(x)).$$

(5) Repeat a similar construction in the case of a time depending drift force field $a = a(t, x) \in C^1([0, T] \times \mathbb{R}^d)$ and for the transport equation with a gain source term added at the RHS of (1.1).

2.2 L^p initial datum.

As a second step we want to generalize the construction of solutions to more general initial data as announced in (1.2). We observe that at least formally the following computation holds for a given positive solution f of the transport equation (1.1) :

$$\begin{aligned} \frac{d}{dt} \int_{\mathbb{R}^d} f^p dx &= \int_{\mathbb{R}^d} \partial_t f^p dx = \int_{\mathbb{R}^d} p f^{p-1} \partial_t f dx \\ &= \int_{\mathbb{R}^d} p f^{p-1} a \cdot \nabla_x dx = \int_{\mathbb{R}^d} a(x) \cdot \nabla_x f^p dx \\ &= \int_{\mathbb{R}^d} (-\text{div}_x a) f^p dx \leq \|\text{div}_x a\|_{L^\infty} \int_{\mathbb{R}^d} f^p dx. \end{aligned}$$

With the help of the Gronwall lemma, we learn from that differential inequality that the following (still formal) estimate holds

$$(2.3) \quad \|f(t)\|_{L^p} \leq e^{bt/p} \|f_0\|_{L^p} \quad \forall t \geq 0,$$

with $b := \|\text{div}_x a\|_{L^\infty}$. As a consequence, we may propose the following natural definition of solution.

Definition 2.2 *We say that $f = f(t, x)$ is a weak solution to the transport equation (1.1) associated to the initial datum $f_0 \in L^p(\mathbb{R}^d)$ if it satisfies the bound*

$$f \in L^\infty(0, T; L^p(\mathbb{R}^d))$$

and it satisfies the equation in the following weak sense :

$$\int_0^T \int_{\mathbb{R}^d} f \left\{ \partial_t \varphi + \text{div}_x(a\varphi) \right\} dx dt + \int_{\mathbb{R}^d} f_0 \varphi(0, \cdot) dx = 0$$

for any $\varphi \in C_c^1([0, T] \times \mathbb{R}^d)$.

Exercise 2.3 1. Prove that a classical solution is a weak solution.

2. Prove that a weak solution f is weakly continuous (after modification of $f(t)$ on a time set of measure zero) in the following sense :

- (i) $f \in C([0, T]; \mathcal{D}'(\mathbb{R}^d))$ in general (and even $f \in Lip([0, T]; w * -(C_c^1(\mathbb{R}^d))')$);
- (ii) $f \in C([0, T]; w * -(C_c(\mathbb{R}^d))')$ when $p = 1$ (for the weak topology $*\sigma(M^1, C_c)$);
- (ii) $f \in C([0, T]; w - L^p(\mathbb{R}^d))$ when $p \in (1, \infty)$ (for the weak topology $\sigma(L^p, L^{p'})$);
- (ii) $f \in C([0, T]; w - L_{loc}^p(\mathbb{R}^d))$ for any $p \in [1, \infty)$ when $p = \infty$.

Theorem 2.4 (Existence) For any $f_0 \in L^p(\mathbb{R}^d)$, $1 \leq p \leq \infty$, there exists a global (defined for any $T > 0$) weak solution to the transport equation (1.1) which furthermore satisfies

$$f \in C([0, \infty); L^p(\mathbb{R}^d)) \text{ when } p \in [1, \infty); \quad f \in C([0, \infty); L_{loc}^1(\mathbb{R}^d)) \text{ when } p = \infty.$$

If moreover $f_0 \geq 0$ then $f(t, \cdot) \geq 0$ for any $t \geq 0$.

Step 1. Rigorous a priori bounds. Take $f_0 \in C_c^1(\mathbb{R}^d)$. For any smooth (renormalizing) function $\beta : \mathbb{R} \rightarrow \mathbb{R}_+$, $\beta(0) = 0$, which are C^1 and globally Lipschitz we clearly have that $\beta(f(t, x))$ is a solution to the same equation associated to the initial datum $\beta(f_0)$ and $\beta(f(t, \cdot)) \in C_c^1(\mathbb{R}^d)$ for any $t \geq 0$. The function

$$(0, T) \rightarrow \mathbb{R}_+, \quad t \mapsto \int_{\mathbb{R}^d} \beta(f(t, x)) dx$$

is clearly C^1 (that is an exercise using the Lebesgue's dominated convergence Theorem) and

$$\begin{aligned} \frac{d}{dt} \int_{\mathbb{R}^d} \beta(f(t, x)) dx &= \int_{\mathbb{R}^d} \partial_t \beta(f(t, x)) dx = \int_{\mathbb{R}^d} \beta'(f(t, x)) \partial_t f(t, x) dx \\ &= \int_{\mathbb{R}^d} \beta'(f(t, x)) a(x) \cdot \nabla_x f(t, x) dx = \int_{\mathbb{R}^d} a(x) \cdot \nabla_x \beta(f(t, x)) dx \\ &= \int_{\mathbb{R}^d} (-\operatorname{div}_x a)(x) \beta(f(t, x)) dx. \end{aligned}$$

We deduce from that identity the differential inequality

$$\frac{d}{dt} \int_{\mathbb{R}^d} \beta(f(t, x)) dx \leq b \int_{\mathbb{R}^d} \beta(f(t, x)) dx,$$

with $b := \|\operatorname{div}_x a\|_{L^\infty}$, and then thanks to the Gronwall lemma

$$\int_{\mathbb{R}^d} \beta(f(t, x)) dx \leq e^{bt} \int_{\mathbb{R}^d} \beta(f_0(x)) dx.$$

Since $f_0 \in L^1(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d)$ by assumption, for any $1 \leq p < \infty$, we can define a sequence of renormalized functions (β_n) such that $0 \leq \beta_n(s) \nearrow |s|^p$ for any $s \in \mathbb{R}$ and we can pass to the limit in the preceding inequality using the monotonous Lebesgue Theorem at the RHS and the Fatou Lemma at the LHS in order to get

$$\int_{\mathbb{R}^d} |f(t, x)|^p dx \leq e^{bt} \int_{\mathbb{R}^d} |f_0(x)|^p dx,$$

or in other words

$$\|f(t, \cdot)\|_{L^p} \leq e^{bt/p} \|f_0\|_{L^p} \quad \forall t \geq 0.$$

Passing to the limit $p \rightarrow \infty$ in the above equation we obtain (maximum principle)

$$\|f(t, \cdot)\|_{L^\infty} \leq \|f_0\|_{L^\infty} \quad \forall t \geq 0.$$

Moreover, $f \in C([0, T]; L^p(\mathbb{R}^d))$ for any $p \in [1, \infty)$.

Step 2. Existence in the case $p \in [1, \infty)$. For any function $f_0 \in L^p(\mathbb{R}^d)$, $1 \leq p < \infty$, we may define a sequence of functions $f_{0,n} \in C_c^1(\mathbb{R}^d)$ (take for instance $f_{0,n} := (\chi_n f_0) * \rho_n$ such that $f_{0,n} \rightarrow f_0$ in $L^p(\mathbb{R}^d)$: here comes the restriction $p < \infty$). Because of the first step we may define $f_n(t)$ a solution to the transport equation. Moreover, thanks to the first step and because the equation is linear we have

$$\sup_{t \in [0, T]} \|f_n(t, \cdot) - f_m(t, \cdot)\|_{L^p} \leq e^{bt/p} \|f_{0,n} - f_{0,m}\|_{L^p} \rightarrow 0 \quad \forall T \geq 0.$$

The sequence (f_n) being a Cauchy sequence, there exists $f \in C([0, T]; L^p(\mathbb{R}^d))$ such that $f_n \rightarrow f$ in $C([0, T]; L^p(\mathbb{R}^d))$ as $n \rightarrow \infty$. Now, writing

$$\begin{aligned} 0 &= - \int_0^T \int_{\mathbb{R}^d} \varphi \left\{ \partial_t f_n + a \cdot \nabla f_n \right\} dx dt \\ &= \int_0^T \int_{\mathbb{R}^d} f_n \left\{ \partial_t \varphi + \operatorname{div}_x(a\varphi) \right\} dx dt + \int_{\mathbb{R}^d} f_{0,n} \varphi(0, \cdot) dx, \end{aligned}$$

we may pass to the limit in the above equation and we get that f is a solution in the convenient sense.

If moreover $f_0 \geq 0$ then the same holds for $f_{0,n}$, then for f_n and finally for f . \square

Exercise 2.5 (1) Show that for any solution f to the transport equation associated to an initial datum $f_0 \in C_c^1(\mathbb{R}^d)$ built by the characteristics method, for any times $T > 0$ and radius R there exists some constants $C_T, R_T \in (0, \infty)$ such that

$$\sup_{t \in [0, T]} \int_{B_R} |f(t, x)| dx \leq C_T \int_{B_{R_T}} |f_0(x)| dx.$$

(Hint. Use the property of finite speed propagation of the transport equation).

(2) Adapt the proof of existence to the case $f_0 \in L^\infty$.

3 Weak solutions are renormalized solutions

Definition 3.1 Let $\Omega \subset \mathbb{R}^d$ and assume here $a \in W^{1, \infty}((0, T) \times \Omega)$. We say that $g \in L_{loc}^1([0, T] \times \Omega)$ is a weak solution to the PDE evolution equation

$$(3.1) \quad Lg := \partial_t g - \Lambda g := \partial_t g + a \cdot \nabla_x g - \nu \Delta_x g = G, \quad g(0, \cdot) = g_0,$$

with $G \in L_{loc}^1([0, T] \times \Omega)$, $\nu \in \mathbb{R}_+$, $g_0 \in L_{loc}^1(\Omega)$, if for any $\varphi \in C_c^2([0, T] \times \Omega)$ there holds

$$\int_0^T \int_{\Omega} g L^* \varphi = \int_{\Omega} g_0 \varphi(0, \cdot) + \int_0^T \int_{\Omega} \varphi G$$

where L^* is the dual operator

$$L^* \varphi := -\partial_t \varphi - \operatorname{div}_x(a\varphi) - \nu \Delta_x \varphi.$$

In order to simplify the presentation, from now on, we may assume $\Omega = \mathbb{R}^d$, $a \in W^{1, \infty}(\Omega)$.

Remarks 3.2 (1) In the above definition of weak solution, we do not need that $a \in W^{1, \infty}$, but just that $a, \operatorname{div}_x a \in L_{loc}^\infty$. However, that additional information will be necessary in order to prove the renormalization result.

(2) One can take equivalently $\varphi \in \mathcal{D}([0, T] \times \mathbb{R}^d)$ in the definition : we usually call such a solution a “solution in the distributional sense”. We do not make the difference here between the different notions of weak solutions which are all equivalent in our framework.

(3) Any weak solution satisfies $f \in C([0, T]; \mathcal{D}'(\mathbb{R}^d))$ in the sense that for any given test function $\varphi \in C_c^2(\mathbb{R}^d)$ the following quantity

$$t \mapsto \int_{\mathbb{R}^d} f(t, x) \varphi(x) dx$$

is continuous.

For any $g \in C^2$ classical solution of (3.1) and $\beta \in C^2(\mathbb{R}; \mathbb{R})$, there holds

$$\begin{aligned} & \partial_t \beta(g) + a \cdot \nabla_x (\beta(g)) - \Delta \beta(g) = \\ & = \beta'(g) \partial_t g + \beta'(g) a \cdot \nabla_x g - \operatorname{div}(\beta'(g) \nabla_x g) \\ & = \beta'(g) G - \beta''(g) |\nabla g|^2. \end{aligned}$$

Definition 3.3 We say that $g \in L^1_{loc}([0, T] \times \Omega)$ is a renormalized solution to the PDEs evolution equation (3.1) with $G \in L^1_{loc}([0, T] \times \Omega)$, $\nu \in \mathbb{R}_+$, $g_0 \in L^1_{loc}(\Omega)$ if g satisfies the additionnal bound $\nu \nabla_x g \in L^2_{loc}([0, T] \times \Omega)$ as well as the equations

$$(3.2) \quad \int_0^T \int_{\Omega} \beta(g) L^* \varphi = \int_{\Omega} \beta(g_0) \varphi(0, \cdot) + \int_0^T \int_{\Omega} \varphi \{ \beta'(g) G - \beta''(g) |\nabla g|^2 \}$$

for any test function $\varphi \in C_c^2([0, T] \times \Omega)$ and any renormalizing function $\beta \in C^2(\mathbb{R})$ such that $\beta'' \in C_c(\mathbb{R})$.

Theorem 3.4 With the above notations and assumptions, any weak solution $g \in C([0, T]; L^1_{loc}(\Omega))$ to the equation (3.1) such that $\nu \nabla g \in L^2_{loc}$ is a renormalized solution.

For the sake of simplicity, we only deal with the case $\Omega = \mathbb{R}^d$. We start with two elementary but fundamental lemmas.

Lemma 3.5 Given $G \in L^1_{loc}([0, T] \times \mathbb{R}^d)$, let $g \in L^1_{loc}([0, T] \times \mathbb{R}^d)$ be a weak solution to the PDE

$$\Delta g = G \quad \text{on } (0, T) \times \mathbb{R}^d.$$

For a mollifier sequence

$$\rho_{\varepsilon}(t, x) := \frac{1}{\varepsilon^{d+1}} \rho\left(\frac{t}{\varepsilon}, \frac{x}{\varepsilon}\right), \quad 0 \leq \rho \in \mathcal{D}(\mathbb{R}^{d+1}), \quad \operatorname{supp} \rho \subset (-1, 0) \times B(0, 1), \quad \int_{\mathbb{R}^{d+1}} \rho = 1,$$

and for $\tau \in (0, T)$, $\varepsilon \in (0, \tau)$, we define the function

$$g_{\varepsilon} := (\rho_{\varepsilon} *_{t,x} g)(t, x) := \int_0^T \int_{\mathbb{R}^d} g(s, y) \rho(t-s, x-y) ds dy.$$

Then $g_{\varepsilon} \in C^{\infty}([0, T-\tau] \times \mathbb{R}^d)$ and it satisfies the equation

$$Lg_{\varepsilon} = G_{\varepsilon} + r_{\varepsilon}$$

in the classical differential calculus sense on $[0, T-\tau] \times \mathbb{R}^d$, with

$$G_{\varepsilon} := \rho_{\varepsilon} *_{t,x} G, \quad r_{\varepsilon} := a \cdot \nabla_x g_{\varepsilon} - (a \cdot \nabla g) * \rho_{\varepsilon}.$$

It is worth emphasizing that in the above formula the ‘‘commutator’’ r_{ε} is defined in a weak sense, namely

$$r_{\varepsilon}(t, x) := \int_{\mathbb{R}^{d+1}} g(s, y) \left\{ a(x) \cdot \nabla_x \rho_{\varepsilon}(t-s, x-y) + \operatorname{div}_y [a(y) \rho_{\varepsilon}(t-s, x-y)] \right\} dy ds.$$

Proof of Lemma 3.5. Define $\mathcal{O} := [0, T-\tau] \times \mathbb{R}^d$. For any $(t, x) \in \mathcal{O}$ fixed and any $\varepsilon \in (0, \tau)$, we define

$$(s, y) \mapsto \varphi(s, y) = \varphi_{\varepsilon}^{t,x}(s, y) := \rho_{\varepsilon}(t-s, x-y) \in \mathcal{D}([0, T] \times \mathbb{R}^d).$$

We then just write the weak formulation of equation (3.1) for that test function, and we get

$$\begin{aligned}
0 &= \int_0^T \int_{\mathbb{R}^d} g \Lambda^* \varphi - \int_0^T \int_{\mathbb{R}^d} G \varphi \\
&= \int_0^T \int_{\mathbb{R}^d} g(s, y) \{ -\partial_s \varphi^{t,x}(s, y) - \nabla_y(a(y) \varphi^{t,x}(s, y)) - \Delta_y \varphi^{t,x}(s, y) \} \\
&\quad - \int_0^T \int_{\mathbb{R}^d} G(s, y) \varphi^{t,x}(s, y) \\
&= \int_0^T \int_{\mathbb{R}^d} g(s, y) \{ \partial_t \varphi^{t,x}(s, y) + a(x) \cdot \nabla_x \varphi^{t,x}(s, y) - \Delta_x \varphi^{t,x}(s, y) \} \\
&\quad + \int_0^T \int_{\mathbb{R}^d} g(s, y) \{ a(y) \cdot \nabla_y \varphi^{t,x}(s, y) - a(x) \cdot \nabla_x \varphi^{t,x}(s, y) \} - \int_0^T \int_{\mathbb{R}^d} G(s, y) \varphi^{t,x}(s, y) \\
&= \partial_t g_\varepsilon(t, x) + a \cdot \nabla_x g_\varepsilon(t, x) - \Delta_x g_\varepsilon(t, x) - r_\varepsilon(t, x) - G_\varepsilon(t, x),
\end{aligned}$$

which is the announced equation. \square

Lemma 3.6 *Under the assumptions $B \in W_{loc}^{1,q}(\mathbb{R}^d)$ and $g \in L_{loc}^p(\mathbb{R}^d)$ with $1/r = 1/p + 1/q \leq 1$, then*

$$R_\varepsilon := (B \cdot \nabla g) * \rho_\varepsilon - B \cdot \nabla(g * \rho_\varepsilon) \rightarrow 0 \quad L_{loc}^r,$$

for any mollifier sequence (ρ_ε) .

Remark 3.7 *For a time dependent field vector $a(t, x)$ satisfying the boundedness conditions of Theorem 3.4 the same result (with the same proof) holds, so that the commutator r_ε defined in Lemma 3.5 satisfies $r_\varepsilon \rightarrow 0$ in $L_{loc}^1([0, T] \times \mathbb{R}^d)$.*

Proof of Lemma 3.6. We only consider the case $p = 1$, $q = \infty$ and $r = 1$. We start writing

$$\begin{aligned}
R_\varepsilon(x) &= - \int g(y) \left\{ \operatorname{div}_y (B(y) \rho_\varepsilon(x - y)) + B(x) \cdot \nabla_x (\rho_\varepsilon(x - y)) \right\} dy \\
&= \int g(y) \left\{ (B(y) - B(x)) \cdot \nabla_x (\rho_\varepsilon(x - y)) \right\} dy - ((g \operatorname{div} B) * \rho_\varepsilon)(x) \\
&=: R_\varepsilon^1(x) + R_\varepsilon^2(x).
\end{aligned}$$

For the first term, we remark that

$$\begin{aligned}
|R_\varepsilon^1(x)| &\leq \int |g(y)| \left| \frac{B(y) - B(x)}{\varepsilon} \right| |(\nabla \rho)_\varepsilon(x - y)| dy \\
&\leq \|\nabla B\|_{L^\infty} \int_{|x-y| \leq 1} |g(y)| |(\nabla \rho)_\varepsilon(x - y)| dy,
\end{aligned}$$

so that

$$(3.3) \quad \int_{B_R} |R_\varepsilon^1(x)| dx \leq \|\nabla B\|_{L^\infty} \|\nabla \rho\|_{L^1} \|g\|_{L^1(B_{R+1})}.$$

On the other hand, if g is a smooth (say C^1) function

$$\begin{aligned}
R_\varepsilon^1(x) &= \nabla_x ((gB) * \rho_\varepsilon) - B \cdot \nabla_x (g * \rho_\varepsilon) \\
&\rightarrow \nabla_x (gB) - B \cdot \nabla_x g = (\operatorname{div} B) g.
\end{aligned}$$

Since every things make sense at the limit with the sole assumption $\operatorname{div} B \in L^\infty$ and $g \in L^1$, with the help of (3.3) we can use a density argument in order to get the same result without the additional smoothness hypothesis on g . More precisely, for a sequence g_α in C^1 such that $g_\alpha \rightarrow g$ in L_{loc}^1 , we have

$$R_\varepsilon^1[g_\alpha] \rightarrow (\operatorname{div} B) g \text{ in } L_{loc}^1, \quad \|R_\varepsilon^1[h]\|_{L^1} \leq C \|h\|_{L^1} \quad \forall h,$$

so that

$$R_\varepsilon^1[g] - (\operatorname{div} B)g = \{R_\varepsilon^1[g] - R_\varepsilon^1[g_\alpha]\} + \{R_\varepsilon^1[g_\alpha] - (\operatorname{div} B)g_\alpha\} + \{(\operatorname{div} B)g_\alpha - (\operatorname{div} B)g\} \rightarrow 0$$

in L_{loc}^1 as $\varepsilon \rightarrow 0$. For the second term, we clearly have

$$R_\varepsilon^2 = (g \operatorname{div} B) * \rho_\varepsilon \rightarrow g \operatorname{div} B$$

and we conclude by putting all the terms together. \square

Proof of Theorem 3.4. Step 1. We consider a weak solution $g \in L_{loc}^1$ to the PDE

$$Lg = G \quad \text{in } [0, T] \times \mathbb{R}^d.$$

By mollifying the functions with the sequence (ρ_ε) defined in Lemma 3.5 and using Lemma 3.5, we get

$$Lg_\varepsilon = G_\varepsilon + r_\varepsilon \quad \text{in } [0, T] \times \mathbb{R}^d, \quad r_\varepsilon \rightarrow 0 \text{ in } L_{loc}^1.$$

Because g_ε is a smooth function, we may perform the following computation (in the sense of the classical differential calculus)

$$L\beta(g_\varepsilon) = \beta'(g_\varepsilon)G_\varepsilon - \nu \beta''(g_\varepsilon)|\nabla_x g_\varepsilon|^2 + \beta'(g_\varepsilon)r_\varepsilon,$$

so that

$$(3.4) \quad \int \beta(g_\varepsilon)L^*\varphi = \int_\Omega \beta(g_\varepsilon(0, \cdot))\varphi(0, \cdot) + \int \beta'(g_\varepsilon)G_\varepsilon\varphi - \nu \int \beta''(g_\varepsilon)|\nabla_x g_\varepsilon|^2\varphi + \int \beta'(g_\varepsilon)r_\varepsilon$$

for any $\varphi \in C_c^2([0, T] \times \mathbb{R}^d)$. Using that

$$g_\varepsilon \rightarrow g, \quad G_\varepsilon \rightarrow G, \quad r_\varepsilon \rightarrow 0, \quad \nu|\nabla_x g_\varepsilon|^2 \rightarrow \nu|\nabla_x g|^2$$

in L_{loc}^1 as $\varepsilon \rightarrow 0$, which in turns imply $\beta''(g_\varepsilon) \rightarrow \beta''(g)$ a.e., and that $(\beta''(g_\varepsilon))$ is bounded in L^∞ , we may pass to the limit $\varepsilon \rightarrow 0$ in the last identity and we obtain (3.2) for any test function $\varphi \in C_c^2([0, T] \times \Omega)$.

In the case we consider a solution g built thanks to Theorem 2.4 above or Theorem 3.2 in chapter 1, we know that additionally $g \in C([0, T]; L_{loc}^1(\Omega))$ and therefore

$$g_\varepsilon \rightarrow g \quad \text{in } C([0, T]; L_{loc}^1(\Omega)).$$

In particular $g_\varepsilon(0, \cdot) \rightarrow g(0, \cdot)$ in $L_{loc}^1(\Omega)$ and we may pass to the limit in equation (3.4) for any test function $\varphi \in C_c^2([0, T] \times \Omega)$, which ends the proof of (3.2).

4 Consequence of the renormalization result

In this section we present several immediate consequences of the renormalization formula established in Theorem 3.4 for the transport equation (1.1).

4.1 Uniqueness and C_0 -semigroup in $L^p(\mathbb{R}^d)$, $1 \leq p < \infty$

Corollary 4.1 *Assume $p \in [1, \infty)$. For any initial datum $g_0 \in L^p(\mathbb{R}^d)$, the transport equation admits a unique weak solution $g \in C([0, T]; L^p(\mathbb{R}^d))$.*

Proof of Corollary 4.1. Consider two weak solutions g_1 and g_2 to the transport equation (1.1) associated to the same initial datum g_0 . The function $g := g_2 - g_1 \in C([0, T]; L^p(\mathbb{R}^d))$ is then a weak solution to the transport equation (1.1) associated to the initial datum $g(0) = 0$. Thanks to Theorem 3.4 it is also a renormalized solution, which means

$$\int_{\mathbb{R}^d} \beta(g(t, \cdot)) \varphi dx = \int_0^t \int_{\mathbb{R}^d} \beta(g) \operatorname{div}_x(a \varphi) dx ds$$

for any renormalizing function $\beta \in W^{1,\infty}(\mathbb{R})$, $\beta(0) = 0$, and any test function $\varphi = \varphi(x) \in C_c^1(\mathbb{R}^d)$. We fix β such that furthermore $0 < \beta(s) \leq |s|^p$ for any $s \neq 0$, $\chi \in \mathcal{D}(\mathbb{R}^d)$ such that $0 \leq \chi \leq 1$, $\chi \equiv 1$ on $B(0, 1)$ and we take $\psi(x) = \chi_R(x) = \chi(x/R)$, so that

$$\int_{\mathbb{R}^d} \beta(g(t, \cdot)) \chi_R dx = \int_0^t \int_{\mathbb{R}^d} \beta(g) (\operatorname{div}_x a) \chi_R dx ds + \frac{1}{R} \int_0^t \int_{\mathbb{R}^d} \beta(g) a(x) \cdot \nabla \chi(x/R) dx ds$$

Observing that $\beta(g) \in C([0, T]; L^1(\mathbb{R}^d))$ and $\chi_R \rightarrow 1$, we easily pass to the limit $R \rightarrow \infty$ in the above expression, and we get

$$(4.1) \quad \int_{\mathbb{R}^d} \beta(g(t, \cdot)) dx = \int_0^t \int_{\mathbb{R}^d} \beta(g) (\operatorname{div}_x a) dx ds$$

By the Gronwall lemma we conclude that $\beta(g(t, \cdot)) = 0$ and then $g(t, \cdot) = 0$ for any $t \in [0, T]$. \square

In the same way as in chapter 1, we can deduce from the above existence and uniqueness result on the linear transport equation (1.1) that the formula

$$(S_t g_0)(x) := g(t, x)$$

defines a C_0 -semigroup on $L^p(\mathbb{R}^d)$, $1 \leq p < \infty$, where g is the solution to the transport equation (1.1) associated to the initial datum g_0 .

4.2 Positivity

We can recover in a quite elegant way the positivity as an a posteriori property that we deduce from the renormalization formula.

Corollary 4.2 *Consider a solution $g \in C([0, T]; L^p(\mathbb{R}^d))$, $1 \leq p < \infty$, to the transport equation (1.1). If $g_0 \geq 0$ then $g(t, \cdot) \geq 0$ for any $t \geq 0$.*

Proof of Corollary 4.3. We argue similarly as in the proof of Corollary 4.1 but fixing a renormalizing function $\beta \in W^{1,\infty}(\mathbb{R})$ such that $\beta(s) = 0$ for any $s \geq 0$, $\beta(s) > 0$ for any $s < 0$. Since then $\beta(g_0) = 0$, we deduce that (4.1) holds again with that choice of function β and then, thanks to Gronwall lemma, $\beta(g(t, \cdot)) = 0$ for any $t \geq 0$. That means $g(t, \cdot) \geq 0$ for any $t \geq 0$. \square

4.3 A posteriori estimate

Corollary 4.3 *Consider a solution $g \in C([0, T]; L^p(\mathbb{R}^d))$, $1 \leq p < \infty$, to the transport equation (1.1). If $g_0 \in L^q(\mathbb{R}^d)$, $1 \leq q \leq \infty$, then $g \in L^\infty(0, T; L^q(\mathbb{R}^d))$ for any $T > 0$.*

Proof of Corollary 4.3. We argue similarly as in the proof of Corollary 4.1 but fixing an arbitrary renormalizing function $\beta \in W^{1,\infty}(\mathbb{R})$, $\beta(s) = 0$ on a small neighbourhood of $s = 0$, so that $\beta(g) \in C([0, T]; L^1(\mathbb{R}^d))$. For such a choice, we obtain the time integrale inequality

$$\int_{\mathbb{R}^d} \beta(g(t, \cdot)) dx = \int_{\mathbb{R}^d} \beta(g_0) dx + \int_0^t \int_{\mathbb{R}^d} \beta(g) (\operatorname{div}_x a) dx ds \quad \forall t \geq 0.$$

From the Gronwall lemma, we obtain with $b = \|\operatorname{div} a\|_{L^\infty}$, the estimate

$$(4.2) \quad \int_{\mathbb{R}^d} \beta(g(t, \cdot)) dx \leq e^{bt} \int_{\mathbb{R}^d} \beta(g_0) dx \quad \forall t \geq 0.$$

Because estimate (4.2) is uniform with respect to β , we may choose a sequence of renormalizing functions (β_n) such that $\beta_n(s) \nearrow |s|^q$ in the case $1 \leq q < \infty$ and we get

$$\|g(t, \cdot)\|_{L^q} \leq e^{bt/q} \|g_0\|_{L^q} \quad \forall t \geq 0.$$

In the case $q = \infty$, we obtain the same conclusion by fixing $\beta \in W^{1,\infty}$ such that $\beta(s) = 0$ for any $|s| \leq \|g_0\|_{L^\infty}$, $\beta(s) > 0$ for any $|s| > \|g_0\|_{L^\infty}$ or by passing to the limit $q \rightarrow \infty$ in the above inequality. \square

4.4 Continuity

We can recover the strong L^p continuity property from the renormalization formula for a given solution. We do not present that rather technical issue here.

5 Complementary results

In this section we state and give a sketch of the proof of several complementary results of existence and uniqueness.

Regarding to the existence issue, we may extend our analysis to more general

- equations (modifying the assumptions on the coefficients);
- initial data;
- equations again by adding a given source term / a nonlinear RHS term;
- domains by considering the equation set on $\Omega \subset \mathbb{R}^d$ (and we possibly have to add boundary conditions).

Regarding the uniqueness issue, we will explain how to obtain it in a L^∞ framework.

5.1 Parabolic equation in L^p

We consider the parabolic equation

$$(5.1) \quad \partial_t g = \Lambda g + G \quad \text{in } (0, \infty) \times \mathbb{R}^d,$$

with

$$\Lambda := \Delta + a \cdot \nabla$$

As a first step, we look for a priori estimates. Given any solution g and any **convex** function β , we (formally) have

$$\begin{aligned} \frac{d}{dt} \int \beta(g) &= \int \Delta \beta(g) - \int \beta''(g) |\nabla g|^2 - \int (\operatorname{div} a) \beta(g) + \int \beta'(g) G \\ &\leq \int |\operatorname{div} a| \beta(g) + \int \beta'(g) |G| \end{aligned}$$

Particularizing $\beta(s) = |s|^p$, $1 \leq p < \infty$, and using the Young inequality $a^{p-1}b \leq a^p + b^p/p$, we get

$$\frac{d}{dt} \int |g|^p \leq p b \int |g|^p + \int |G|^p, \quad b := 1 + \|\operatorname{div} a\|_{L^\infty}.$$

The Gronwall lemma yields

$$\begin{aligned} \|g(t)\|_{L^p}^p &= e^{pbt} \|g_0\|_{L^p}^p + \int_0^t e^{pb(t-s)} \|G(s)\|_{L^p}^p ds \\ &\leq e^{pbt} \left(\|g_0\|_{L^p} + \left(\int_0^t \|G(s)\|_{L^p}^p ds \right)^{1/p} \right)^p, \end{aligned}$$

or equivalently

$$(5.2) \quad \sup_{[0, T]} \|g\|_{L^p} \leq e^{bT} \left(\|g_0\|_{L^p} + \|G\|_{L^1(0, T; L^p)} \right).$$

Next, defining $\beta = \beta_M$, $M \in \mathbb{N}$, a C^2 even and convex function such that

- if $M \leq 2$, $\beta(s) := s^2/2$ for $s \leq 2$, $\beta''(s) = 0$ for $s \geq 3$;
 - if $M \geq 3$, $\beta''(s) = 0$ for $0 \leq s \leq M - 1/2$ and $s \geq M + 3/2$, $\beta''(s) = 1$ for $M \leq s \leq M + 1$,
- and fixing $\chi \in \mathcal{D}(\mathbb{R}^d)$, $0 \leq \chi \leq 1$, $|\nabla \chi|^2 \leq \chi$, we have

$$\begin{aligned} \frac{1}{2} \int_0^T \int \beta''(g) \left(|\nabla g|^2 \chi - \frac{|\nabla \chi|^2}{\chi} \right) &\leq \int_0^T \int \beta''(g) (|\nabla g|^2 \chi - \nabla g \cdot \nabla \chi) \\ &= \left[\int \beta(g) \chi \right]_T^0 + \int_0^T \int \beta'(g) g \Delta \chi - \int \beta(g) \operatorname{div}(a \chi) + \int \beta'(g) G \chi \end{aligned}$$

from which we deduce that for any $T, R > 0$ and any $M \in \mathbb{N}$ that there exists a constant $C_{T,R}$

$$(5.3) \quad \int_0^T \int_{B_R} |\nabla g|^2 \mathbf{1}_{M \leq |g| \leq M+1} \leq C_{T,R} \left(\sup_{[0,T]} \|g\|_{L^1(B_{R+2})} + \|G\|_{L^1((0,T) \times B_{R+2})} \right).$$

The corresponding existence and uniqueness result reads as follows.

Theorem 5.1 *For any exponent $1 \leq p \leq \infty$, any initial datum $g_0 \in L^p(\mathbb{R}^d)$ and any source term $G \in L^1(0, T; L^p(\mathbb{R}^d))$, there exists a unique renormalized solution g in the sense that g satisfies the estimates (5.2) and (5.3) as well as*

$$g \in C([0, T]; L^p(\mathbb{R}^d)) \text{ if } p \in [1, \infty), \quad g \in C([0, T]; L^1_{loc}(\mathbb{R}^d)) \text{ if } p = \infty,$$

and satisfies equation (5.5) in the following renormalized sense

$$(5.4) \quad \int \beta(g_t) \varphi(t, \cdot) = \int_0^t \int \beta(g) \{ \partial_t \varphi - \operatorname{div}(a \varphi) + \Delta \varphi \} + \int_0^t \int \varphi \{ \beta'(g) G - \beta''(g) |\nabla g|^2 \}$$

for any test function $\varphi \in C_c^2([0, T] \times \Omega)$ and any renormalizing function $\beta \in C^2(\mathbb{R})$ such that $\beta'' \in C_c(\mathbb{R})$.

Elements of proof of Theorem 5.1. Step 1. The general case. Consider some data $g_0 \in L^p$ and $G \in L^1(0, T; L^p)$. We introduce two sequences $(g_{0,n})$ and (G_n) such that $g_{0,n} \in L^2 \cap L^p$, $g_{0,n} \rightarrow g_0$ in L^p , $G_n \in L^1(0, T; L^2 \cap L^p)$ and $G_n \rightarrow G$ in $L^1(0, T; L^p)$ and the corresponding sequence (g_n) of variational solutions in $X_T = C(L^2) \cap L^2(H^1) \cap H^1(H^{-1})$ to equation (5.5) which existence has been proved in Chapter 1. Notice in particular that $g_n \in C([0, T]; L^1_{loc})$ and that g_n is a renormalized solution so that the additional a posteriori estimates (5.2) and (5.3) holds uniformly in n .

Step 2. The case $p \in (1, \infty)$. We claim that $g_n \in C([0, T]; L^p(\mathbb{R}^d))$. Indeed, from the renormalizing formula, we easily show that $|g_n|^{p-2} |\nabla g_n|^2 \in L^1((0, T) \times \mathbb{R}^d)$, next

$$\frac{d}{dt} \int \frac{|g_n|^p}{p} = -(p-1) \int |g_n|^{p-2} |\nabla g_n|^2 - \int |g_n|^p \operatorname{div} a + \int G_n g_n |g_n|^{p-2} \in L^1(0, T)$$

and then $\|g\|_{L^p} \in C([0, T])$. Together with the fact that $g_n \in C([0, T]; L^1_{loc})$, we proved the above claim.

Now, using (5.2) we classically get that (g_n) is a Cauchy sequence in $C([0, T]; L^p(\mathbb{R}^d))$, it thus converges to a limit g in $C([0, T]; L^p(\mathbb{R}^d))$, from what we immediately pass to the limit $n \rightarrow \infty$ in the renormalized formulation (5.4) and conclude to the existence. The uniqueness follows from the renormalization property.

Step 3. The case $p = 1$. Here again we can also prove that $g_n \in C([0, T]; L^1(\mathbb{R}^d))$ and conclude exactly as in Step 2. The claimed continuity property comes from the fact that one can prove

$$\sup_{[0,T]} \int_{\mathbb{R}^d} |g_n| \mathbf{1}_{|g_n| \geq M} \rightarrow 0, \quad \sup_{[0,T]} \int_{\mathbb{R}^d} |g_n| \mathbf{1}_{|x| \geq M} \rightarrow 0,$$

when $M \rightarrow \infty$ for any n (and in fact uniformly in n).

Step 4. The case $p = \infty$. Here we argue in a different way. From (5.2), the equation (5.5) and summing (5.3) up to $M = \|g_{in}\|_{L^\infty_{tx}}$, we get that (g_n) is bounded in $L^\infty((0, T) \times \mathbb{R}^d)$, (∇g_n) is bounded in $L^2_{loc}((0, T) \times \mathbb{R}^d)$ and

$$\int_{\mathbb{R}^d} g_n \varphi \, dx \text{ is strongly compact in } C([0, T]) \text{ for any } \varphi \in C_c^2([0, T] \times \mathbb{R}^d).$$

We may then extract a subsequence of (g_n) (still denoted in same way) such that g_n converges to a limit g in $\sigma(L_{tx}^\infty, L_{tx}^1)$ and also in $C([0, T]; w - L_{loc}^2)$. We then can pass to the limit in the **weak formulation** (5.4) **with** $\beta(s) = s$ and for any test function $\varphi \in C_c^2([0, T] \times \mathbb{R}^d)$. Thanks to Theorem 3.4, we recover a posteriori the fact that g is a renormalized solution and the local continuity of g . Uniqueness follows from a duality argument that we present below. \square

5.2 Duhamel formula and existence for transport equation with an additional term

We consider the transport equation with an additional term

$$(5.5) \quad \partial_t g = \Lambda g + G \quad \text{in } (0, \infty) \times \mathbb{R}^d,$$

with

$$(\Lambda g)(x) := -a(x) \cdot \nabla g(x) + c(x)g(x) + \int_{\mathbb{R}^d} b(x, y)g(y) dy$$

We interpret that equation as a perturbation equation

$$\partial_t g = \mathcal{B}g + \tilde{G}, \quad \tilde{G} = \mathcal{A}g + G,$$

and we claim that the function

$$(5.6) \quad g(t) = S_{\mathcal{B}}(t)g_0 + \int_0^t S_{\mathcal{B}}(t-s)\tilde{G}(s) ds$$

is a solution to equation (5.5). Indeed, the semigroup $S_{\mathcal{B}}$ satisfies by definition (and at least formally)

$$\frac{d}{dt} S_{\mathcal{B}}(t)h = \mathcal{B}S_{\mathcal{B}}(t)h,$$

so that (again formally)

$$\begin{aligned} \frac{d}{dt} g(t) &= \frac{d}{dt} S_{\mathcal{B}}(t)g_0 + \int_0^t \frac{d}{dt} S_{\mathcal{B}}(t-s)\tilde{G}(s) ds + S_{\mathcal{B}}(0)\tilde{G}(t) \\ &= \mathcal{B}\left\{ S_{\mathcal{B}}(t)g_0 + \int_0^t S_{\mathcal{B}}(t-s)\tilde{G}(s) ds \right\} + \tilde{G}(t) \\ &= \mathcal{B}g(t) + \tilde{G}(t). \end{aligned}$$

All that computations can be justified when written in a weak sense. The method used here is nothing but the wellknown variation of the constant method in ODE, the expression (5.6) is called the “*Duhamel formula*” and a function $g(t)$ which satisfies (5.6) (in an appropriate and meaningful functional sense) is called a “*mild solution*” to the equation (5.5).

Theorem 5.2 *Assume $a \in W^{1, \infty}$, $c \in L^\infty$, $b \in L_x^\infty(L_y^{p'}) \cap L_y^\infty(L_x^{p'})$, $1 \leq p < \infty$. For any $g_0 \in L^p$ and $G \in L^1(0, T; L^p)$ there exists a unique mild (weak, renormalized) solution to equation (5.5).*

Elements of proof of Theorem 5.2. For any $h \in C([0, T]; L^p)$, we define the mapping

$$(\mathcal{U}h)(t) := S_{\mathcal{B}}(t)g_0 + \int_0^t S_{\mathcal{B}}(t-s)\left\{ \mathcal{A}h(s) + G(s) \right\} ds$$

and we observe that

$$\mathcal{U} : C([0, T]; L^p) \rightarrow C([0, T]; L^p)$$

with Lipschitz constant bounded by bT . We just point out that thanks to Young inequality (when $1 < p < \infty$)

$$\begin{aligned} \int \int b(x, y)h(y)g(x)^{p-1} dx dy &\leq \int \int b(x, y)[h(y)^p + g(x)^p] dx dy \\ &\leq \|b\|_{L_x^\infty(L_y^{p'})} \|h\|_{L^p}^p + \|b\|_{L_y^\infty(L_x^{p'})} \|g\|_{L^p}^p. \end{aligned}$$

Choosing T small enough, we can apply the Banach-Picard contraction theorem and we get the existence of a fixed point $g \in C([0, T]; L^p)$, $g = \mathcal{U}g$. Proceeding by induction, we obtain in that way a global mild solution to equation (5.5). \square

5.3 Duality and uniqueness in the case $p = \infty$

Theorem 5.3 *Assume $a \in W^{1,\infty}$. For any $g_0 \in L^\infty$ there exists at most one weak solution $g \in L^\infty((0, T) \times \mathbb{R}^d)$ to the transport equation (1.1).*

Elements of proof of Theorem 5.3. Since the equation is linear we only have to prove that the unique weak solution $g \in L^\infty((0, T) \times \mathbb{R}^d)$ associated to the initial datum $g_0 = 0$ is $g = 0$. By definition, for any $\psi \in C_c^1([0, T] \times \mathbb{R}^d)$, there holds

$$\int_0^T \int_{\mathbb{R}^d} g L^* \psi \, dx dt = - \int_{\mathbb{R}^d} g(T) \psi(T) \, dx$$

with $L^* \psi := -\partial_t \psi - \operatorname{div}(a \psi)$. We claim that for any $\Psi \in C_c^1((0, T) \times \mathbb{R}^d)$ there exists a function $\psi \in C_c^1([0, T] \times \mathbb{R}^d)$ such that

$$(5.7) \quad \Lambda^* \psi = \Psi, \quad \psi(T) = 0.$$

If we accept that fact, we obtain

$$\int_0^T \int_{\mathbb{R}^d} g \Psi \, dx dt = 0 \quad \forall \Psi \in C_c^1((0, T) \times \mathbb{R}^d),$$

which in turns implies $g = 0$ and that ends the proof.

Here we can solve easily the backward equation (5.7) thanks to the characteristics method which leads to an explicit representation formula. In order to make the discussion simpler we exhibit that formula for the associated forward problem (we do not want to bother with backward time, but one can pass from a formula to another just by changing time $t \rightarrow T - t$). We then consider the equation

$$\partial_t \psi + a \cdot \nabla \psi + c \psi = \Psi, \quad \psi(0) = 0,$$

with $c := \operatorname{div} a$. Introduction the flow $\Phi_t(x)$ associated to the ODE $\dot{x} = a(x)$, if such a solution exists, we have

$$\frac{d}{dt} \left[\psi(t, \Phi_t(x)) e^{\int_0^t c(\Phi_s(x)) \, ds} \right] = \Psi(t, \Phi_t(x)) e^{\int_0^t c(\Phi_s(x)) \, ds},$$

from which we deduce

$$\psi(t, \Phi_t(x)) = e^{-\int_0^t c(\Phi_\tau(x)) \, d\tau} \int_0^t \Psi(s, \Phi_s(x)) e^{\int_0^s c(\Phi_\tau(x)) \, d\tau},$$

or equivalently, observing that $\Phi_t^{-1} = \Phi_{-t}$ because the ODE is time autonomous, we have

$$\psi(t, x) := \int_0^t \Psi(s, \Phi_{s-t}(x)) e^{-\int_s^t c(\Phi_{\tau-t}(x)) \, d\tau} \, ds.$$

It is clear that ψ defined by the above formula is the solution to our dual problem from which we get (reversing time) the solution to (5.7) we were trying to find. \square