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# Numerical Implementation of the Method of Reflections

*as a Preconditioner for the Multiple  
Scattering Helmholtz Problem using BEM*

# 1 The Multiple Scattering Helmholtz Problem

1 Multiple Scatt. Helmholtz Pb

2 Basics of DIE

3 Algorithm of the MOR

4 Preconditioner for It. Solvers

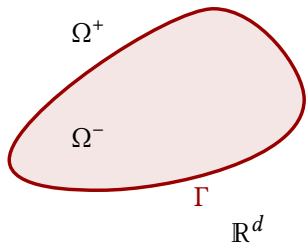
5 Numerical Results

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## Scattering problem:

find  $u \in H_{\text{loc}}^1(\mathbb{R}^d)$  such that:

$$\begin{cases} \Delta u + k^2 u = 0 & \text{in } \Omega^+ \\ u = -u^{\text{inc}} & \text{on } \Gamma \\ u \text{ outgoing} \end{cases}$$

Outgoing  $\rightarrow$  the Sommerfeld radiation condition:

$$\lim_{\|\mathbf{x}\| \rightarrow \infty} \|\mathbf{x}\|^{(d-1)/2} \left( \nabla u \cdot \frac{\mathbf{x}}{\|\mathbf{x}\|} - iku \right) = 0$$

and

$$\forall \mathbf{x} \in \mathbb{R}^d, \quad u^{\text{inc}}(\mathbf{x}) = e^{ik\beta \cdot \mathbf{x}}$$

- ▶  $\Omega^-$  bounded open set of  $\mathbb{R}^d$ ,  
 $d = 2, 3$
- ▶ *propagation domain*  
 $\Omega^+ = \mathbb{R}^d \setminus \overline{\Omega^-}$  connected
- ▶ the boundary of  $\Omega^-$ :  $\Gamma$

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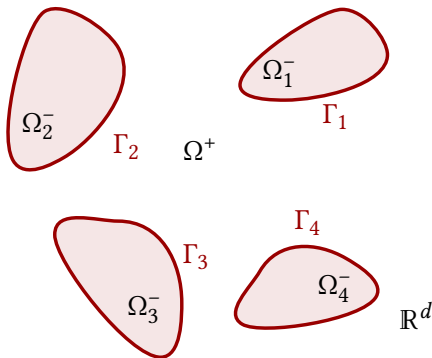
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and

$$\forall \mathbf{x} \in \mathbb{R}^d, \quad u^{\text{inc}}(\mathbf{x}) = e^{ik\beta \cdot \mathbf{x}}$$

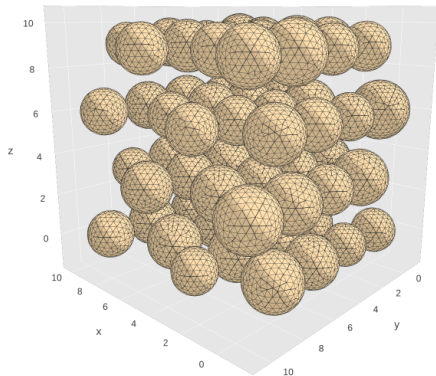
# Multiple Scattering Problem

- ▶ The domain  $\Omega^-$  is a collection of  $N$  disjoint bounded open sets  $\{\Omega_i^-\}_{i \in \llbracket 1, N \rrbracket}$  of  $\mathbb{R}^d$
- ▶ every domain  $\mathbb{R}^d \setminus \overline{\Omega_i^-}$  is connected.



# Multiple Scattering Problem

- ▶ The domain  $\Omega^-$  is a collection of  $N$  **disjoint** bounded open sets  $\{\Omega_i^-\}_{i \in \llbracket 1, N \rrbracket}$  of  $\mathbb{R}^d$
- ▶ every domain  $\mathbb{R}^d \setminus \overline{\Omega_i^-}$  is connected.



# 2 Basics of Direct Integral Equations

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Well known properties that can be found in [Chandler-Wilde et al. 2012; McLean 2000] and references therein.

## SINGLE-LAYER VOLUME OPERATOR

$$\begin{aligned} \mathcal{L} : H^{-1/2}(\Gamma) &\rightarrow H_{\text{loc}}^1(\mathbb{R}^d) \\ \rho &\mapsto \mathcal{L}\rho, \end{aligned} \quad \mathcal{L}\rho(\mathbf{x}) = \int_{\Gamma} G(\mathbf{x}, \mathbf{y})\rho(\mathbf{y})d\Gamma(\mathbf{y})$$

where  $G$  is the usual **Green function** for the Helmholtz problem

## DOUBLE-LAYER VOLUME OPERATOR

$$\begin{aligned} \mathcal{M} : H^{1/2}(\Gamma) &\rightarrow H_{\text{loc}}^1(\mathbb{R}^d \setminus \Gamma) \\ \lambda &\mapsto \mathcal{M}\lambda, \end{aligned} \quad \mathcal{M}\lambda(\mathbf{x}) = - \int_{\Gamma} \partial_{n_{\mathbf{y}}} G(\mathbf{x}, \mathbf{y})\lambda(\mathbf{y})d\Gamma(\mathbf{y})$$



## Proposition

For every densities  $\rho \in H^{-1/2}(\Gamma)$  and  $\lambda \in H^{1/2}(\Gamma)$ , the single-layer potential  $\mathcal{L}\rho$  and the double-layer potential  $\mathcal{M}\lambda$  are outgoing solutions of the Helmholtz equation in  $\mathbb{R}^d \setminus \Gamma$ . Moreover, the scattered field  $u$  can be written as

$$\forall \mathbf{x} \in \Omega^+, \quad u(\mathbf{x}) = -\mathcal{L}(\partial_{\mathbf{n}} u|_{\Gamma})(\mathbf{x}) - \mathcal{M}(u|_{\Gamma})(\mathbf{x}).$$

## Proposition

The trace ( $\gamma_0$ ) and the normal trace ( $\gamma_1$ ) of the operators  $\mathcal{L}$  and  $\mathcal{M}$  are given by the following relations:

$$\gamma_0^\pm \mathcal{L} \rho = L\rho, \quad \gamma_0^\pm \mathcal{M} \lambda = \left( \mp \frac{1}{2} I + M \right) \lambda,$$

$$\gamma_1^\pm \mathcal{L} \rho = \left( \mp \frac{1}{2} I + N \right) \rho, \quad \gamma_1^\pm \mathcal{M} \lambda = D\lambda,$$

where  $I$  is the identity operator and,...

## Proposition

...for  $\mathbf{x} \in \Gamma$ ,  $\rho \in H^{-1/2}(\Gamma)$  and  $\lambda \in H^{1/2}(\Gamma)$ , the four boundary integral operator are defined by

$$L : H^{-1/2}(\Gamma) \rightarrow H^{1/2}(\Gamma), \quad L\rho(\mathbf{x}) = \int_{\Gamma} G(\mathbf{x}, \mathbf{y})\rho(\mathbf{y})d\Gamma(\mathbf{y}),$$

$$M : H^{1/2}(\Gamma) \rightarrow H^{1/2}(\Gamma), \quad M\lambda(\mathbf{x}) = - \int_{\Gamma} \partial_{\mathbf{n}_y} G(\mathbf{x}, \mathbf{y})\lambda(\mathbf{y})d\Gamma(\mathbf{y}),$$

$$N : H^{-1/2}(\Gamma) \rightarrow H^{-1/2}(\Gamma), \quad N\rho(\mathbf{x}) = \int_{\Gamma} \partial_{\mathbf{n}_x} G(\mathbf{x}, \mathbf{y})\rho(\mathbf{y})d\Gamma(\mathbf{y}),$$

$$D : H^{1/2}(\Gamma) \rightarrow H^{-1/2}(\Gamma), \quad D\lambda(\mathbf{x}) = -\partial_{\mathbf{n}_x} \int_{\Gamma} \partial_{\mathbf{n}_y} G(\mathbf{x}, \mathbf{y})\lambda(\mathbf{y})d\Gamma(\mathbf{y}).$$

# Direct Integral Equations (DIE)

- ▶ Choosing an operator  $A$  (a trace operator)

## Scattering problem:

find  $u \in H_{\text{loc}}^1(\mathbb{R}^d)$  s. t.

$$\begin{cases} \Delta u + k^2 u = 0 & \text{in } \Omega^+ \\ u = -u^{\text{inc}} & \text{on } \Gamma \\ u \text{ outgoing} \end{cases}$$

## DIE Problem

find  $\rho \in H^{-1/2}(\Gamma)$  s. t.

$$A\mathcal{L}\rho = -Au^{\text{inc}}, \quad \text{on } \Gamma$$

$$L_A\rho = -Au^{\text{inc}}, \quad \text{with } L_A\rho = A\mathcal{L}\rho$$

**Remark:** Possible choices for  $A$

- ▶  $A = \gamma_0^- : L_A\rho = -Au^{\text{inc}} \rightarrow L\rho = -u|_{\Gamma}^{\text{inc}} \quad (\text{EFIE formulation})$
- ▶  $A = \gamma_1^- : L_A\rho = -Au^{\text{inc}} \rightarrow \left(\frac{1}{2}I + N\right)\rho = -\partial_{\mathbf{n}}u|_{\Gamma}^{\text{inc}} \quad (\text{MFIE formulation})$
- ▶  $A = (1 - \alpha)\gamma_0^- + \alpha\eta\gamma_1^- : \rightarrow \text{linear combination} \quad (\text{CFIE formulation})$

see [Thierry 2014]

The single-layer volume integral operator  $\mathcal{L}$  can be written as the sum of  $N$  operators  $\{\mathcal{L}_i\}_{i \in \llbracket 1, N \rrbracket}$  defined by

$$\mathcal{L}_i : \begin{array}{l} H^{-1/2}(\Gamma_i) \rightarrow H_{\text{loc}}^1(\mathbb{R}^d) \\ \rho_i \mapsto \mathcal{L}_i \rho_i \end{array}, \quad \mathcal{L}_i \rho_i(\mathbf{x}) = \int_{\Gamma_i} G(\mathbf{x}, \mathbf{y}) \rho_i(\mathbf{y}) d\Gamma_i(\mathbf{y})$$

and

$$\forall \rho \in H^{-1/2}(\Gamma), \quad \mathcal{L} \rho = \sum_{i=1}^N \mathcal{L}_i \rho_i, \quad \text{with } \rho_i = \rho|_{\Gamma_i}$$

Defining

$$\forall g \in H^1(\Omega^-), \quad A_i g = (A g)|_{\Gamma_i}$$

it holds that

$$\forall i \in \llbracket 1, N \rrbracket, \quad \sum_{j=1}^N A_i \mathcal{L}_j \rho_j = -A_i u^{\text{inc}}$$

## Complex linear system, non symmetric and dense (BEM)

$$L_A \rho = -A u^{\text{inc}}:$$

$$\begin{pmatrix} L_A^{1,1} & L_A^{1,2} & \dots & L_A^{1,N} \\ L_A^{2,1} & L_A^{2,2} & \dots & L_A^{2,N} \\ \vdots & \vdots & \ddots & \vdots \\ L_A^{N,1} & L_A^{N,2} & \dots & L_A^{N,N} \end{pmatrix} \begin{pmatrix} \rho_1 \\ \rho_2 \\ \vdots \\ \rho_N \end{pmatrix} = - \begin{pmatrix} A_1 u^{\text{inc}} \\ A_2 u^{\text{inc}} \\ \vdots \\ A_N u^{\text{inc}} \end{pmatrix}$$

- ▶  $A$ : a trace operator
- ▶  $\rho$ : unknown ( $-\partial_{\mathbf{n}} u|_{\Gamma}$ )
- ▶  $L_A$ : boundary operator
- ▶  $\forall \rho_j \in H^{-1/2}(\Gamma_j), L_A^{i,j} \rho_j = A_i(\mathcal{L}_j \rho_j)$
- ▶  $L_A^{i,j}$  for  $i \neq j$  interactions between domains
- ▶ **Natural domain decomposition** (decomposition of the boundary)

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# Parallel Method of Reflections (MOR)

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- ▶ Parallel Method of Reflections ([G. M. Golusin 1934; Laurent, Legendre, and Salomon 2017]): domain decomposition method with natural partition (objects)
- ▶ Well suited for the BEM with a boundary decomposition
- ▶ Numerical application: is it useful?
- ▶ Example: Multiple Scattering Problem

**Remark:** *Two versions of the Method of Reflections, one sequential [Smoluchowski 1911] and one parallel, we only consider here the second one.*



# Algorithm of the Parallel MOR

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## INITIALIZATION

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*PDE Context*

$$u^{(0)} = 0$$

Solve

$$\begin{cases} \Delta \delta u_i^{(1)} + k^2 \delta u_i^{(1)} = 0 & \text{in } \Omega^+ \\ \delta u_i^{(1)} = -u^{\text{inc}} & \text{on } \Gamma_i \\ \delta u_i^{(1)} \text{ outgoing} \end{cases}$$

*DIE Context*

$$\forall i \in \llbracket 1, N \rrbracket, \rho_i^{(0)} = 0$$

Solve

$$L_A^{i,i} \delta \rho_i^{(1)} = -A_i u^{\text{inc}}$$

---

## UPDATE

---

$$u^{(1)} = u^{(0)} + \sum_{i=1}^N \delta u_i^{(0)}|_{\Omega^+}$$

$$\forall i \in \llbracket 1, N \rrbracket, \rho_i^{(1)} = \rho_i^{(0)} + \delta \rho_i^{(1)}$$

# Algorithm of the Parallel MOR

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## ITERATIONS $\ell + 1$

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*PDE Context*

Solve

$$\begin{cases} \Delta \delta u_i^{(\ell+1)} + k^2 \delta u_i^{(\ell+1)} = 0 & \text{in } \Omega^+ \\ \delta u_i^{(\ell+1)}|_{\Gamma_i} = - \sum_{j=1, j \neq i}^N \delta u_j^{(\ell)}|_{\Gamma_i} & \text{on } \Gamma_i \\ \delta u_i^{(\ell+1)} \text{ outgoing} \end{cases}$$

*DIE Context*

Solve

$$L_A^{i,i} \delta \rho_i^{(\ell+1)} = - \sum_{j \neq i} L_A^{i,j} \delta \rho_j^{(\ell)}$$

---

## UPDATE

---

$$u^{(\ell+1)} = u^{(\ell)} + \sum_{i=1}^N \delta u_i^{(\ell+1)}|_{\Omega^+}$$

$$\rho_i^{(\ell+1)} = \rho_i^{(\ell)} + \delta \rho_i^{(\ell+1)}$$

# 4 Preconditioner for Iterative Solvers

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- ▶ Is the MOR useful **as a solver?** → No, compared to a GMRES solver applied to the global problem with hierarchical matrix structures

## Preconditioned Block Jacobi Method

The method of reflections for the multiple scattering Helmholtz problem using direct integral equation is equivalent to the block Jacobi method, that is to say, the following iterative solver:

$$\forall \ell \in \mathbb{N}, \quad D_A \rho^{(\ell+1)} = D_A \rho^{(\ell)} + (F - L_A \rho^{(\ell)})$$

where  $D_A = \text{diag}((L_A^{i,i})_{i \in \llbracket 1, N \rrbracket})$  and  $F = -Au^{\text{inc}}$

- ▶ Proved by induction

- ▶ **Preconditioner**:  $D_A^{-1}$  for an iterative solver, *i.e.*, Generalized Conjugate Residual (GCR), GMRES, etc. (see [Saad 2003])
- ▶ The convergence of the MOR (Jacobi) is not guaranteed, but convergence occurs for **Krylov subspace methods**
- ▶ Structure of

$$D_A^{-1} = \begin{pmatrix} L_A^{1,1^{-1}} & 0 & \dots & 0 \\ 0 & L_A^{2,2^{-1}} & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & L_A^{N,N^{-1}} \end{pmatrix}$$

→ **Parallel preconditioner**

# 5 Numerical Results

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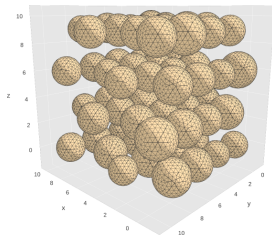
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# Numerical Results with GCR algorithm

- ▶ Set of spheres with different radius in 3D



# Numerical Results with GCR algorithm

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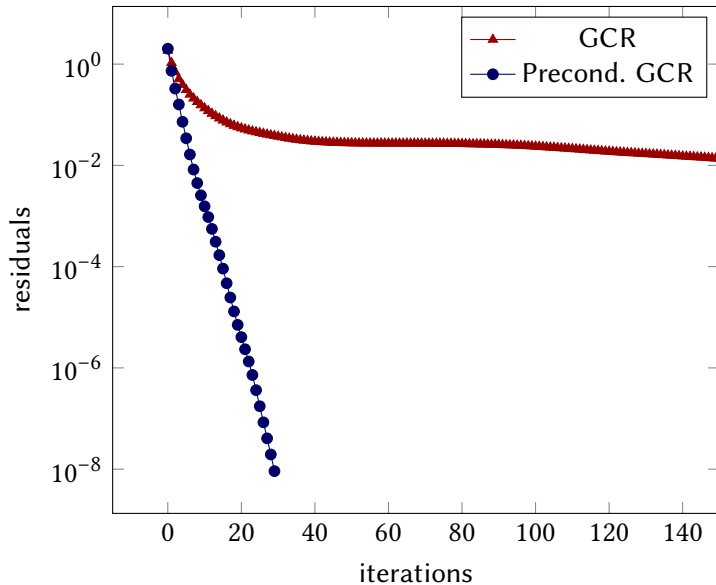
- ▶ **Set of spheres** with different radius in 3D
- ▶ Operator matrices computed **by BEMPP** (python)<sup>1</sup> ([Scroggs et al. 2017]), linear problem solved with a **homemade preconditioned GCR solver** (python+numpy)
- ▶ Useful when the spheres are close to each other
- ▶ Well known preconditioner: see [Thierry 2014]
- ▶ **Numerical study** depending on the number of spheres using the (small) cluster of the laboratory CEREMADE, Université Paris-Dauphine: one node with 40CPUs and 128Go of RAM

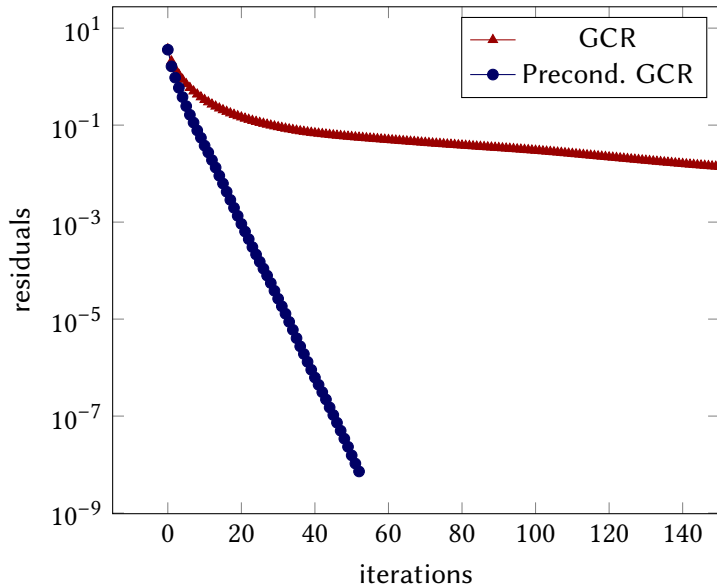
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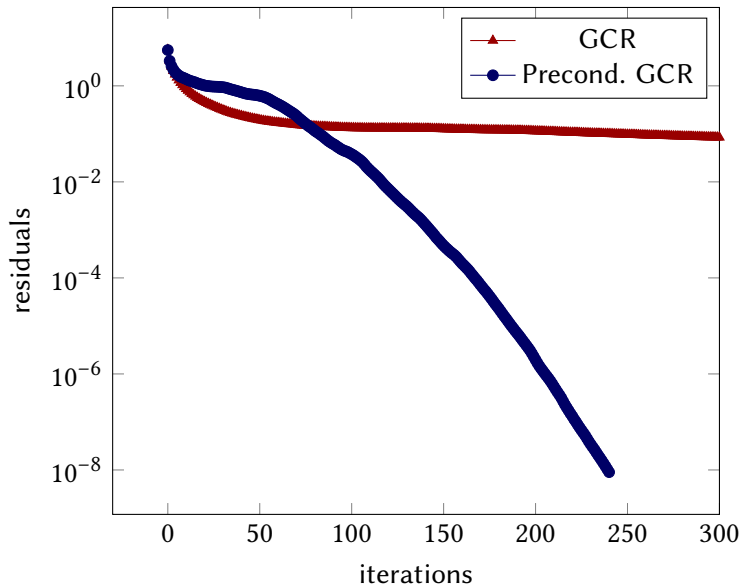
<sup>1</sup>[www.bempp.com](http://www.bempp.com)



# 8 Spheres







- ▶ Distance between centers of spheres is 3.3, and random radius are between 1 and 1.6
- ▶ 3D positioning

Number of Spheres	D.o.F.	GCR it.	Precond. GCR it.
8	3464	412	30
27	12246	>500	52
64	34024	>500	240

# 6 Averaged MOR

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# Algorithm of the Averaged Parallel MOR

- $(\omega_i)_{i \in \llbracket 1, N \rrbracket} \in \mathbb{R}^N$  s.t.  $\sum_{i=1}^N \omega_i = 1$  and  $\forall i \in \llbracket 1, N \rrbracket, \omega_i > 0$

## INITIALIZATION

*PDE Context*

$$u^{(0)} = 0$$

Solve

$$\begin{cases} \Delta \delta u_i^{(1)} + k^2 \delta u_i^{(1)} = 0 & \text{in } \Omega^+ \\ \delta u_i^{(1)} = -u^{\text{inc}} & \text{on } \Gamma_i \\ \delta u_i^{(1)} \text{ outgoing} \end{cases}$$

*DIE Context*

$$\forall i \in \llbracket 1, N \rrbracket, \rho_i^{(0)} = 0$$

Solve

$$L_A^{i,i} \delta \rho_i^{(1)} = -A_i u^{\text{inc}}$$

## UPDATE

$$u^{(1)} = u^{(0)} + \sum_{i=1}^N \omega_i \delta u_i^{(1)} \Big|_{\Omega^+}$$

$$\forall i \in \llbracket 1, N \rrbracket, \rho_i^{(1)} = \rho_i^{(0)} + \omega_i \delta \rho_i^{(1)}$$

# Algorithm of the Averaged Parallel MOR

ITERATION  $\ell + 1$

*PDE Context*

*DIE Context*

Solve

Solve

$$\left\{ \begin{array}{ll} \Delta \delta u_i^{(\ell+1)} + k^2 \delta u_i^{(\ell+1)} = 0 & \text{in } \Omega^+ \\ \delta u_i^{(\ell+1)}|_{\Gamma_i} = (1 - \omega_i) \delta u_i^{(\ell)}|_{\Gamma_i} & \text{on } \Gamma_i \\ \quad - \sum_{j \neq i} \omega_j \delta u_j^{(\ell)}|_{\Gamma_i} & \\ \delta u_i^{(\ell+1)} \text{ outgoing} & \end{array} \right.$$

$$\begin{aligned} L_A^{i,i} \delta \rho_i^{(\ell+1)} &= (1 - \omega_i) \delta \rho_i^{(\ell)} \\ &\quad - \sum_{j \neq i} L_A^{i,j} \omega_j \delta \rho_j^{(\ell)} \end{aligned}$$

UPDATE

$$u^{(\ell+1)} = u^{(\ell)} + \sum_{i=1}^N \omega_i \delta u_i^{(\ell+1)}|_{\Omega^+}$$

$$\rho_i^{(\ell+1)} = \rho_i^{(\ell)} + \omega_i \delta \rho_i^{(\ell+1)}$$

# Weighted Preconditioner of Iterative Solvers

## Weighted Preconditioned Block Jacobi Method

The method of reflections for the multiple scattering Helmholtz problem using direct integral equation is equivalent to the weighted block Jacobi method, that is to say, the following iterative solver:

$$\forall \ell \in \mathbb{N}, \forall i \in \llbracket 1, N \rrbracket \quad \rho_i^{(\ell+1)} = \rho_i^{(\ell)} + \omega_i L_A^{i,i-1} \left( F_i - \sum_{j=1}^N L_A^{i,j} \rho_j^{(\ell)} \right)$$

- ▶ Once again proved by induction
- ▶ Preconditioner:  $\mathbf{H} = \sum_{i=1}^N \omega_i R_i^T L_A^{i,i-1} R_i$  where  $R_i$  is the restriction operator
- ▶ How to choose the weights  $\omega_i$ ?



# Connection with Multipreconditioning

- ▶ Averaged MOR preconditioner:

$$\mathbf{H} = \sum_{k=1}^N \omega_k R_k^T L_A^{k,k-1} R_k$$

- ▶ *Additive Schwarz with Variable Weights* [Greif, Rees, and Szyld 2012]: sequence of preconditioners

$$M^{(i)} = \sum_{k=1}^N \alpha_k^{(i)} R_k^T A_k^{-1} R_k$$

- ▶ Multipreconditioning with the MOR preconditioner gives sequence  $(\omega_k^{(i)})_{k \in \llbracket 1, N \rrbracket}$
- ▶ Implementation of a multipreconditioned CGR

# 7 Multipreconditioned GCR

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# (Multi)Preconditioned GCR I

► **MOR Preconditioner**:  $\mathbf{H} = D_A^{-1} = \sum_{k=1}^N R_k^T L_A^{k,k-1} R_k = \sum_{k=1}^N \mathbf{H}^k$

Preconditioned GCR

Multipreconditioned GCR

```

1  $\mathbf{r}_0 = \mathbf{b} - \mathbf{A}\mathbf{x}_0$ ;  $\mathbf{z}_0 = \mathbf{H}\mathbf{r}_0$ ;  $\mathbf{p}_0 = \mathbf{z}_0$ 
2  $\mathbf{q}_0 = \mathbf{A}\mathbf{p}_0$ 
3 for  $i = 0, 1, \dots$ , conv. do
4    $\Delta_i = \mathbf{q}_i^\top \mathbf{q}_i$ ;    $\gamma_i = \mathbf{q}_i^\top \mathbf{r}_i$ ;    $\alpha_i = \Delta_i^{-1} \gamma_i$ 
5    $\mathbf{x}_{i+1} = \mathbf{x}_i + \mathbf{p}_i \alpha_i$    ←  $\alpha_i \in \mathbb{R}, \mathbf{p}_i \in \mathbb{R}^n$ 
6    $\mathbf{r}_{i+1} = \mathbf{r}_i - \mathbf{q}_i \alpha_i$ 
7    $\mathbf{z}_{i+1} = \mathbf{H}\mathbf{r}_{i+1}$    ← Precond.
8    $\forall j \in \llbracket 0, i \rrbracket, \Phi_{i,j} = \mathbf{q}_j^\top (\mathbf{A}\mathbf{z}_{i+1})$ 
    $\beta_{i,j} = \Delta_j^{-1} \Phi_{i,j}$ 
9    $\mathbf{p}_{i+1} = \mathbf{z}_{i+1} - \sum_{j=0}^i \mathbf{p}_j \beta_{i,j}$    ← Ortho.
10   $\mathbf{q}_{i+1} = (\mathbf{A}\mathbf{z}_{i+1}) - \sum_{j=0}^i \mathbf{q}_j \beta_{i,j}$ 
11 end
12 Return  $\mathbf{x}_{i+1}$ 

```

```

 $\mathbf{r}_0 = \mathbf{b} - \mathbf{A}\mathbf{x}_0$ ;  $\mathbf{Z}_0 = [\mathbf{H}^1 \mathbf{r}_0 \mid \dots \mid \mathbf{H}^N \mathbf{r}_0]$ ;  $\mathbf{P}_0 = \mathbf{Z}_0$ 
 $\mathbf{Q}_0 = \mathbf{A}\mathbf{P}_0$ 
for  $i = 0, 1, \dots$ , conv. do
   $\Delta_i = \mathbf{Q}_i^\top \mathbf{Q}_i$ ;    $\gamma_i = \mathbf{Q}_i^\top \mathbf{r}_i$ ;    $\alpha_i = \Delta_i^{-1} \gamma_i$ 
   $\mathbf{x}_{i+1} = \mathbf{x}_i + \mathbf{P}_i \alpha_i$    ←  $\alpha_i \in \mathbb{R}^N, \mathbf{P}_i \in \mathbb{R}^{n \times N}$ 
   $\mathbf{r}_{i+1} = \mathbf{r}_i - \mathbf{Q}_i \alpha_i$ 
   $\mathbf{Z}_{i+1} = [\mathbf{H}^1 \mathbf{r}_{i+1} \mid \dots \mid \mathbf{H}^N \mathbf{r}_{i+1}]$    ← Multi.
   $\forall j \in \llbracket 0, i \rrbracket, \Phi_{i,j} = \mathbf{Q}_j^\top (\mathbf{A}\mathbf{Z}_{i+1})$ 
    $\beta_{i,j} = \Delta_j^{-1} \Phi_{i,j}$ 
   $\mathbf{P}_{i+1} = \mathbf{Z}_{i+1} - \sum_{j=0}^i \mathbf{P}_j \beta_{i,j}$    ← Ortho.
   $\mathbf{Q}_{i+1} = (\mathbf{A}\mathbf{Z}_{i+1}) - \sum_{j=0}^i \mathbf{Q}_j \beta_{i,j}$ 
end
Return  $\mathbf{x}_{i+1}$ 

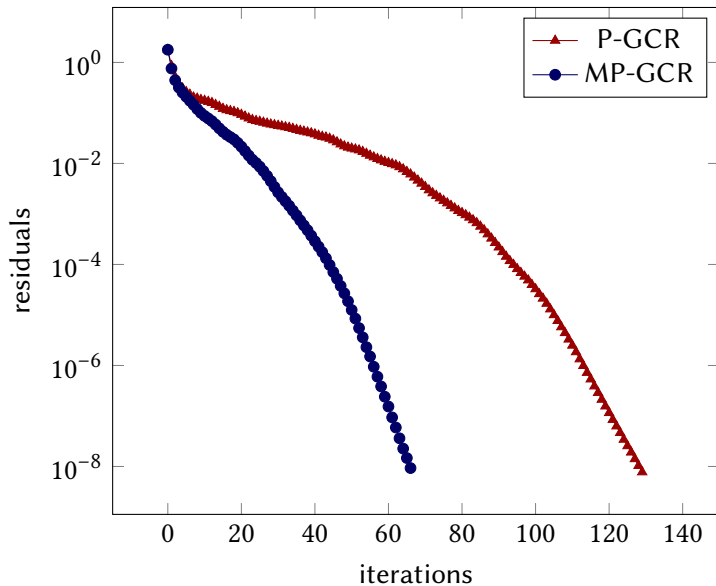
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## – RECALL OF PROPERTIES OF (MULTI)PRECONDITIONED GCR –

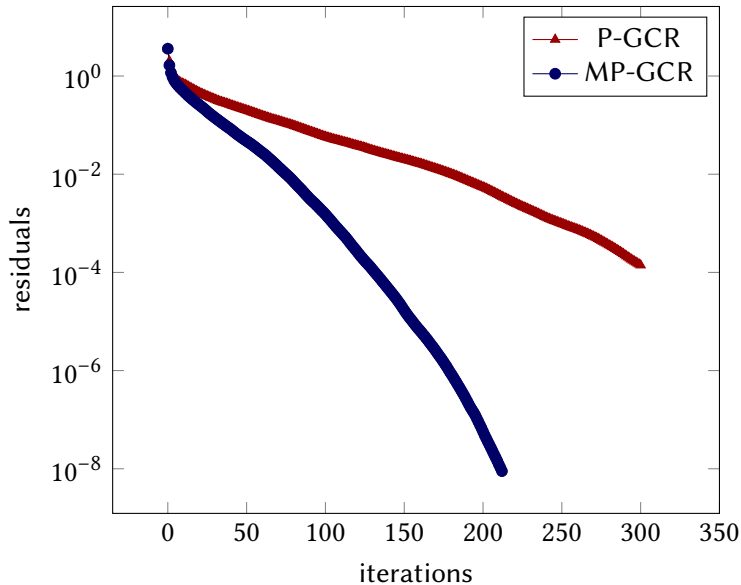
- ▶  $\|\mathbf{r}_i\|_{\ell_2} = \|\mathbf{x}_* - \mathbf{x}_i\|_{\mathbf{A}^\top \mathbf{A}} = \min \left\{ \|\mathbf{x}_* - \mathbf{x}\|_{\mathbf{A}^\top \mathbf{A}}; \mathbf{x} \in \mathbf{x}_0 + \bigoplus_{j=0}^{i-1} \text{range}(\mathbf{P}_j) \right\},$
- ▶  $\mathbf{P}_i^\top (\mathbf{A}^\top \mathbf{A}) \mathbf{P}_j = \mathbf{0}$  for every  $j = 0, \dots, i-1$ .
- ▶ See [Bovet, Gosselet, and Spillane 2017; Bridson and Greif 2006]
- ▶ MOR multipreconditioner:

$$\mathbf{H}^{(i)} = \sum_{k=1}^N \omega_k^{(i)} R_k^\top L_A^{k,k^{-1}} R_k$$

## 8 Spheres Test

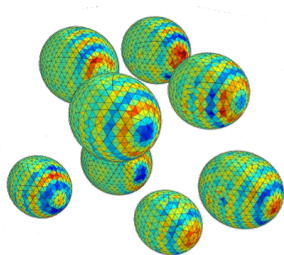


## 27 Spheres Test



- ▶ **CPU time** → be sure about what to compare
- ▶ Numerical study of the **influence of the distance** between the spheres and the consequence for the weights
- ▶ More irregular objects
- ▶ **Adaptive Multipreconditioning**
- ▶ Improve preconditioning with **a coarse space** coming from a simpler problem (smaller objects with a rough discretization?)

# Thank you!





# 9 References

- 1 Multiple Scatt. Helmholtz Pb
- 2 Basics of DIE
- 3 Algorithm of the MOR
- 4 Preconditioner for It. Solvers

- 5 Numerical Results
- 6 Averaged MOR
- 7 Multipreconditioned GCR
- 8 Perspectives
- 9 References



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