

Random walk in 1d diffusive random environment

François Huveneers

discussions with F. Simenhaus, M. Salvi and F. Völlering



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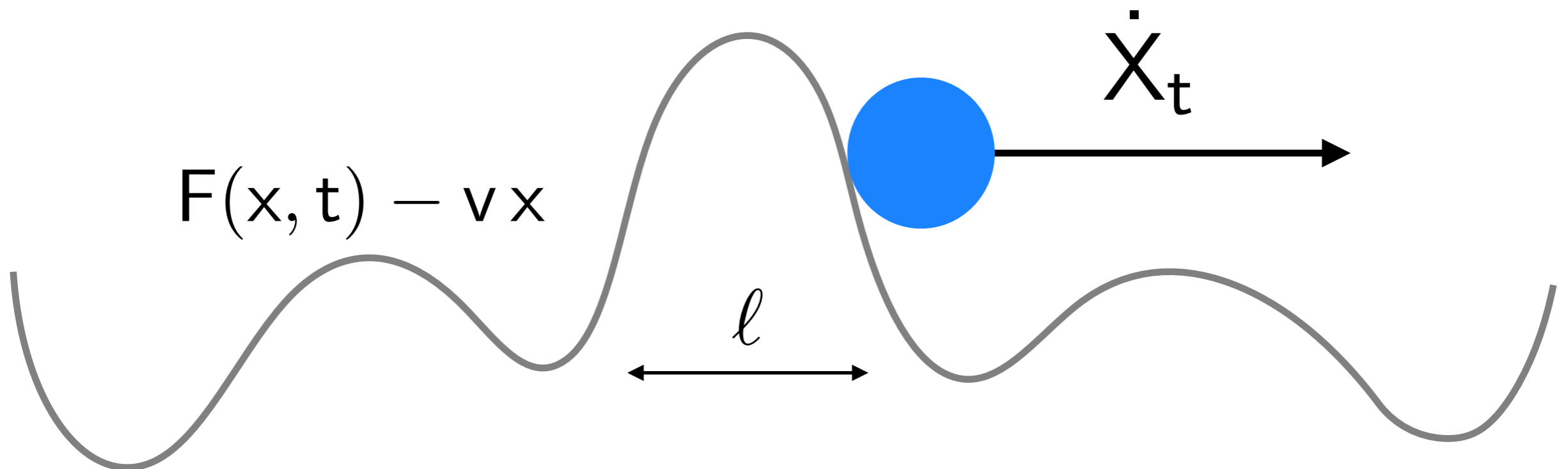
ICTS, Bangalore 2017

Passive particle = walker
on a fluctuating surface

$$\dot{X}_t = \lambda \left(-\partial_x F(X_t, t) + v \right) \quad (\lambda > 0)$$

fluctuation

drift ($0 \leq v \ll 1$)



the fluctuating surface $F(x,t)$

$F(x,t)$ of Edwards-Wilkinson type:

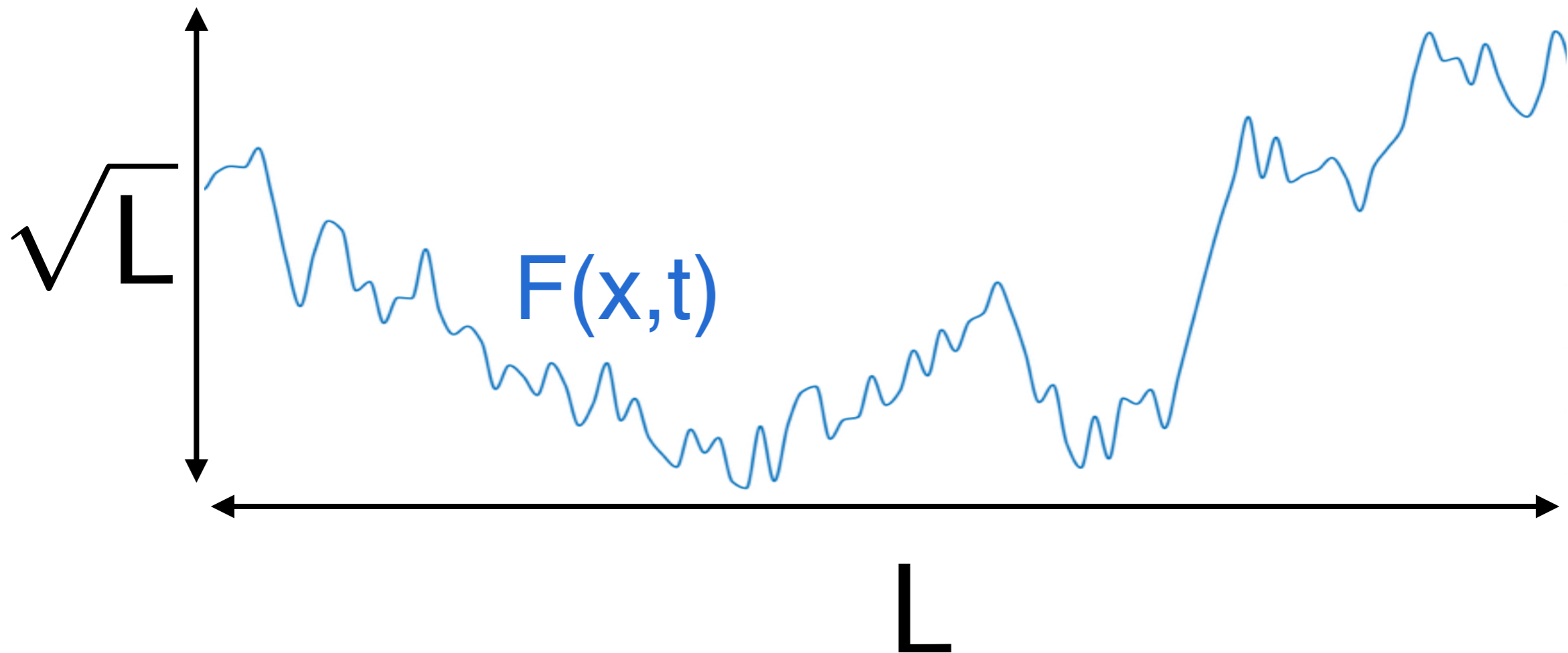
- $\langle \partial_x F(x, t) \rangle = 0$
- $\partial_t F = D \partial_x^2 F + \xi$ (D: diffusion constant)
- $\xi = \xi(x, t)$ white noise in time,
correlation length ℓ in space ($\ell = 1$ here)

Remark:

- Two rates: λ, D
- Dimensionless control parameters: $\lambda/D, v$

Main characteristics of $F(x,t)$

Relaxation time $\sim L^2 / D$

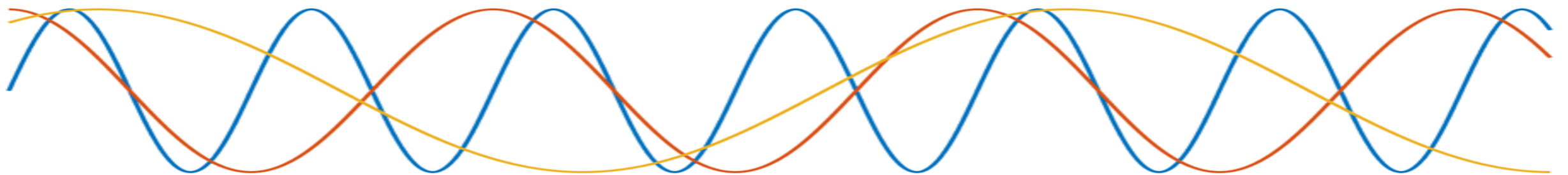


Formal definition of $F(x,t)$

$$-\partial_x F(x, t) = \int_{\mathbb{R}} dk (\sqrt{\ell} e^{-(k\ell)^2}) (A_k(t) e^{ikx} + cc) \quad (\ell = 1)$$

$$\langle A_k(s) A_{k'}^*(t) \rangle = \delta(k - k') e^{-Dk^2|t-s|} \quad (\text{gaussian})$$

The field is a superposition of independent modes:

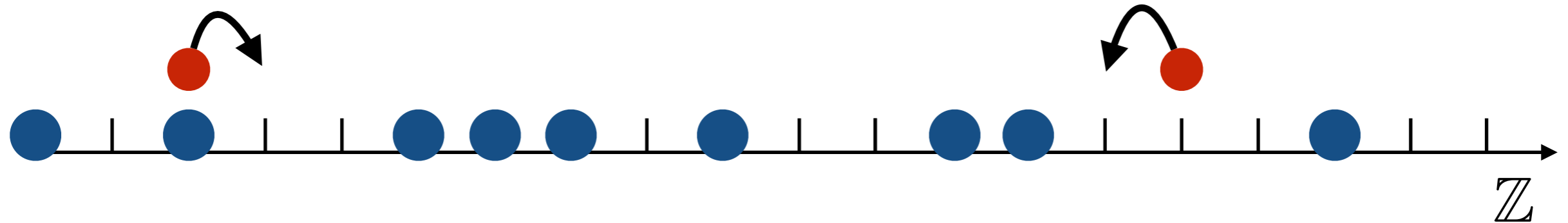


mode k : wavelength: $1/k$ relaxation time: $1/Dk^2$

both useful way to think, and used in the numerics

Similar behavior expected for similar models

e.g. popular lattice model (see Avena and Thomann, J. Stat. Phys. 2012):



$$-\partial_x F + v$$



SSEP at density $\rho = 1/2 + v$

diffusion constant D



SSEP with rate D

coupling strength λ



jump rate λ of the walker

Randomness on the walker (molecular mobility) could be added too

What is interesting about it?

- 1) Diffusive environment come out naturally in the presence of single conserved quantity
- 2) Predicting the behavior of the walker is puzzling!

$$\langle \partial_x F(x, s) \partial_x F(y, t) \rangle \sim \frac{e^{-\frac{(x-y)^2}{D|t-s|}}}{(D|t-s|)^{1/2}}$$

Slow decay of correlations \Rightarrow memory effects

\Rightarrow **???**

Main questions

- 1) Does the walker reach a NESS at $v > 0$ and/or $v = 0$?
If yes, how fast?

NESS: non-equilibrium stationary state,
invariant measure for the environment seen by the walker.

- 2) For $v > 0$, let $V(v) = \lim_{t \rightarrow \infty} X_t^v / t$

$$V(v) \sim v^\alpha \quad \text{as } v \rightarrow 0, \quad \alpha ?$$

- 3) For $v=0$,

$$\langle X_t^2 \rangle \sim t^\beta \quad \text{as } t \rightarrow \infty, \quad \beta ?$$

- 4) Do the answers depend on the value of λ/D ?

These questions are correlated

Much can be learned by studying the response of a system to an external perturbation.

E.g. linear response relates diffusion in equilibrium to fluxes out of equilibrium.

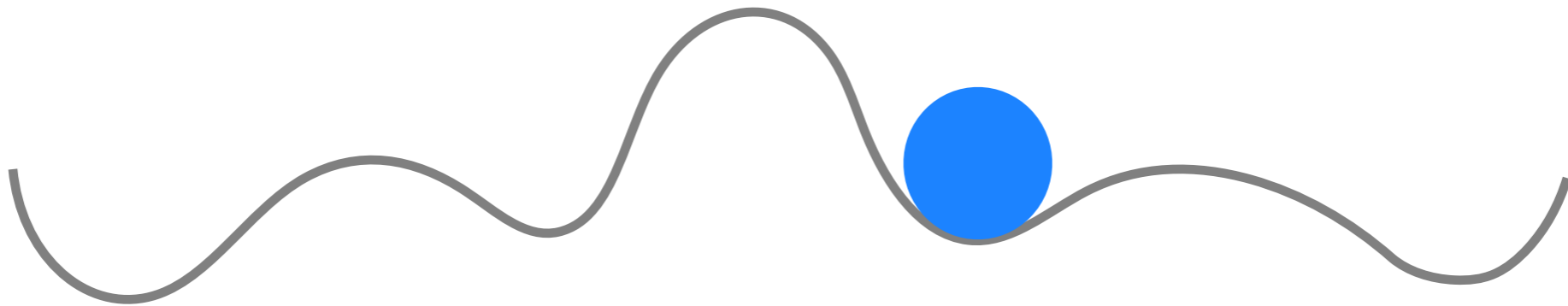
Generalization to systems out of equilibrium usually relies on the existence of a NESS.

Two distinct regimes

(Gopalakrishnan, Phys Rev. E, 2004)

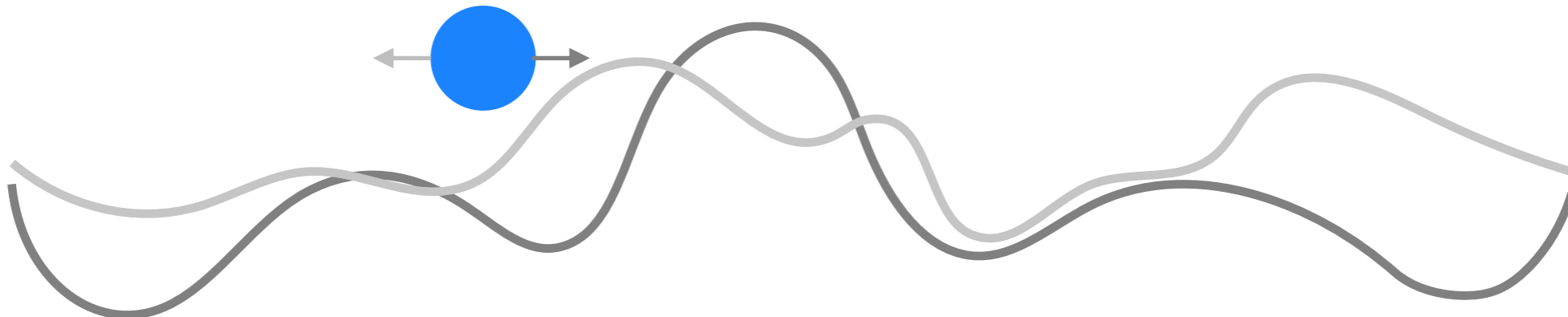
$\lambda/D \gg 1$: quasi-static or trapped

the walker sticks to the minima of $F(x,t) - vx$



$\lambda/D \ll 1$: homogenized regime

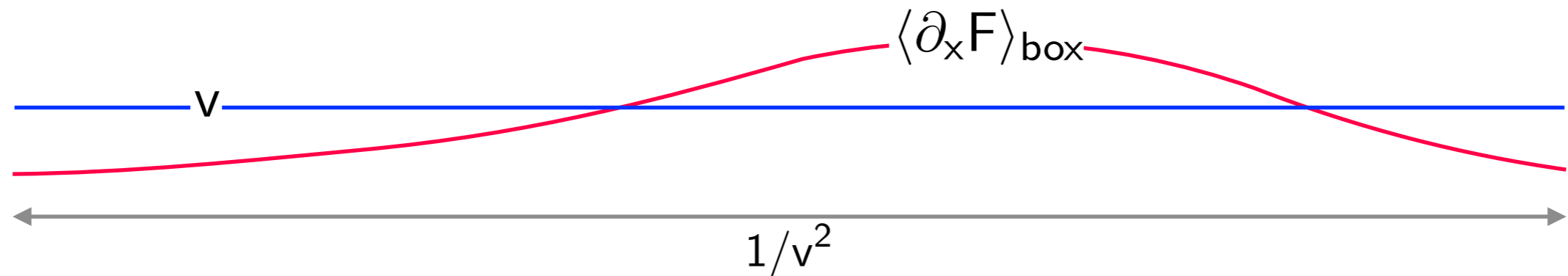
the walker evolves slower than the environment



1) Trapped regime $\lambda/D \gg 1$

Drift $V(v)$ for $v \rightarrow 0$

Spatial average of $\partial_x F$ in a box of size $1/v^2$: v



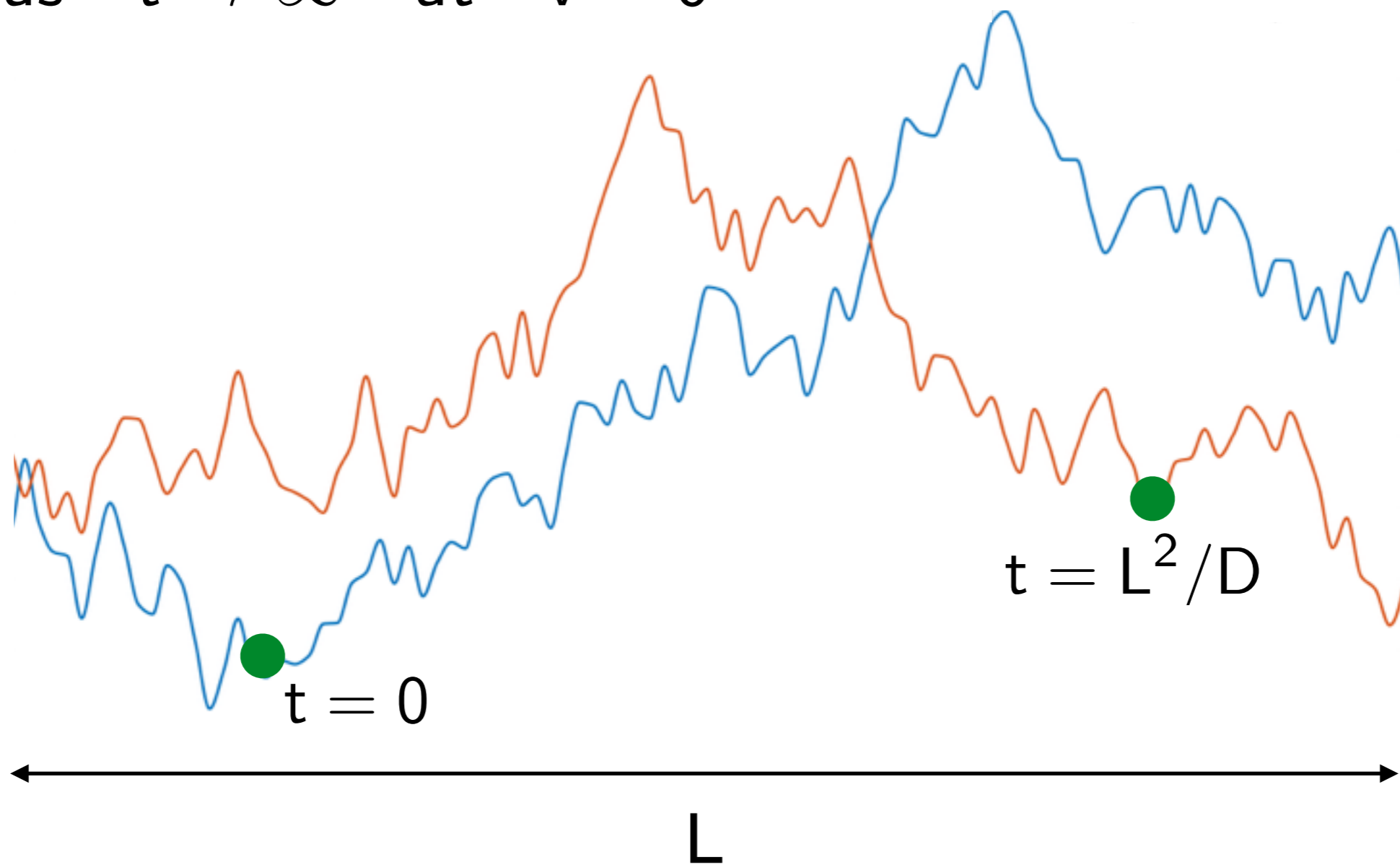
Relaxation time in this box : $1/Dv^4$
~ time to pass across

hence

$$V(v) = \frac{\text{space}}{\text{time}} = \frac{1/v^2}{1/Dv^4} = D^{-1} v^2$$

1) Trapped regime $\lambda/D \gg 1$

$\langle X_t^2 \rangle$ as $t \rightarrow \infty$ at $v = 0$



hence

$$\langle X_t^2 \rangle = Dt$$

2) Homogenized regime $\lambda/D \ll 1$

Self-consistent approximation:

$$X_t = \lambda \int_0^t ds \left(-\partial_x F(X_s, s) + v \right)$$



$$X_t = \lambda \int_0^t ds \left(-\partial_x F(Y_s, s) + v \right)$$

- Y_t is independent from the environment
- X_t and Y_t have same law

can make sense if the walker is indeed not trapped

2) Homogenized regime $\lambda/D \ll 1$

Solving for the 1st moment at $\mathbf{v} > \mathbf{0}$:

$$\langle \mathbf{X}_t \rangle = \lambda \mathbf{v} t \quad \Rightarrow \quad \boxed{V(\mathbf{v}) = \lambda \mathbf{v}}$$

Solving (gaussian approx.) for the second moment at $\mathbf{v} = \mathbf{0}$:

$$\langle \mathbf{X}_t^2 \rangle = \lambda^2 \int_0^t \int_0^t ds ds' \langle \partial_x F(\mathbf{Y}_s, s) \partial_x F(\mathbf{Y}_{s'}, s') \rangle$$

$$\Rightarrow \dots \Rightarrow \boxed{\langle \mathbf{X}_t^2 \rangle = (\lambda t)^{4/3}}$$

see F. Völlering, in prep.

Validity of the self-consistent approximation

- For the SCA to be valid, the NESS should exist and “resemble” the equilibrium state of the environment
- Dynamical point of view: fluctuations at all scales should be strong enough to overcome the trapping



SCA yields the same super-diffusive exponent for Sinai walk in a static environment. We know $\langle X_T^2 \rangle \sim (\log T)^4$

Numerical results

- 1) time to stationarity at $v > 0$. Useful both by itself and to tune numerical experiments.
- 2) $V(v)$ as $v \rightarrow 0$
- 3) $\langle X_t^2 \rangle$ as $t \rightarrow \infty$ at $v = 0$

Numerics reveal that

- 1) the walker is always trapped (quasi-static regime)
- 2) possible important finite size effects
- 3) possible logarithmic like corrections wrt naive predictions (to be discussed later)

Time T to stationarity at $v > 0$

- Consider $-\partial_x F + v$ and decompose

$$-\partial_x F(x, t) = \int_{|k| \leq (cv)^2} dk(\dots) + \int_{|k| > (cv)^2} dk(\dots)$$

amplitude: $cv \ll v$.
Neglect this term!

get refreshed
in a time $1/Dv^4$

For generic observables:

$$T \sim 1/Dv^4$$

- Thus $v > 0$ = infra-red cut-off
- We expect **no NESS** at $v = 0$

Numerics: convergence of $V(v)$

We test this scaling on

$$V(v, t) = \frac{\langle X_t \rangle}{t} \rightarrow V(v) \quad \text{as } t \rightarrow \infty$$

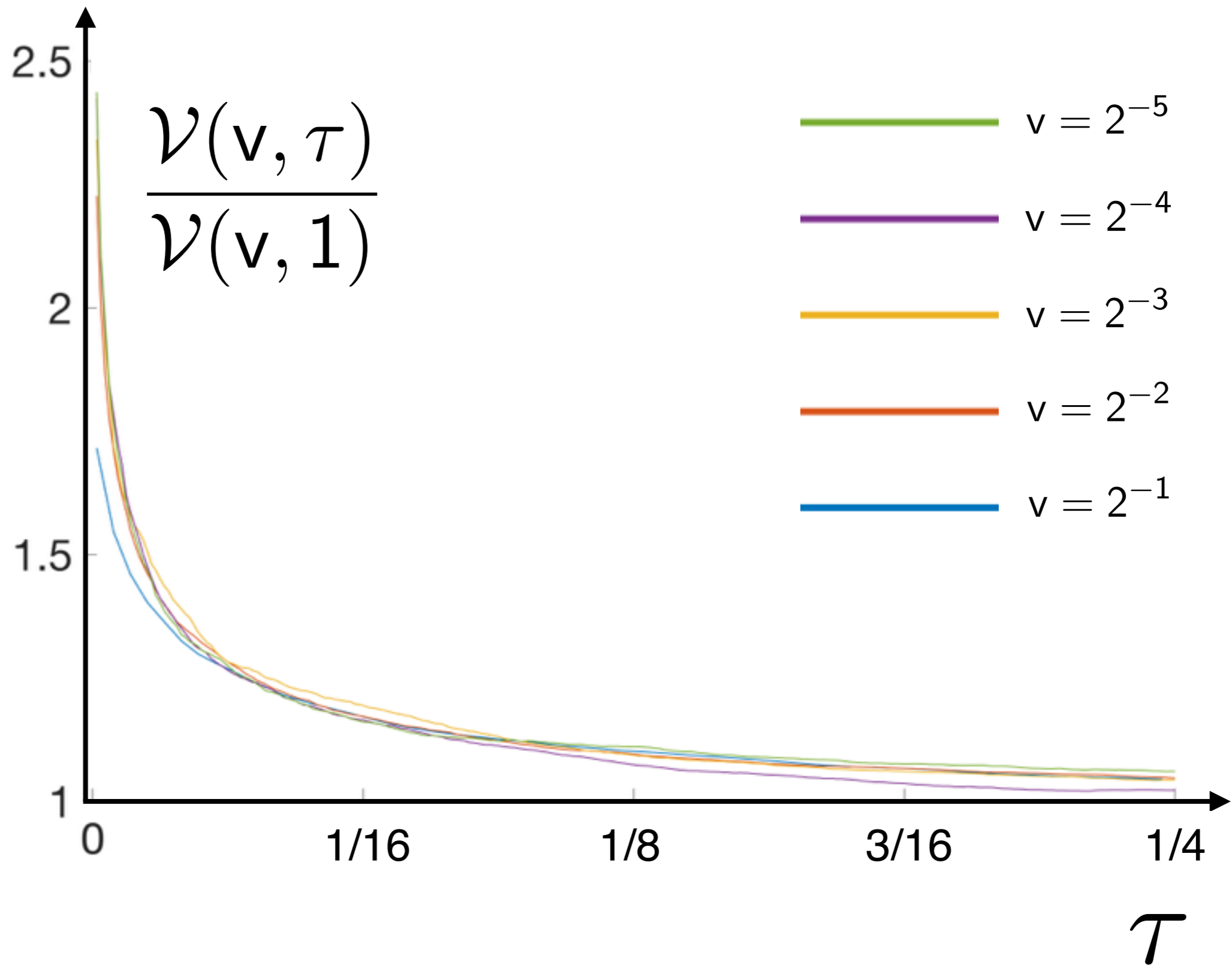
Given $v > 0$, let $t_* = K/Dv^4$ ($K \gg 1$)

$$\tau = t/t_*$$

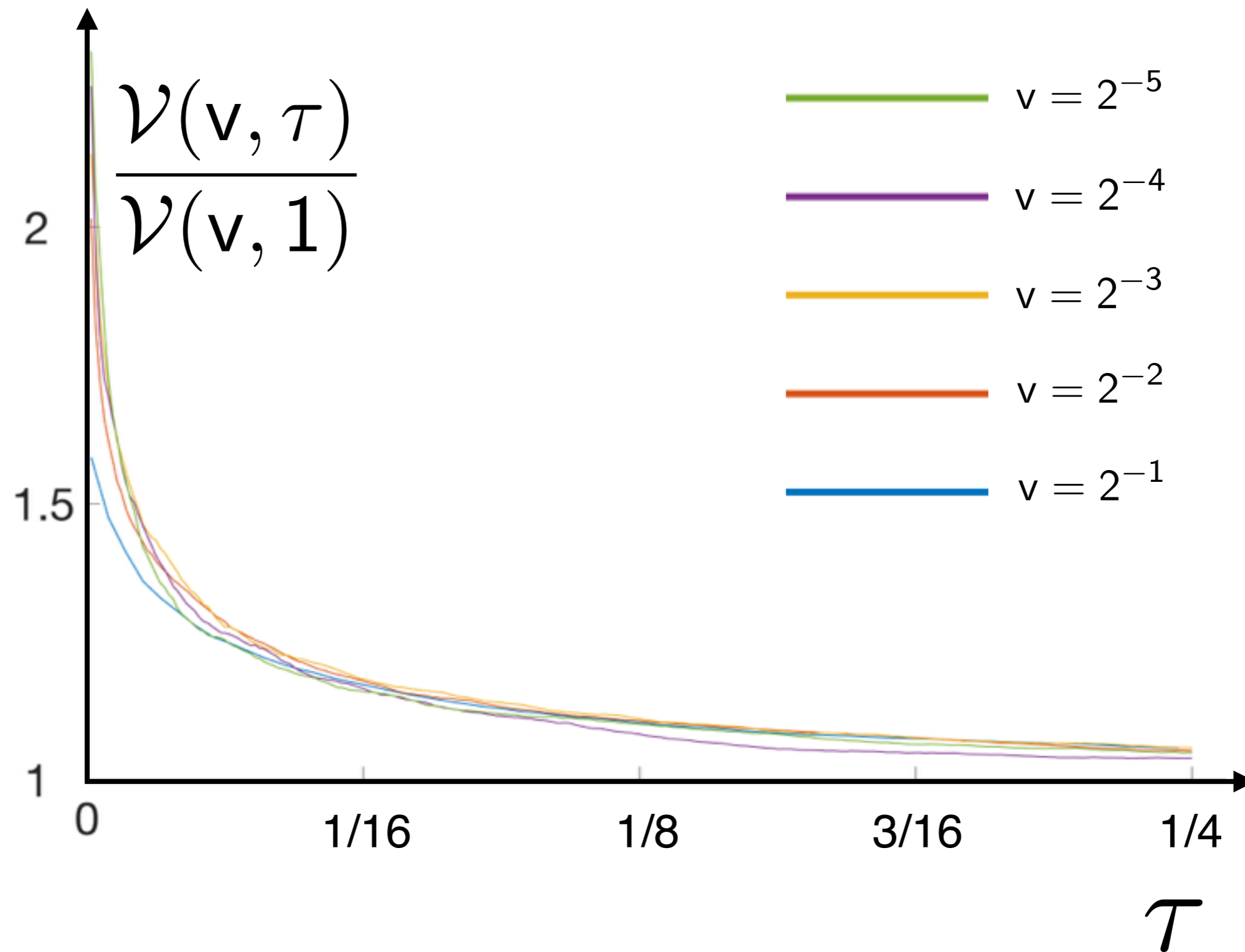
Define \mathcal{V} as a function of rescaled time:

$$\mathcal{V}(v, \tau) = \frac{\langle X_{t_*\tau} \rangle}{t_*\tau}$$

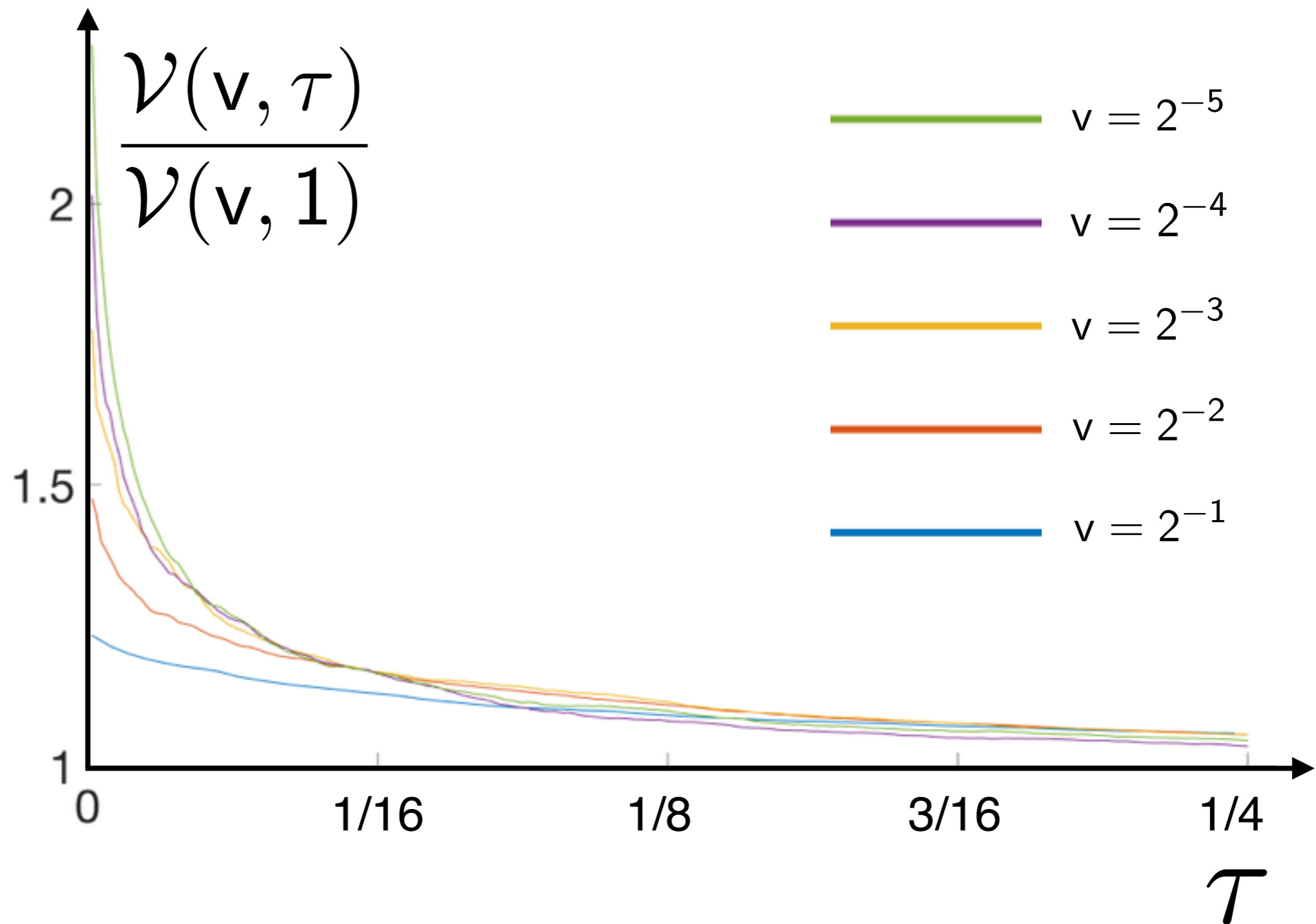
$\lambda = 1$ (D = 1 for numerics)



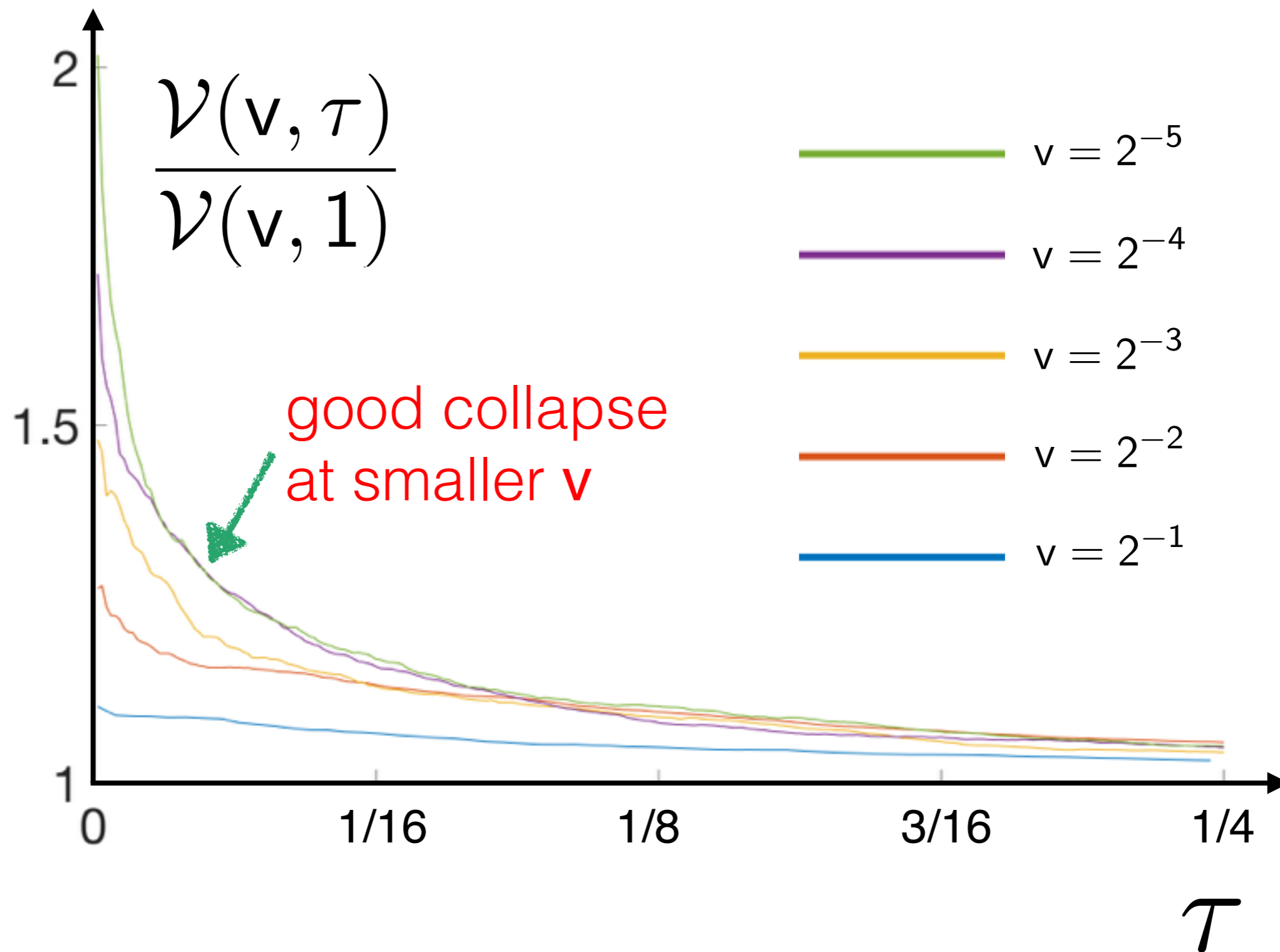
$$\lambda = 1/2$$



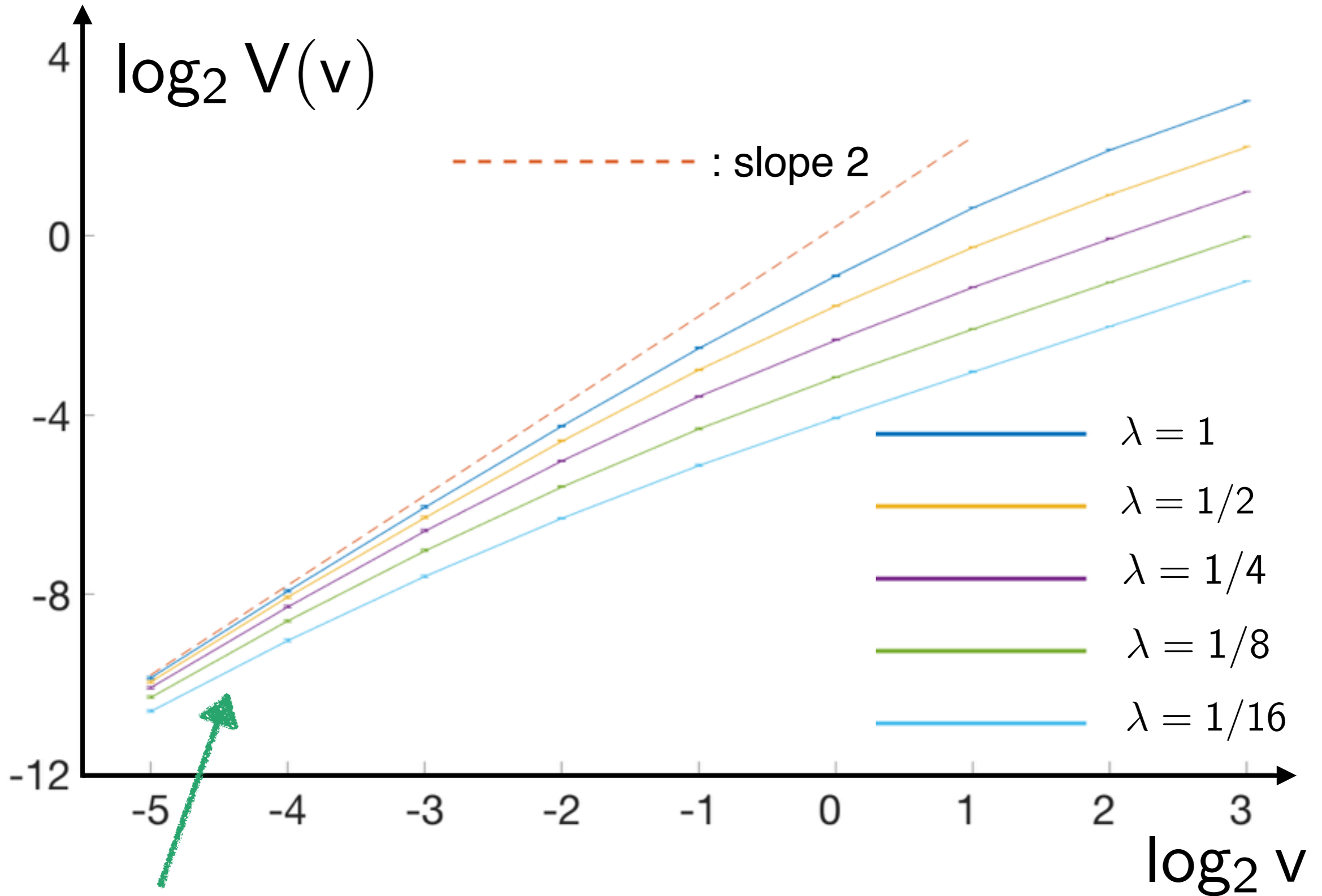
$$\lambda = 1/8$$



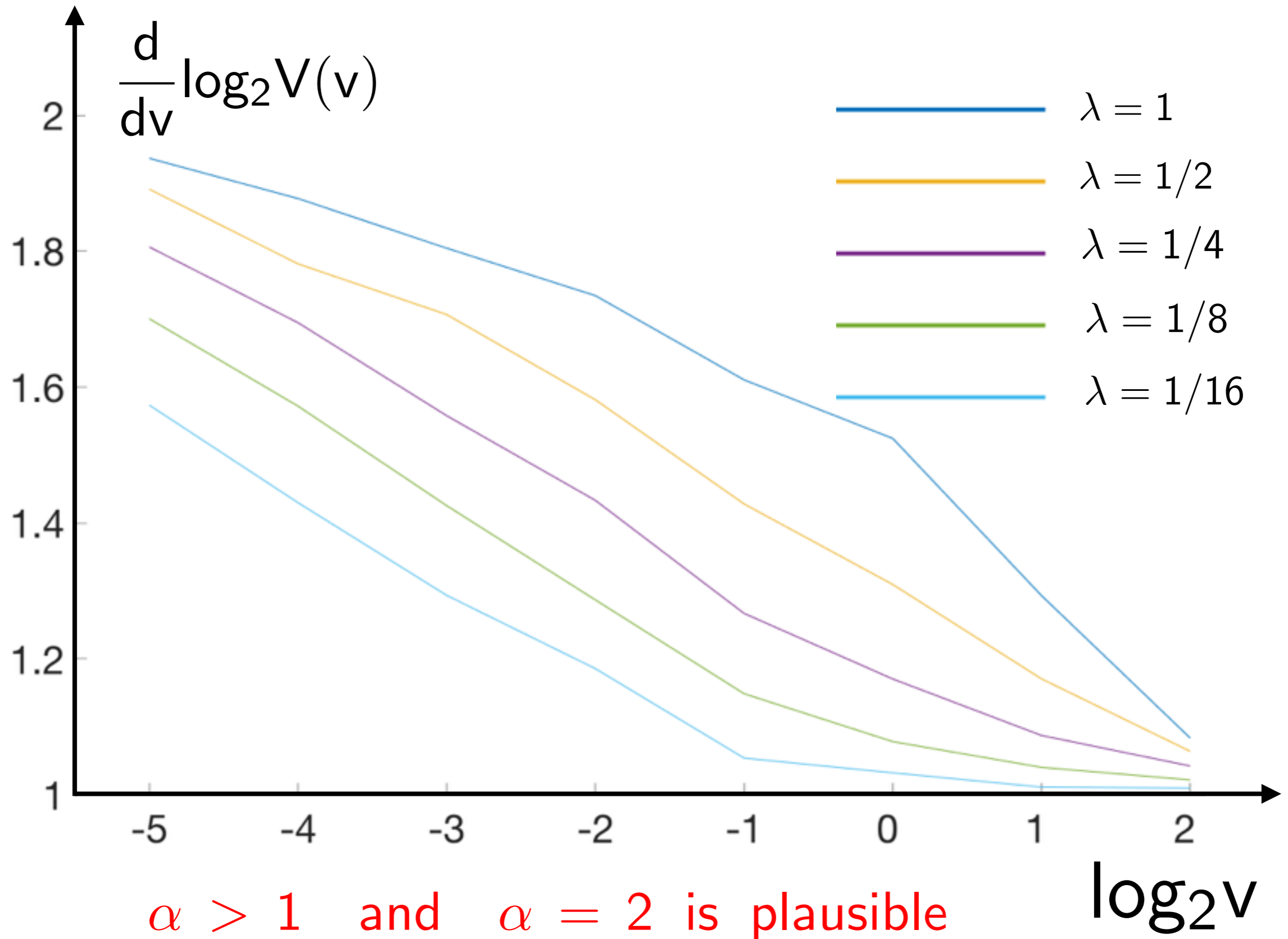
$$\lambda = 1/16$$



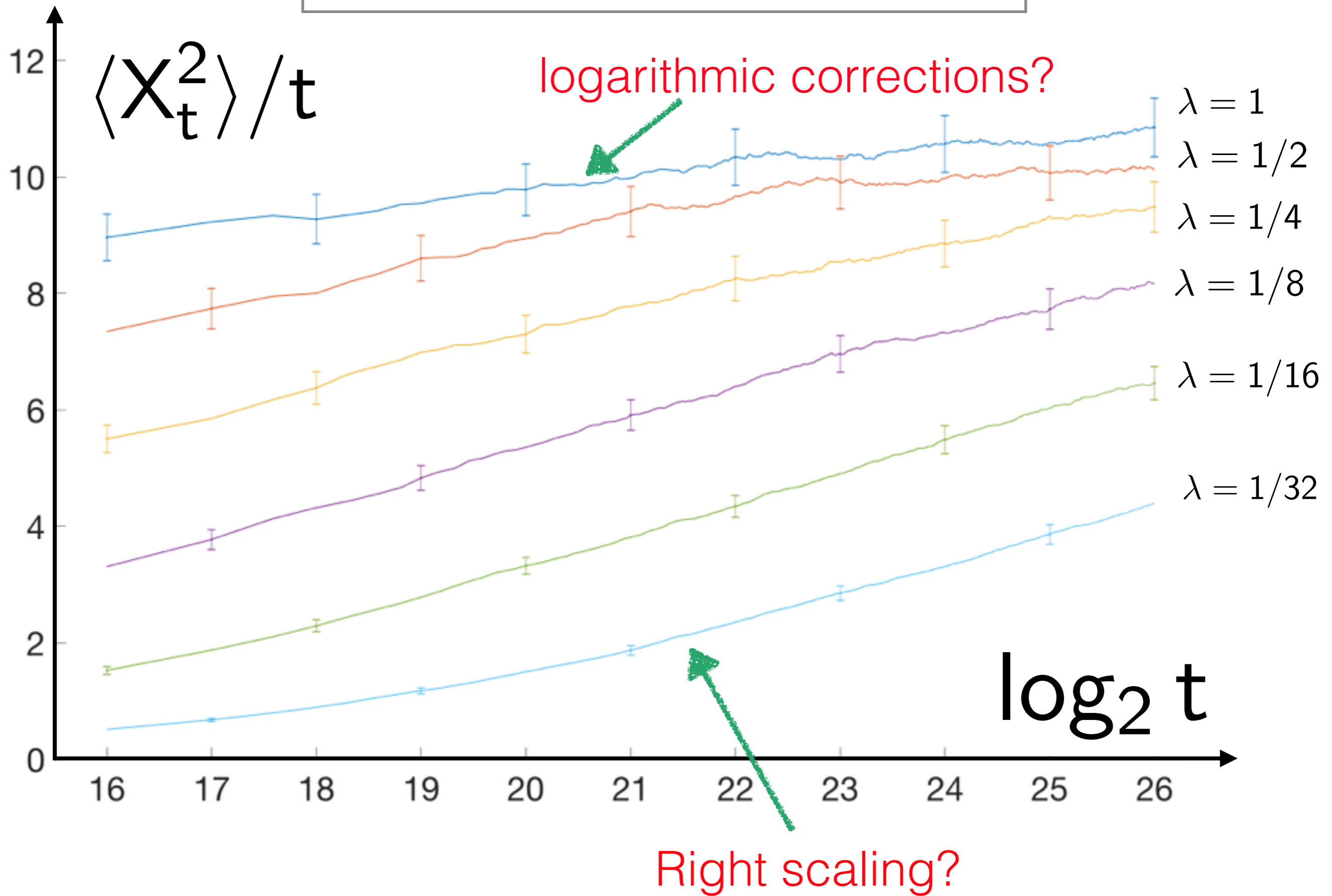
Exponent α : $V(v) \sim v^\alpha$ as $v \rightarrow 0$



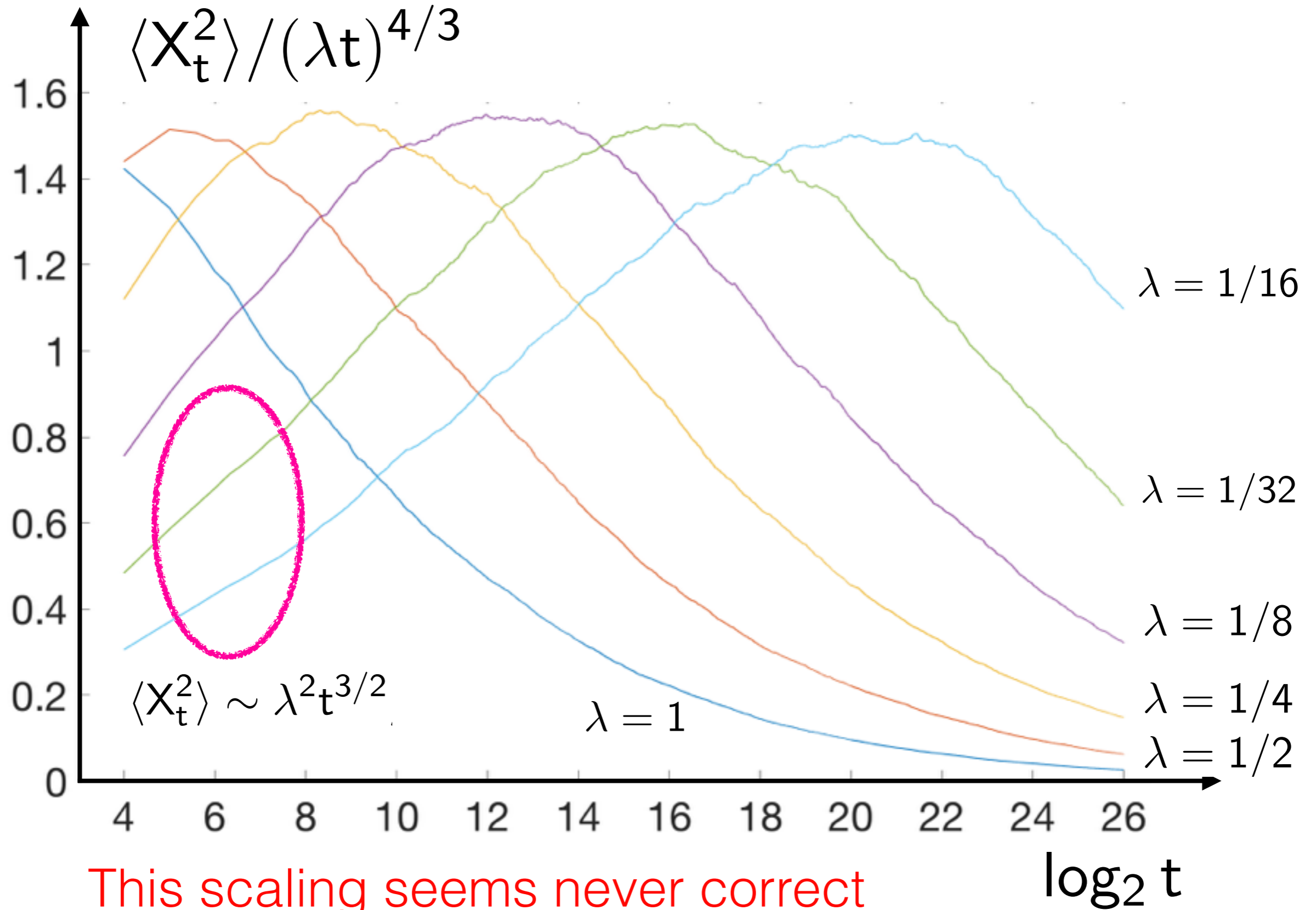
Corresponding slopes



Fluctuations at $v = 0$



Scaling from the self-consistent approximation



Tentative theory

Try to explain:

- 1) Why is the walker eventually always trapped?
- 2) Why are some small corrections (log like) wrt the naive explanation plausible?

Proposal:

- 1) Express a relation between the two exponent α (drift) and β (fluctuations)
- 2) Observe that the walker is always trapped by the static modes as in Sinai random walk.
This leads to logarithmic corrections.

“The walker wants to be super-diffusive but does not succeed”, F. Völlering

Relating α and β

1) Assume $V(v) \sim v^\alpha$ ($\alpha \rightarrow 0$) for some $1 \leq \alpha \leq 2$

SCA Strong trapping

2) Let $v = 0$ and replace

$$-\partial_x F = \int_{\mathbb{R}} dk (A_k(t) e^{ikx} + cc)$$



$$\Psi = \int_{\mathbb{R}} dk |k|^{(\alpha-1)/2} (A_k(t) e^{ikx} + cc)$$

Effect: $\int_{|k| \leq v^2} dk (\dots) \sim v \longrightarrow \int_{|k| \leq v^2} dk (\dots) \sim v^\alpha$

Relating α and β

3) Compute β through the self-consistent approximation for Ψ instead of $-\partial_x F$

This yields

$$V(v) \sim v^\alpha \quad \Rightarrow \quad \langle X_t^2 \rangle \sim t^{\frac{4}{2+\alpha}}, \quad 1 \leq \alpha < 2$$

$$\langle X_t^2 \rangle \sim t (\log t)^{1/2}, \quad \alpha = 2$$

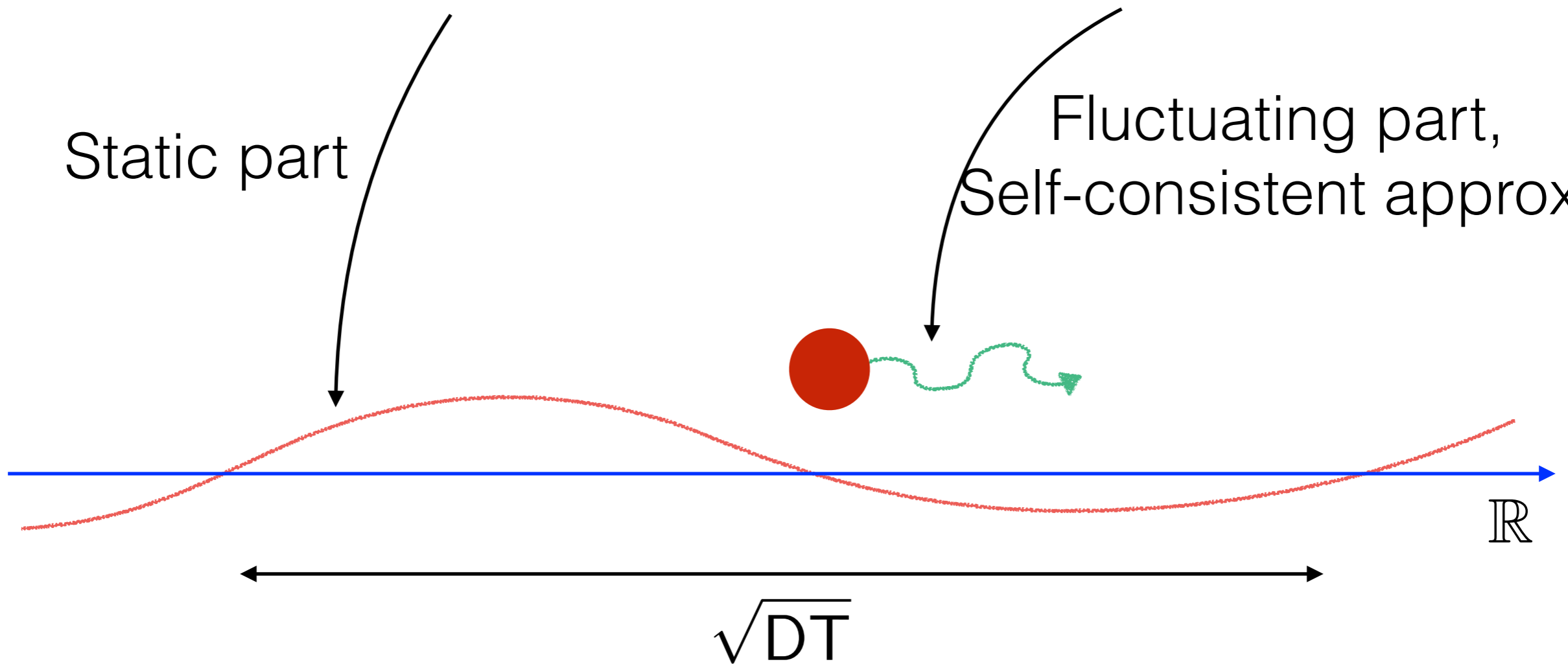
Determining α and β

Fix α tentatively. Let T be some large time. Split

$$\psi = \int_{|k| \leq (DT)^{1/2}} dk(\dots) + \int_{|k| > (DT)^{1/2}} dk(\dots)$$

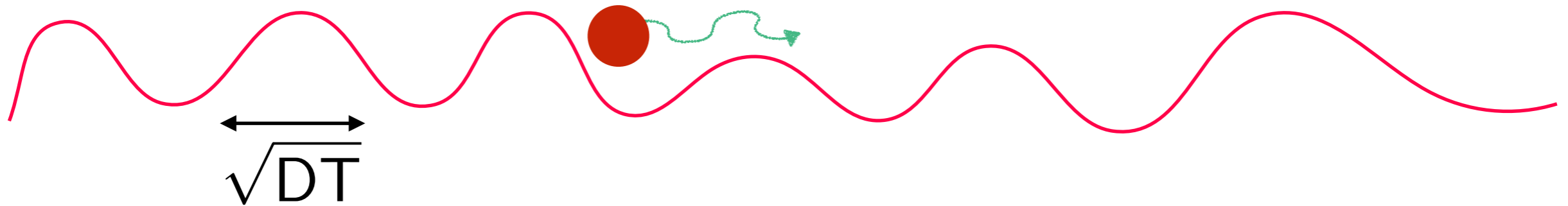
Static part

Fluctuating part,
Self-consistent approx.



Determining α and β

We get thus an effective Sinai random walk:



Computations yields (for **any** $1 \leq \alpha \leq 2$)

$$\langle X_T^2 \rangle \sim DT (\log T)^4$$

- Hence:
- $\beta = 1$
 - $\alpha = 2$
 - possible logarithmic corrections

Conclusions

Approach: response of a random walk to a small external perturbation

- 1) The time to reach the NESS diverges
- 2) No linear response. The system is far from equilibrium
- 3) Trustable way to detect trapping effects:
response to a drift and fluctuations
- 4) Tentative non-linear response theory