Generalized linear models

Generalized linear models



Generalized linear models

- Metropolis–Hastings algorithms

-Generalized linear models

-Generalisation of linear models

Generalisation of Linear Models

Linear models model connection between a response variable y and a set x of explanatory variables by a linear dependence relation with [approximately] normal perturbations.

Many instances where either of these assumptions not appropriate, e.g. when the support of y restricted to \mathbb{R}_+ or to \mathbb{N} .

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bank

Four measurements on 100 genuine Swiss banknotes and 100 counterfeit ones:

 x_1 length of the bill (in mm),

 x_2 width of the left edge (in mm),

 x_3 width of the right edge (in mm),

 x_4 bottom margin width (in mm).

Response variable y: status of the banknote [0 for genuine and 1 for counterfeit]

Probabilistic model that predicts counterfeiting based on the four measurements

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The impossible linear model

Example of the influence of x_4 on ySince y is binary,

 $y|x_4 \sim \mathscr{B}(p(x_4)),$

© Normal model is impossible

Linear dependence in $p(\boldsymbol{x}) = \mathbb{E}[\boldsymbol{y}|\boldsymbol{x}]$'s

$$p(x_{4i}) = \beta_0 + \beta_1 x_{4i} \,$$

estimated [by MLE] as

$$\hat{p}_i = -2.02 + 0.268 \, x_{i4}$$

which gives $\hat{p}_i = .12$ for $x_{i4} = 8$ and ... $\hat{p}_i = 1.19$ for $x_{i4} = 12!!!$ © Linear dependence is impossible

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Generalisation of the linear dependence

Broader class of models to cover various dependence structures.

Class of generalised linear models (GLM) where

 $y|\mathbf{x}, \beta \sim f(y|\mathbf{x}^{\mathrm{T}}\beta)$.

i.e., dependence of y on \mathbf{x} partly *linear*

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Notations

Same as in linear regression chapter, with n-sample

$$\mathbf{y}=(y_1,\ldots,y_n)$$

and corresponding explanatory variables/covariates

$$X = \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1k} \\ x_{21} & x_{22} & \dots & x_{2k} \\ x_{31} & x_{32} & \dots & x_{3k} \\ \vdots & \vdots & \vdots & \vdots \\ x_{n1} & x_{n2} & \dots & x_{nk} \end{bmatrix}$$

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Specifications of GLM's

Definition (GLM)

A GLM is a conditional model specified by two functions:

- (2) the density f of y given \mathbf{x} parameterised by its expectation parameter $\mu = \mu(\mathbf{x})$ [and possibly its dispersion parameter $\varphi = \varphi(\mathbf{x})$]
- ② the link g between the mean μ and the explanatory variables, written customarily as $g(\mu) = \mathbf{x}^{\mathrm{T}}\beta$ or, equivalently, $\mathbb{E}[y|\mathbf{x},\beta] = g^{-1}(\mathbf{x}^{\mathrm{T}}\beta).$

For identifiability reasons, g needs to be bijective.

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Likelihood

Obvious representation of the likelihood

$$\ell(\beta,\varphi|\mathbf{y},X) = \prod_{i=1}^{n} f\left(y_i|\mathbf{x}^{i\mathrm{T}}\beta,\varphi\right)$$

with parameters $\beta \in \mathbb{R}^k$ and $\varphi > 0$.

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Examples

• Ordinary linear regression Case of GLM where

$$g(x) = x, \ \varphi = \sigma^2, \quad \text{and} \quad \mathbf{y}|X, \beta, \sigma^2 \sim \mathscr{N}_n(X\beta, \sigma^2).$$

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Examples (2)

Case of binary and binomial data, when

 $y_i | \mathbf{x}^i \sim \mathscr{B}(n_i, p(\mathbf{x}^i))$

with known n_i

• Logit [or logistic regression] model Link is *logit transform* on probability of success

$$g(p_i) = \log(p_i/(1-p_i)),$$

with likelihood

$$\prod_{i=1}^{n} \binom{n_i}{y_i} \left(\frac{\exp(\mathbf{x}^{i\mathrm{T}}\beta)}{1 + \exp(\mathbf{x}^{i\mathrm{T}}\beta)} \right)^{y_i} \left(\frac{1}{1 + \exp(\mathbf{x}^{i\mathrm{T}}\beta)} \right)^{n_i - y_i} \\ \propto \exp\left\{ \sum_{i=1}^{n} y_i \mathbf{x}^{i\mathrm{T}}\beta \right\} / \prod_{i=1}^{n} \left(1 + \exp(\mathbf{x}^{i\mathrm{T}}\beta) \right)^{n_i - y_i}$$

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Canonical link

Special link function g that appears in the natural exponential family representation of the density

$$g^{\star}(\mu) = \theta$$
 if $f(y|\mu) \propto \exp\{T(y) \cdot \theta - \Psi(\theta)\}$

Example

Logit link is canonical for the binomial model, since

$$f(y_i|p_i) = \binom{n_i}{y_i} \exp\left\{y_i \log\left(\frac{p_i}{1-p_i}\right) + n_i \log(1-p_i)\right\},\,$$

and thus

$$\theta_i = \log p_i / (1 - p_i)$$

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Examples (3)

Customary to use the canonical link, but only customary ...

• Probit model

Probit link function given by

$$g(\mu_i) = \Phi^{-1}(\mu_i)$$

where Φ standard normal cdf Likelihood

$$\ell(\beta|\mathbf{y}, X) \propto \prod_{i=1}^{n} \Phi(\mathbf{x}^{i\mathrm{T}}\beta)^{y_i} (1 - \Phi(\mathbf{x}^{i\mathrm{T}}\beta))^{n_i - y_i}.$$

Full processing

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Log-linear models

Standard approach to describe associations between several *categorical* variables, i.e, variables with finite support Sufficient statistic: *contingency table*, made of the cross-classified counts for the different categorical variables. • Full entry to loginear models

Example (Titanic survivor)

		Child		Adult	
Survivor	Class	Male	Female	Male	Female
	1st	0	0	118	4
	2nd	0	0	154	13
No	3rd	35	17	387	89
	Crew	0	0	670	3
	1st	5	1	57	140
	2nd	11	13	14	80
Yes	3rd	13	14	75	76
	Crew	0	0	192	20

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Poisson regression model

- **1** Each count y_i is Poisson with mean $\mu_i = \mu(\mathbf{x}_i)$
- 2 Link function connecting \mathbb{R}^+ with \mathbb{R} , e.g. logarithm $g(\mu_i) = \log(\mu_i)$.

Corresponding likelihood

$$\ell(\beta|y,X) = \prod_{i=1}^{n} \left(\frac{1}{y_i!}\right) \exp\left\{y_i \mathbf{x}^{i\mathrm{T}}\beta - \exp(\mathbf{x}^{i\mathrm{T}}\beta)\right\} \,.$$

Generalized linear models

Metropolis–Hastings algorithms

Metropolis-Hastings algorithms

Posterior inference in GLMs harder than for linear models

 \bigcirc Working with a GLM requires specific numerical or simulation tools [E.g., GLIM in classical analyses]

Opportunity to introduce universal MCMC method: *Metropolis–Hastings* algorithm

-Generalized linear models

Metropolis–Hastings algorithms

Generic MCMC sampler

- Metropolis–Hastings algorithms are generic/down-the-shelf MCMC algorithms
- Only require likelihood up to a constant [difference with Gibbs sampler]
- can be tuned with a wide range of possibilities [difference with Gibbs sampler & blocking]
- natural extensions of standard simulation algorithms: based on the choice of a *proposal* distribution [difference in Markov proposal q(x, y) and acceptance]

Generalized linear models

Metropolis–Hastings algorithms

Why Metropolis?

Originally introduced by Metropolis, Rosenbluth, Rosenbluth, Teller and Teller in a setup of optimization on a discrete state-space. All authors involved in Los Alamos during and after WWII:

- Physicist and mathematician, Nicholas Metropolis is considered (with Stanislaw Ulam) to be the father of Monte Carlo methods.
- Also a physicist, Marshall Rosenbluth worked on the development of the hydrogen (H) bomb
- Edward Teller was one of the first scientists to work on the Manhattan Project that led to the production of the A bomb. Also managed to design with Ulam the H bomb.

Generalized linear models

Metropolis-Hastings algorithms

Generic Metropolis-Hastings sampler

For target π and proposal kernel q(x, y)

Initialization: Choose an arbitrary $x^{(0)}$

Iteration *t*:

- 1) Given $x^{(t-1)}$, generate $\tilde{x} \sim q(x^{(t-1)}, x)$
- ② Calculate

$$\rho(x^{(t-1)}, \tilde{x}) = \min\left(\frac{\pi(\tilde{x})/q(x^{(t-1)}, \tilde{x})}{\pi(x^{(t-1)})/q(\tilde{x}, x^{(t-1)})}, 1\right)$$

3 With probability $\rho(x^{(t-1)}, \tilde{x})$ accept \tilde{x} and set $x^{(t)} = \tilde{x}$; otherwise reject \tilde{x} and set $x^{(t)} = x^{(t-1)}$.

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Metropolis–Hastings algorithms

Universality

Algorithm only needs to simulate from

q

which can be chosen [almost!] arbitrarily, i.e. unrelated with π [q also called *instrumental* distribution]

Note: π and q known up to proportionality terms ok since proportionality constants cancel in ρ .

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Metropolis–Hastings algorithms

Validation

Markov chain theory

Target π is stationary distribution of Markov chain $(x^{(t)})_t$ because probability $\rho(x, y)$ satisfies *detailed balance equation*

$$\pi(x)q(x,y)\rho(x,y) = \pi(y)q(y,x)\rho(y,x)$$

[Integrate out x to see that π is stationary]

For convergence/ergodicity, Markov chain must be *irreducible*: q has positive probability of reaching all areas with positive π probability in a finite number of steps.

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Metropolis–Hastings algorithms

Choice of proposal

Theoretical guarantees of convergence very high, but choice of q is crucial in practice. Poor choice of q may result in

- ${\hfill}$ very high rejection rates, with very few moves of the Markov chain $(x^{(t)})_t$ hardly moves, or in
- a myopic exploration of the support of π, that is, in a dependence on the starting value x⁽⁰⁾, with the chain stuck in a neighbourhood mode to x⁽⁰⁾.

Note: hybrid MCMC

Simultaneous use of different kernels valid and recommended

Generalized linear models

Metropolis–Hastings algorithms

The independence sampler

Pick proposal q that is independent of its first argument,

$$q(x,y) = q(y)$$

 ρ simplifies into

$$\rho(x,y) = \min\left(1, \frac{\pi(y)/q(y)}{\pi(x)/q(x)}\right) \,.$$

Special case: $q \propto \pi$

Reduces to $\rho(x,y)=1$ and iid sampling

Analogy with Accept-Reject algorithm where $\max \pi/q$ replaced with the current value $\pi(x^{(t-1)})/q(x^{(t-1)})$ but sequence of accepted $x^{(t)}$'s not i.i.d.

Generalized linear models

Metropolis–Hastings algorithms

Choice of q

Convergence properties highly dependent on q.

- ${\, \bullet \, } q$ needs to be positive everywhere on the support of π
- for a good exploration of this support, π/q needs to be bounded.

Otherwise, the chain takes too long to reach regions with low q/π values.

Generalized linear models

Metropolis-Hastings algorithms

The random walk sampler

Independence sampler requires too much global information about π : opt for a local gathering of information

Means exploration of the neighbourhood of the current value $x^{(t)}$ in search of other points of interest.

Simplest exploration device is based on random walk dynamics.

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Metropolis-Hastings algorithms

Random walks

Proposal is a symmetric transition density

$$q(x, y) = q_{RW}(y - x) = q_{RW}(x - y)$$

Acceptance probability $\rho(x,y)$ reduces to the simpler form

$$\rho(x,y) = \min\left(1, \frac{\pi(y)}{\pi(x)}\right).$$

Only depends on the target π [accepts all proposed values that increase π]

Generalized linear models

Metropolis–Hastings algorithms

Choice of q_{RW}

Considerable flexibility in the choice of q_{RW} ,

- ${\ensuremath{\, \circ }}$ tails: Normal versus Student's t
- scale: size of the neighbourhood

Can also be used for restricted support targets [with a waste of simulations near the boundary]

Can be tuned towards an acceptance probability of 0.234 at the *burnin* stage [Magic number!]

Generalized linear models

Metropolis–Hastings algorithms

Convergence assessment

Capital question: How many iterations do we need to run???

- **Rule # 1** There is no absolute number of simulations, i.e. 1,000 is neither large, nor small.
- Rule # 2 It takes [much] longer to check for convergence than for the chain itself to converge.
- Rule # 3 MCMC is a "what-you-get-is-what-you-see" algorithm: it fails to tell about unexplored parts of the space.
- **Rule # 4** When in doubt, run MCMC chains in parallel and check for consistency.

Many "quick-&-dirty" solutions in the literature, but not necessarily trustworthy.

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Metropolis–Hastings algorithms

Prohibited dynamic updating

Tuning the proposal in terms of its past performances can
 only be implemented at *burnin*, because otherwise this cancels
 Markovian convergence properties.

Use of several MCMC proposals together within a single algorithm using circular or random design is ok. It almost always brings an improvement compared with its individual components (at the cost of increased simulation time)

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Metropolis–Hastings algorithms

Effective sample size

How many iid simulations from π are equivalent to N simulations from the MCMC algorithm?

Based on estimated k-th order auto-correlation,

$$\rho_k = \operatorname{cov}\left(x^{(t)}, x^{(t+k)}\right) \,,$$

effective sample size

$$N^{\rm ess} = n \, \left(1 + 2 \, \sum_{k=1}^{T_0} \hat{\rho}_k \right)^{-1/2} \, , \label{eq:Ness}$$

Only partial indicator that fails to signal chains stuck in one mode of the target

Generalized linear models

└─ The Probit Model

The Probit Model

Likelihood

Recall Probit

$$\ell(\beta|\mathbf{y}, X) \propto \prod_{i=1}^{n} \Phi(\mathbf{x}^{i\mathrm{T}}\beta)^{y_i} (1 - \Phi(\mathbf{x}^{i\mathrm{T}}\beta))^{n_i - y_i}$$

If no prior information available, resort to the flat prior $\pi(\beta)\propto 1$ and then obtain the posterior distribution

$$\pi(\beta|\mathbf{y},X) \propto \prod_{i=1}^{n} \Phi\left(\mathbf{x}^{i\mathrm{T}}\beta\right)^{y_{i}} \left(1 - \Phi(\mathbf{x}^{i\mathrm{T}}\beta)\right)^{n_{i}-y_{i}},$$

nonstandard and simulated using MCMC techniques.

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-Generalized linear models

└─ The Probit Model

MCMC resolution

Metropolis-Hastings random walk sampler works well for binary regression problems with small number of predictors

Uses the maximum likelihood estimate $\hat{\beta}$ as starting value and asymptotic (Fisher) covariance matrix of the MLE, $\hat{\Sigma}$, as scale

Generalized linear models

└─ The Probit Model

MLE proposal

R function glm very useful to get the maximum likelihood estimate of β and its asymptotic covariance matrix $\hat{\Sigma}.$

Terminology used in R program

```
mod=summary(glm(y~X-1,family=binomial(link="probit")))
```

with mod\$coeff[,1] denoting $\hat{\beta}$ and mod\$cov.unscaled $\hat{\Sigma}$.

Generalized linear models

└─ The Probit Model

MCMC algorithm

Probit random-walk Metropolis-Hastings

Initialization: Set $\beta^{(0)} = \hat{\beta}$ and compute $\hat{\Sigma}$ **Iteration** *t*:

1 Generate $\tilde{\beta} \sim \mathcal{N}_{k+1}(\beta^{(t-1)}, \tau \hat{\Sigma})$

② Compute

$$\rho(\beta^{(t-1)}, \tilde{\beta}) = \min\left(1, \frac{\pi(\tilde{\beta}|y)}{\pi(\beta^{(t-1)}|y)}\right)$$

3

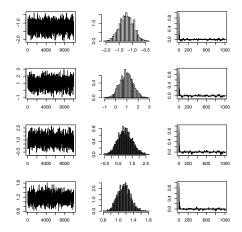
3 With probability $\rho(\beta^{(t-1)}, \tilde{\beta})$ set $\beta^{(t)} = \tilde{\beta}$; otherwise set $\beta^{(t)} = \beta^{(t-1)}$.

Generalized linear models

└─ The Probit Model

bank

Probit modelling with no intercept over the four measurements. Three different scales $\tau = 1, 0.1, 10$: best mixing behavior is associated with $\tau = 1$. Average of the parameters over 9,000iterations gives plug-in estimate



 $\hat{p}_i = \Phi \left(-1.2193x_{i1} + 0.9540x_{i2} + 0.9795x_{i3} + 1.1481x_{i4} \right).$

Generalized linear models

L The Probit Model

G-priors for probit models

Flat prior on β inappropriate for comparison purposes and Bayes factors.

Replace the flat prior with a hierarchical prior,

$$\beta | \sigma^2, X \sim \mathscr{N}_k \left(0_k, \sigma^2 (X^{\mathrm{T}} X)^{-1} \right) \quad \text{and} \quad \pi(\sigma^2 | X) \propto \sigma^{-3/2} \,,$$

as in normal linear regression

Note

The matrix $X^{T}X$ is *not* the Fisher information matrix

Generalized linear models

L The Probit Model

G-priors for testing

Same argument as before: while π is improper, use of the same variance factor σ^2 in both models means the normalising constant cancels in the Bayes factor.

Posterior distribution of β

$$\pi(\beta|\mathbf{y},X) \propto |X^{\mathrm{T}}X|^{1/2} \Gamma((2k-1)/4) \left(\beta^{\mathrm{T}}(X^{\mathrm{T}}X)\beta\right)^{-(2k-1)/4} \pi^{-k/2}$$
$$\times \prod_{i=1}^{n} \Phi(\mathbf{x}^{i\mathrm{T}}\beta)^{y_{i}} \left[1 - \Phi(\mathbf{x}^{i\mathrm{T}}\beta)\right]^{1-y_{i}}$$

[where k matters!]

Generalized linear models

└─ The Probit Model

Marginal approximation Marginal

$$f(\mathbf{y}|X) \propto |X^{\mathrm{T}}X|^{1/2} \pi^{-k/2} \Gamma\{(2k-1)/4\} \int \left(\beta^{\mathrm{T}}(X^{\mathrm{T}}X)\beta\right)^{-(2k-1)/4} \\ \times \prod_{i=1}^{n} \Phi(\mathbf{x}^{i\mathrm{T}}\beta)^{y_{i}} \left[1 - (\Phi(\mathbf{x}^{i\mathrm{T}}\beta)\right]^{1-y_{i}} d\beta,$$

approximated by

$$\frac{|X^{\mathrm{T}}X|^{1/2}}{\pi^{k/2}M} \sum_{m=1}^{M} \left| \left| X\beta^{(m)} \right| \right|^{-(2k-1)/2} \prod_{i=1}^{n} \Phi(\mathbf{x}^{i\mathrm{T}}\beta^{(m)})^{y_{i}} \left[1 - \Phi(\mathbf{x}^{i\mathrm{T}}\beta^{(m)}) \right]^{1-y_{i}} \times \Gamma\{(2k-1)/4\} \left| \widehat{V} \right|^{1/2} (4\pi)^{k/2} e^{(\beta^{(m)} - \widehat{\beta})^{\mathrm{T}} \widehat{V}^{-1}(\beta^{(m)} - \widehat{\beta})/4},$$

where

$$\beta^{(m)} \sim \mathcal{N}_k(\widehat{\beta}, 2\,\widehat{V})$$

with $\widehat{\beta}$ MCMC approximation of $\mathbb{E}^{\pi}[\beta|\mathbf{y}, X]$ and \widehat{V} MCMC approximation of $\mathbb{V}(\beta|\mathbf{y}, X)$.

Generalized linear models

└─ The Probit Model

Linear hypothesis

Linear restriction on β

$$H_0: R\beta = r$$

 $(r \in \mathbb{R}^q, R q \times k \text{ matrix})$ where β^0 is (k-q) dimensional and X_0 and \mathbf{x}_0 are linear transforms of X and of \mathbf{x} of dimensions (n, k-q) and (k-q).

Likelihood

$$\ell(\beta^0|\mathbf{y}, X_0) \propto \prod_{i=1}^n \Phi(\mathbf{x}_0^{iT}\beta^0)^{y_i} \left[1 - \Phi(\mathbf{x}_0^{iT}\beta^0)\right]^{1-y_i},$$

Generalized linear models

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Linear test

Associated [projected] G-prior

$$\beta^0 | \sigma^2, X_0 \sim \mathscr{N}_{k-q} \left(0_{k-q}, \sigma^2 (X_0^\mathrm{T} X_0)^{-1} \right) \quad \text{ and } \quad \pi(\sigma^2 | X_0) \propto \sigma^{-3/2} \,,$$

Marginal distribution of \mathbf{y} of the same type

$$\begin{split} f(\mathbf{y}|X_0) &\propto |X_0^{\mathrm{T}}X_0|^{1/2} \pi^{-(k-q)/2} \Gamma\left\{\frac{(2(k-q)-1)}{4}\right\} \int \left|\left|X\beta^0\right|\right|^{-(2(k-q)-1)/2} \\ &\prod_{i=1}^n \Phi(\mathbf{x}_0^{i\mathrm{T}}\beta^0)^{y_i} \left[1 - (\Phi(\mathbf{x}_0^{i\mathrm{T}}\beta^0)\right]^{1-y_i} \mathrm{d}\beta^0 \,. \end{split}$$

Generalized linear models

L The Probit Model

banknote

For
$$H_0: \beta_1 = \beta_2 = 0$$
, $B_{10}^{\pi} = 157.73$ [against H_0]

Generic regression-like output:

Estimate Post. var. log10(BF)

X1	-1.1552	0.0631	4.5844 (****)
X2	0.9200	0.3299	-0.2875
ХЗ	0.9121	0.2595	-0.0972
X4	1.0820	0.0287	15.6765 (****)

evidence against H0: (****) decisive, (***) strong, (**) subtantial, (*) poor

Generalized linear models

└─ The Probit Model

Informative settings

If prior information available on $p(\mathbf{x})$, transform into prior distribution on β by technique of *imaginary observations*:

Start with k different values of the covariate vector, $\tilde{\mathbf{x}}^1,\ldots,\tilde{\mathbf{x}}^k$ For each of these values, the practitioner specifies

- (i) a prior guess g_i at the probability p_i associated with \mathbf{x}^i ;
- (ii) an assessment of (un)certainty about that guess given by a number K_i of equivalent "prior observations".

On how many imaginary observations did you build this guess?

Generalized linear models

L The Probit Model

Informative prior

$$\pi(p_1,\ldots,p_k) \propto \prod_{i=1}^k p_i^{K_i g_i - 1} (1-p_i)^{K_i (1-g_i) - 1}$$

translates into [Jacobian rule]

$$\pi(\beta) \propto \prod_{i=1}^{k} \Phi(\tilde{\mathbf{x}}^{i\mathrm{T}}\beta)^{K_{i}g_{i}-1} \left[1 - \Phi(\tilde{\mathbf{x}}^{i\mathrm{T}}\beta)\right]^{K_{i}(1-g_{i})-1} \phi(\tilde{\mathbf{x}}^{i\mathrm{T}}\beta)$$

[Almost] equivalent to using the G-prior

$$\beta \sim \mathcal{N}_k \left(\mathbf{0}_k, \left[\sum_{j=1}^k \tilde{\mathbf{x}}^j \tilde{\mathbf{x}}^{j\mathrm{T}} \right]^{-1} \right)$$

Generalized linear models

L The logit model

The logit model

Recall that [for $n_i = 1$]

$$y_i | \mu_i \sim \mathscr{B}(1, \mu_i), \quad \varphi = 1 \quad \text{and} \quad g(\mu_i) = \left(\frac{\exp(\mu_i)}{1 + \exp(\mu_i)} \right).$$

Thus

$$\mathbb{P}(y_i = 1|\beta) = \frac{\exp(\mathbf{x}^{i\mathrm{T}}\beta)}{1 + \exp(\mathbf{x}^{i\mathrm{T}}\beta)}$$

with likelihood

$$\ell(\beta|\mathbf{y}, X) = \prod_{i=1}^{n} \left(\frac{\exp(\mathbf{x}^{i\mathrm{T}}\beta)}{1 + \exp(\mathbf{x}^{i\mathrm{T}}\beta)}\right)^{y_i} \left(1 - \frac{\exp(\mathbf{x}^{i\mathrm{T}}\beta)}{1 + \exp(\mathbf{x}^{i\mathrm{T}}\beta)}\right)^{1-y_i}$$

Generalized linear models

L The logit model

Links with probit

- $\bullet\,$ usual vague prior for $\beta,\,\pi(\beta)\propto 1$
- Posterior given by

$$\pi(\beta|\mathbf{y}, X) \propto \prod_{i=1}^{n} \left(\frac{\exp(\mathbf{x}^{i\mathrm{T}}\beta)}{1 + \exp(\mathbf{x}^{i\mathrm{T}}\beta)}\right)^{y_{i}} \left(1 - \frac{\exp(\mathbf{x}^{i\mathrm{T}}\beta)}{1 + \exp(\mathbf{x}^{i\mathrm{T}}\beta)}\right)^{1-y_{i}}$$

[intractable]

• Same Metropolis–Hastings sampler

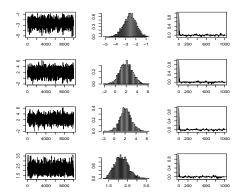
Generalized linear models

└─ The logit model

bank

Same scale factor equal to $\tau = 1$: slight increase in the skewness of the histograms of the β_i 's.

Plug-in estimate of predictive probability of a counterfeit



$$\hat{p}_i = \frac{\exp\left(-2.5888x_{i1} + 1.9967x_{i2} + 2.1260x_{i3} + 2.1879x_{i4}\right)}{1 + \exp\left(-2.5888x_{i1} + 1.9967x_{i2} + 2.1260x_{i3} + 2.1879x_{i4}\right)}$$

Generalized linear models

└─ The logit model

G-priors for logit models

Same story: Flat prior on β inappropriate for Bayes factors, to be replaced with hierarchical prior,

$$\beta | \sigma^2, X \sim \mathscr{N}_k \left(0_k, \sigma^2 (X^{\mathrm{T}} X)^{-1} \right) \quad \text{and} \quad \pi(\sigma^2 | X) \propto \sigma^{-3/2}$$

Example (bank)						
Estimate Post. var. log10(BF)						
X1 -2.3970 0.3286 4.8084 (****) X2 1.6978 1.2220 -0.2453 X3 2.1197 1.0094 -0.1529 X4 2.0230 0.1132 15.9530 (****) evidence against H0: (****) decisive, (***) strong, (**) subtantial, (*) poor						

Generalized linear models

Loglinear models

Loglinear models

Introduction to loglinear models

Example (airquality)

Benchmark in R

> air=data(airquality)

Repeated measurements over 111 consecutive days of ozone u (in parts per billion) and maximum daily temperature v discretized into dichotomous variables

	month	5	6	7	8	9
ozone	temp					
[1,31]	[57,79]	17	4	2	5	18
	(79,97]	0	2	3	3	2
(31,168]	[57,79]	6	1	0	3	1
	(79,97]	1	2	21	12	8

Contingency table with $5 \times 2 \times 2 = 20$ entries

Generalized linear models

Loglinear models

Poisson regression

Observations/counts $\mathbf{y} = (y_1, \dots, y_n)$ are integers, so we can choose

$$y_i \sim \mathscr{P}(\mu_i)$$

Saturated likelihood

$$\ell(\mu|\mathbf{y}) = \prod_{i=1}^{n} \frac{1}{\mu_i!} \mu_i^{y_i} \exp(-\mu_i)$$

GLM constraint via log-linear link

$$\log(\mu_i) = \mathbf{x}^{i\mathrm{T}}\beta, \quad y_i | \mathbf{x}^i \sim \mathscr{P}\left(e^{\mathbf{x}^{i\mathrm{T}}\beta}\right)$$

-Generalized linear models

Loglinear models

Categorical variables

Special feature

Incidence matrix $X = (\mathbf{x}^i)$ such that its elements are all zeros or ones, i.e. covariates are all indicators/dummy variables!

Several types of (sub)models are possible depending on relations between categorical variables.

Re-special feature

Variable selection problem of a specific kind, in the sense that all indicators related with the *same* association must either remain or vanish at once. Thus much fewer submodels than in a regular variable selection problem.

Generalized linear models

Loglinear models

Parameterisations

Example of three variables $1 \le u \le I$, $1 \le v \le j$ and $1 \le w \le K$.

Simplest non-constant model is

$$\log(\mu_{\tau}) = \sum_{b=1}^{I} \beta_b^u \mathbb{I}_b(u_{\tau}) + \sum_{b=1}^{J} \beta_b^v \mathbb{I}_b(v_{\tau}) + \sum_{b=1}^{K} \beta_b^w \mathbb{I}_b(w_{\tau}),$$

that is,

$$\log(\mu_{l(i,j,k)}) = \beta_i^u + \beta_j^v + \beta_k^w \,,$$

where index l(i, j, k) corresponds to u = i, v = j and w = k. Saturated model is

$$\log(\mu_{l(i,j,k)}) = \beta_{ijk}^{uvw}$$

-Generalized linear models

Loglinear models

Log-linear model (over-)parameterisation

Representation

$$\log(\mu_{l(i,j,k)}) = \lambda + \lambda_i^u + \lambda_j^v + \lambda_k^w + \lambda_{ij}^{uv} + \lambda_{ik}^{uw} + \lambda_{jk}^{vw} + \lambda_{ijk}^{uvw} ,$$

as in Anova models.

- $\bullet~\lambda$ appears as the overall or reference average effect
- λ_i^u appears as the marginal discrepancy (against the reference effect λ) when u = i,
- λ_{ij}^{uv} as the interaction discrepancy (against the added effects $\lambda + \lambda_i^u + \lambda_j^v$) when (u, v) = (i, j)

and so on...

Generalized linear models

Loglinear models

Example of submodels

(1) if both v and w are irrelevant, then

$$\log(\mu_{l(i,j,k)}) = \lambda + \lambda_i^u \,,$$

(2) if all three categorical variables are mutually independent, then

$$\log(\mu_{l(i,j,k)}) = \lambda + \lambda_i^u + \lambda_j^v + \lambda_k^w,$$

(3) if u and v are associated but are both independent of w, then

$$\log(\mu_{l(i,j,k)}) = \lambda + \lambda_i^u + \lambda_j^v + \lambda_k^w + \lambda_{ij}^{uv}$$

④ if u and v are conditionally independent given w, then

$$\log(\mu_{l(i,j,k)}) = \lambda + \lambda_i^u + \lambda_j^v + \lambda_k^w + \lambda_{ik}^{uw} + \lambda_{jk}^{vw},$$

if there is no three-factor interaction, then

$$\log(\mu_{l(i,j,k)}) = \lambda + \lambda_i^u + \lambda_j^v + \lambda_k^w + \lambda_{ij}^{uv} + \lambda_{ik}^{uw} + \lambda_{jk}^{vu}$$
[the most complete submodel]

-Generalized linear models

Loglinear models

Identifiability

Representation

 $\log(\mu_{l(i,j,k)}) = \lambda + \lambda_i^u + \lambda_j^v + \lambda_k^w + \lambda_{ij}^{uv} + \lambda_{ik}^{uw} + \lambda_{jk}^{vw} + \lambda_{ijk}^{uvw},$

not identifiable but Bayesian approach handles non-identifiable settings and still estimate properly identifiable quantities. Customary to impose identifiability constraints on the parameters: set to 0 parameters corresponding to the first category of each variable, i.e. remove the indicator of the first category.

E.g., if
$$u \in \{1,2\}$$
 and $v \in \{1,2\}$, constraint could be

$$\lambda_1^u = \lambda_1^v = \lambda_{11}^{uv} = \lambda_{12}^{uv} = \lambda_{21}^{uv} = 0.$$

Generalized linear models

Loglinear models

Inference under a flat prior

Noninformative prior $\pi(\beta) \propto 1$ gives posterior distribution

$$\pi(\beta|\mathbf{y}, X) \propto \prod_{i=1}^{n} \left\{ \exp(\mathbf{x}^{i\mathrm{T}}\beta) \right\}^{y_i} \exp\{-\exp(\mathbf{x}^{i\mathrm{T}}\beta)\}$$
$$= \exp\left\{ \sum_{i=1}^{n} y_i \, \mathbf{x}^{i\mathrm{T}}\beta - \sum_{i=1}^{n} \exp(\mathbf{x}^{i\mathrm{T}}\beta) \right\}$$

Use of same random walk M-H algorithm as in probit and logit cases, starting with MLE evaluation

> mod=summary(glm(y~-1+X,family=poisson()))

Generalized linear models

Loglinear models

airquality

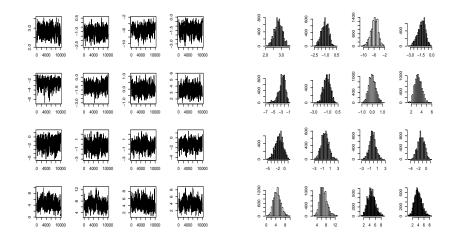
Identifiable non-saturated model involves 16 parameters Obtained with $10,000~{\rm MCMC}$ iterations with scale factor $\tau^2=0.5$

Effect	Post. mean	Post. var.
λ	2.8041	0.0612
λ_2^u	-1.0684	0.2176
λ_2^v	-5.8652	1.7141
λ_2^w	-1.4401	0.2735
λ^w_3	-2.7178	0.7915
λ_4^w	-1.1031	0.2295
λ_5^w	-0.0036	0.1127
λ^{uv}_{22}	3.3559	0.4490
λ_{22}^{uw}	-1.6242	1.2869
λ^{uw}_{23}	- 0.3456	0.8432
λ^{uw}_{24}	-0.2473	0.6658
λ_{25}^{uw}	-1.3335	0.7115
λ_{22}^{vw}	4.5493	2.1997
λ_{23}^{vw}	6.8479	2.5881
λ_{24}^{vw}	4.6557	1.7201
λ_{25}^{vw}	3.9558	1.7128

Generalized linear models

Loglinear models

airquality: MCMC output



Generalized linear models

Loglinear models

Model choice with G-prior

G-prior alternative used for probit and logit models still available:

$$\pi(\beta|\mathbf{y}, X) \propto |X^{\mathrm{T}}X|^{1/2} \Gamma\left\{\frac{(2k-1)}{4}\right\} ||X\beta||^{-(2k-1)/2} \pi^{-k/2}$$
$$\times \exp\left\{\left(\sum_{i=1}^{n} y_i \,\mathbf{x}^i\right)^{\mathrm{T}} \beta - \sum_{i=1}^{n} \exp(\mathbf{x}^{i\mathrm{T}}\beta)\right\}$$

Same MCMC implementation and similar estimates for airquality

Generalized linear models

Loglinear models

airquality

Bayes factors once more approximated by importance sampling based on normal importance functions

```
Anova-like output
```

```
Effect log10(BF)
```

```
u:v 6.0983 (****)
```

```
u:w -0.5732
```

```
v:w 6.0802 (****)
```

```
evidence against H0: (****) decisive, (***) strong,
(**) subtantial, (*) poor
```