

# Variational and viscosity solutions of the Hamilton-Jacobi equation

Patrick Bernard

June 19, 2014

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$$\partial_t u(t, q) + H(q, \partial_q u(t, q)) = 0 \quad (\text{HJ})$$

unknown :  $u(t, q) : \mathbb{R} \times \mathbb{R}^d \longrightarrow \mathbb{R}$

initial condition  $u(0, q) = u_0(q)$ .

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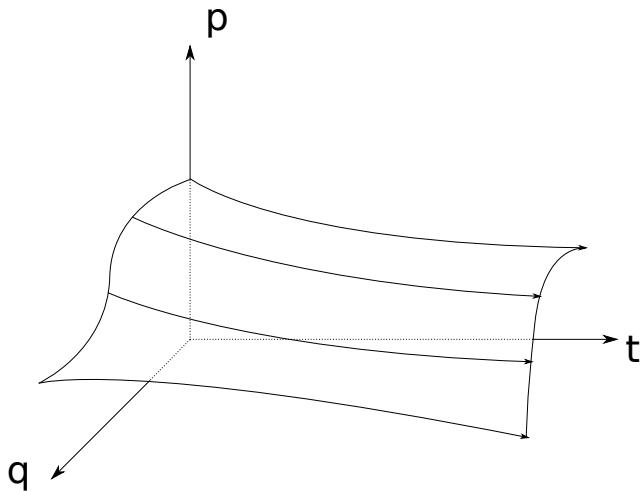
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Hamiltonian action of the curve  $(Q(t), P(t))$ :

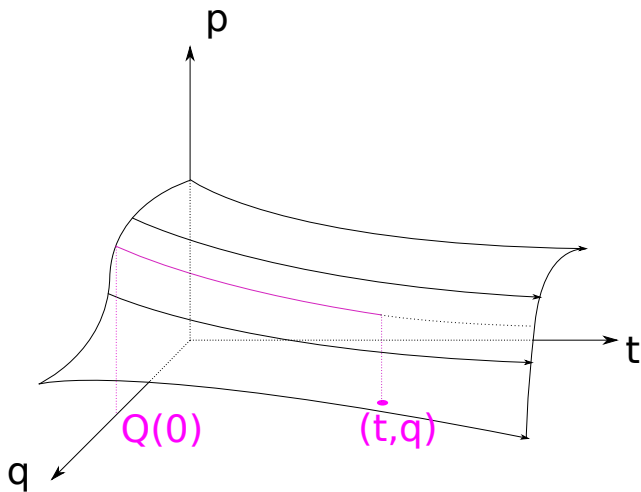
$$\mathcal{A}_0^t(Q, P) := \int_0^t P(s) \cdot \dot{Q}(s) - H(s, Q(s), P(s)) ds$$

# Geometry of the Equations



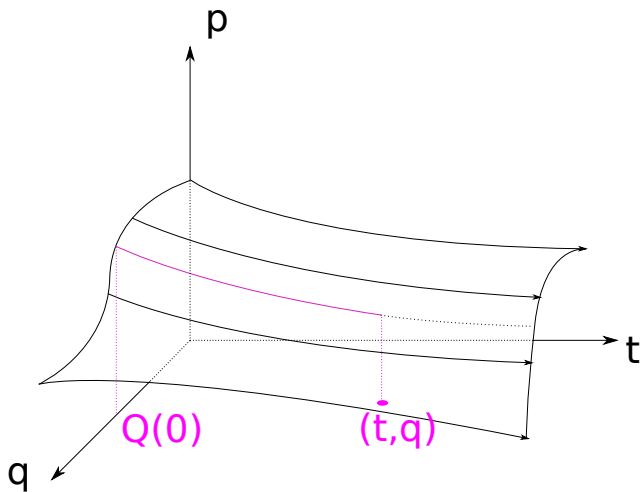
graph of  $\partial_q u(t, q)$ .

# Geometry of the Equations



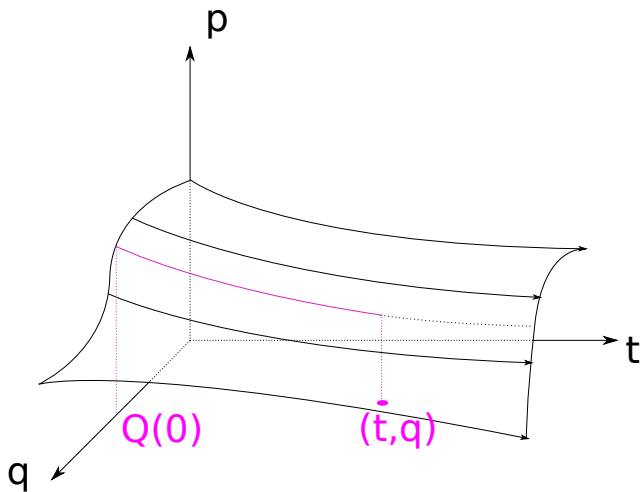
$$u(t, q) = u(0, Q(0)) + \mathcal{A}_0^t(Q, P)$$

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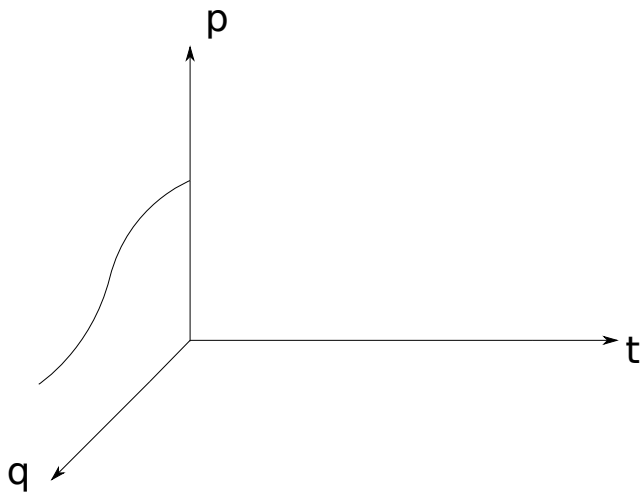
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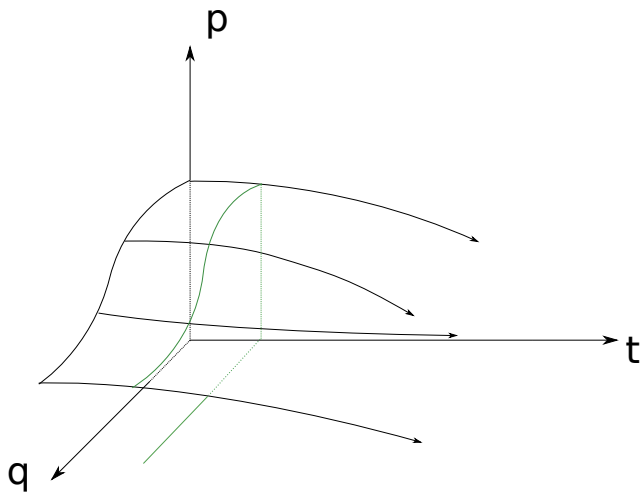


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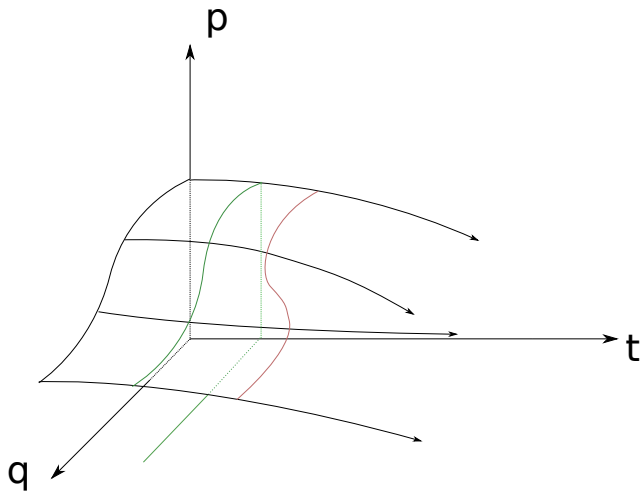


graph of  $q \mapsto \partial_q u_0(q)$



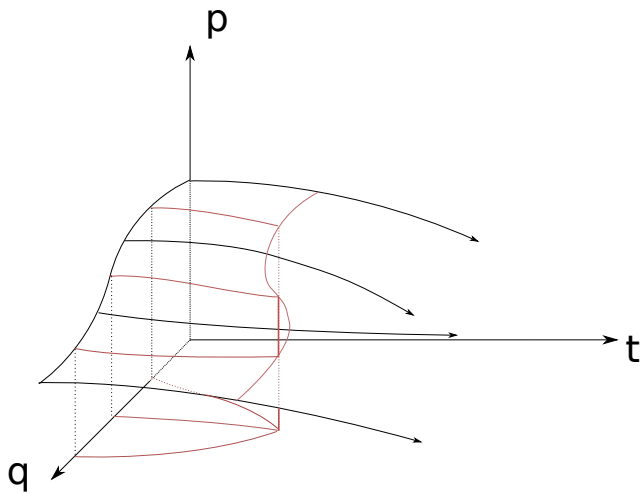
$$u(t, q) = u(0, Q(0)) + \mathcal{A}_0^t(Q, P)$$

# No smooth solution



no smooth solution

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shock!

We assume the existence of  $A > 0$  such that

$$|H(q, p)| \leq A(1+|p|^2), \quad |dH(q, p)| \leq A(1+|p|), \quad |d^2H(q, p)| \leq A.$$

## Theorem

*If  $f_0$  is  $C^2$  and  $|d^2f_0| \leq K$ , then there exists  $T > 0$ , which depends only on  $A$  and  $K$ , such that (HJ) has a  $C^2$  solution  $f$  on  $[0, T] \times \mathbb{R}^d$  with initial condition  $f_0$ .*

## Definition (Variational solution)

A variational solution of (HJ) (with smooth initial condition  $u_0$ ) is a function  $g(t, q)$  such that, for each  $(t, q)$ , the real  $g(t, q)$  is a critical value of the functional

$$(Q, P) \mapsto u_0(Q(0)) + \mathcal{A}_0^t(Q, P)$$

on the space of curves such that  $Q(t) = q$ . In other words, for each  $(t, q)$ , there exists an orbit  $(Q, P)$  of the Hamiltonian system such that

$$Q(t) = q \quad , \quad P(0) = du_0(Q(0))$$

$$g(t, q) = u_0(Q(0)) + \mathcal{A}_0^t(Q, P)$$

## Theorem (Chaperon, Viterbo)

*If  $u_0$  is a  $C^2$  initial condition, then there exists a Lipschitz variational solution  $g(t, x) : [0, \infty) \times \mathbb{R}^d \rightarrow \mathbb{R}^d$  of (HJ). This function is also a solution almost everywhere of the equation.*

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*More precisely, there exists a family  $G^t, t \geq 0$  of maps from  $C^2(\mathbb{R}^d)$  to  $\text{Lip}(\mathbb{R}^d)$  such that the function  $(t, q) \mapsto G^t u(q)$  is a Lipschitz variational solution and such that*

- (1)  $u \leq v \Rightarrow G^t u \leq G^t v$ .
- (2)  $G^t(c + u) = c + G^t u$  for all constant  $c$ .
- (3) If  $u(t, q)$  is a  $C^2$  solution, then  $G^s u_t = u_{t+s}$ .

(1) and (2) imply that  $\|G^t u - G^t v\|_{C^0} \leq \|u - v\|_{C^0}$ .



# Nonsmooth initial condition

The maps  $G^t$  extend to  $C^0(\mathbb{R}^d)$ , and take values in  $C^0(\mathbb{R}^d)$ .

We shall rather consider its restriction

$$G^t : Lip(\mathbb{R}^d) \longrightarrow Lip(\mathbb{R}^d).$$

If  $u_0$  is Lipschitz, then  $g(t, q) := G^t u_0(q)$  is a variational solution in the following sense:

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## Proposition

*For each  $(t, q)$  there exists a trajectory  $(Q, P)$  of (HS) such that*

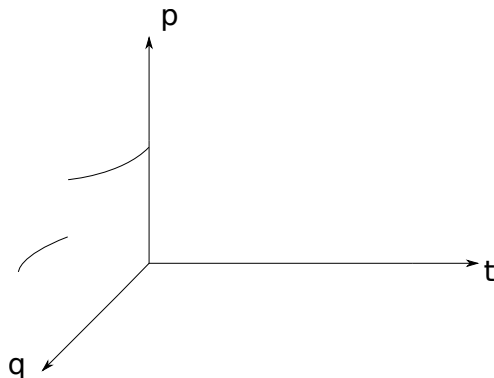
$$Q(t) = q \quad , \quad P(0) \in \partial u_0(Q(0))$$

$$g(t, q) = u_0(Q(0)) + \mathcal{A}_0^t(Q, P)$$

*where  $\partial u_0(Q(0))$  is the Clarke differential of  $u_0$ .*

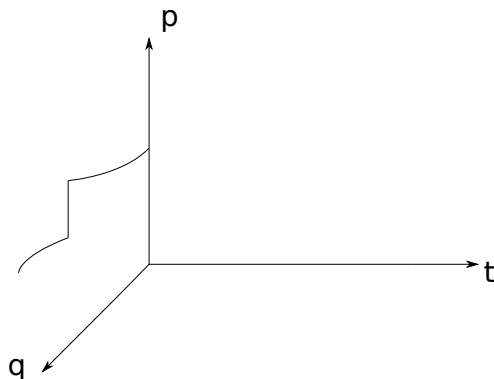
# Clarke differential

The Clarke differential  $\partial u(x)$  of a Lipschitz function on  $\mathbb{R}^d$  at a point  $x$  is the compact subset of  $\mathbb{R}^d$  generated by limits of sequences of the form  $du(q_n)$ ,  $q_n \rightarrow q$ .



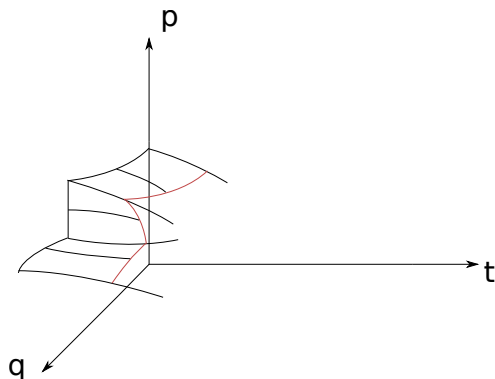
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## Theorem

*There exists a unique family  $V^t, t \geq 0$  of maps of  $Lip(\mathbb{R}^d)$  such that*

- (1)  $u \leq v \Rightarrow V^t u \leq V^t v.$
- (2)  $V^t(c + u) = c + G^t u$  for all constant  $c.$
- (3) If  $u(t, q)$  is a  $C^2$  solution, then  $V^s u_t = u_{t+s}.$
- (4)  $V^{t+s} = V^t \circ V^s$

For each  $u_0$ , the functions  $(t, q) \mapsto V^t u_0(q)$  is the viscosity solution of (HJ).

The following properties are equivalent :

- "The" variational resolution  $G$  satisfies the semi-group property.
- The viscosity solutions are variational.
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These properties are not true for all Hamiltonians. In general:

Theorem (Wei)

$$V^t = \lim_{n \rightarrow \infty} (G^{t/n})^n$$

# The convex case

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In this case, there is an underlying optimisation problem and the Lax-Oleinik formula holds:

$$V^t u_0(q) = G^t u_0(q) = \min_Q (u_0(Q(0)) + \mathcal{A}_0^t(Q, P_Q))$$

on curves  $Q$  such that  $Q(t) = q$ . Here

$$P_Q(s) = \operatorname{argmax}(p \cdot \dot{Q}(s) - H(Q(s), p)).$$

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$$P_Q(s) = \operatorname{argmax}(p \cdot \dot{Q}(s) - H(Q(s), p)).$$

In particular,  $G^t u_0(q)$  is the smallest critical value of the functional  $u_0 + \mathcal{A}$ .

# The Hopf formula

## Theorem

If  $H(q, p) = h(p)$ , and  $u_0$  is convex, then

$$G^t u_0(q) = V^t u_0(q) = \sup_p (p \cdot q - u_0^*(p) - th(p))$$

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and, for each  $p$ ,

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In this case,  $G^t u_0(q)$  is the **largest** critical value of  $u_0 + \mathcal{A}$ .

# Generalized Hopf setting

$H(q, p)$  is arbitrary and  $u_0$  is semi-concave.

It means that there exists  $K > 0$  such that  $q \mapsto u_0(q) - K\|q\|^2$  is concave.

## Theorem

There exists  $T > 0$  (which depends only on  $A$  and  $K$ ) such that, for  $t \in [0, T]$ ,

**1**  $G^t u_0(q)$  is the smallest critical value of the functional

$$(Q, P) \mapsto u_0(Q(0)) + \mathcal{A}_0^t(Q, P)$$

with endpoint  $Q(t) = q$ .

**2**  $V^t u_0 \leq G^t u_0$



A function is semi-concave if and only if it can be written as a minimum of  $C^2$  functions.

More precisely, there exists a family  $\mathcal{F}_0 \subset C^2$  such that

$$u_0 = \min_{f_0 \in \mathcal{F}_0} f_0$$

and  $\|d^2 f_0(q)\| \leq K$  for each  $q \in \mathbb{R}^d$ ,  $f_0 \in \mathcal{F}_0$ .

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There exists  $T > 0$  (which depends only on  $A$  and  $K$ ) such that the Cauchy problem for (HJ) with initial condition  $f_0$  has a  $C^2$  solution  $f$  on  $[0, T] \times \mathbb{R}^d$ , for each  $f_0 \in \mathcal{F}_0$ . We call  $\mathcal{F} \in C^2([0, T] \times \mathbb{R}^d, \mathbb{R})$  the set of these solutions.

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We will see that it's not true in general.

For each  $f_0 \in \mathcal{F}_0$ , we have  $f_0 \geq u_0$  hence

$$\begin{aligned} f_t = G^t f_0 \geq G^t u_0 & \quad , \quad f_t = V^t f_0 \geq G^t u_0 \\ \min f \geq g & \quad , \quad \min f \geq v \end{aligned}$$

# The main Lemma

## Lemma

*Assume that the set  $\underline{\mathcal{F}}_0 \subset C^2$  is sufficiently large for the following property to hold:*

*For each  $q \in \mathbb{R}^d$ , and each  $p \in \partial u_0(q)$ , there exists  $f_0 \in \underline{\mathcal{F}}_0$  such that*

$$f_0(q) = u_0(q) \quad , \quad df_0(q) = p.$$

*Then for each  $(t, q)$ ,  $t \leq T$ , each critical value of  $u_0 + \mathcal{A}$  under the constraint  $Q(t) = q$  is of the form  $f(t, q)$  for some  $f \in \underline{\mathcal{F}}$ .*

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- $\Rightarrow g \geq \min_{f \in \underline{\mathcal{F}}} f \Rightarrow g = \min_{f \in \underline{\mathcal{F}}} f.$
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- $g = \min_{f \in \underline{\mathcal{F}}} f \geq v.$

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- $g = \min_{f \in \underline{\mathcal{F}}} f \geq v$ .
- Each critical point of  $u_0 + \mathcal{A}$  is larger than  $\min_{f \in \underline{\mathcal{F}}} f = g$ .

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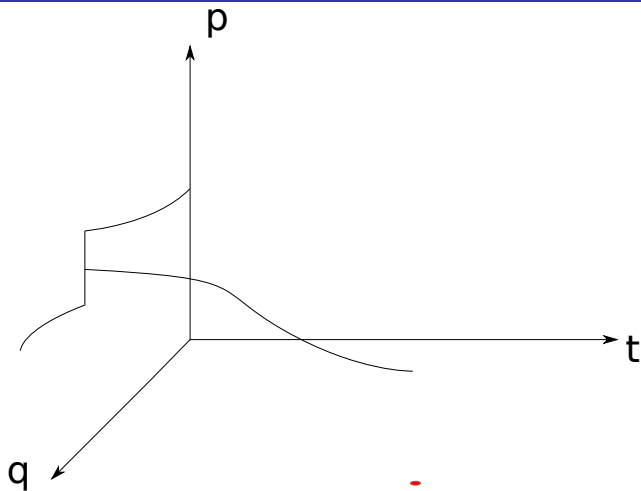
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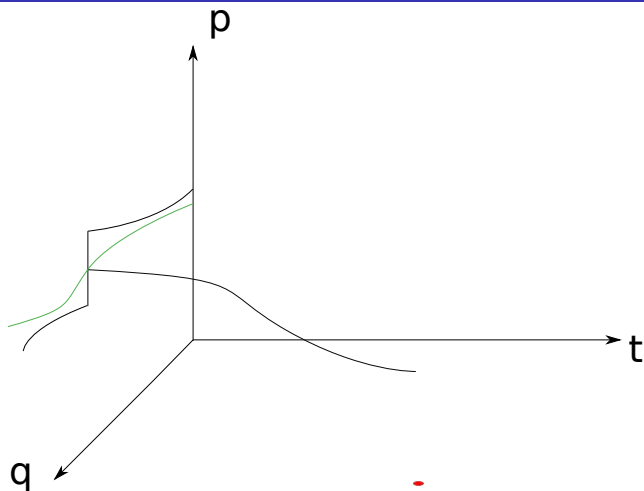
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- Each critical point of  $u_0 + \mathcal{A}$  is larger than  $\min_{f \in \underline{\mathcal{F}}} f = g$ .
- Theorem is proved.

# Proof of the Lemma



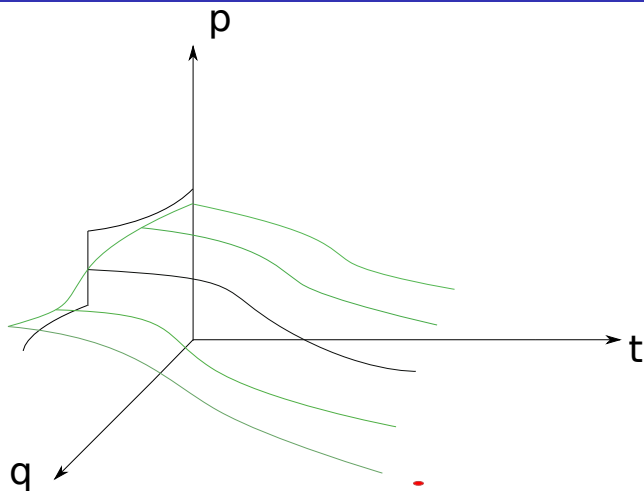
$$(t, q) \quad , \quad C = u_0(Q(0)) + \mathcal{A}_0^t(Q, P)$$

# Proof of the Lemma



$f_0 \in \underline{\mathcal{F}}_0$  such that  $f_0(Q(0)) = u_0(Q(0))$  and  $df_0(Q(0)) = P(0)$ .

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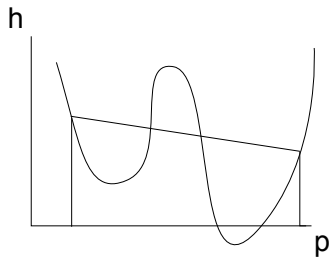


$$\begin{aligned} f(t, q) &= f_0(Q(0)) + \mathcal{A}_0^t(Q, P) \\ &= u_0(Q(0)) + \mathcal{A}_0^t(Q, P) = C \end{aligned}$$

# Example

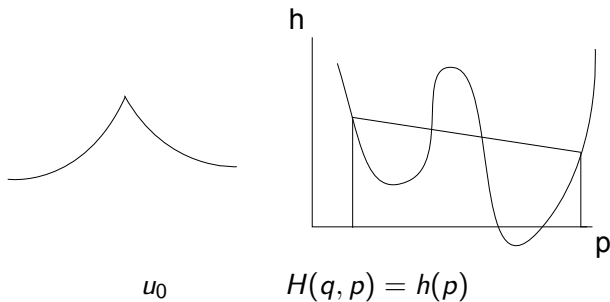


$u_0$



$H(q, p) = h(p)$

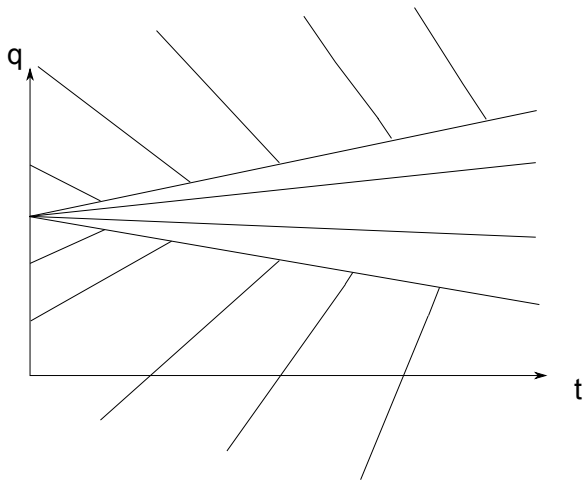
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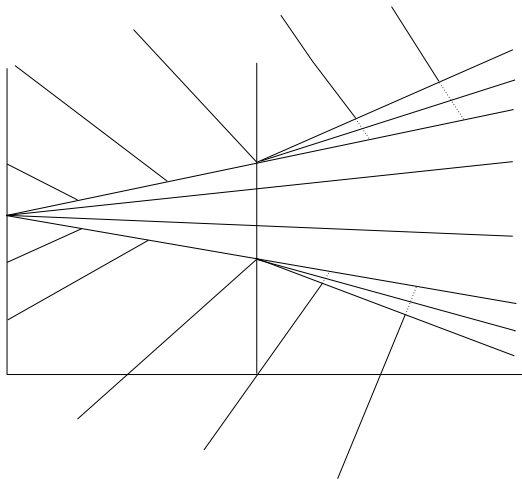
Valentine Roos (extrapolating on Qiaoling Wei) proved that  $v < g$ :



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