

From Ekeland's Hopf-Rinow theorem to optimal incompressible transport theory

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MINIMIZING GEODESICS AND CLOSEST POINTS

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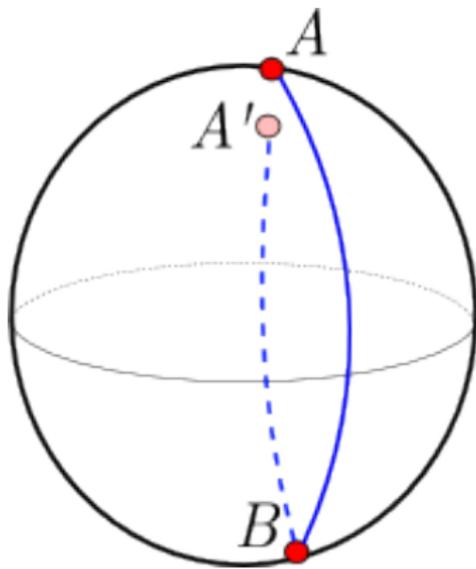
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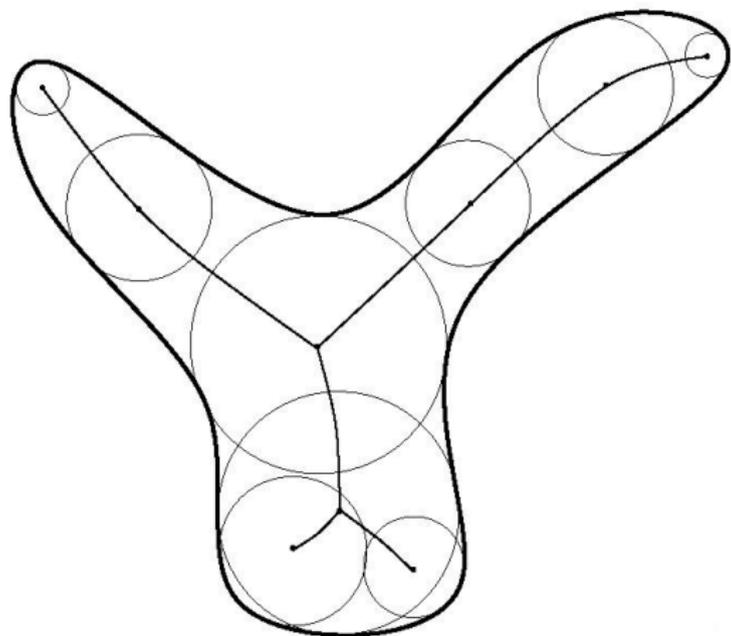
$$\sum_{k=1}^K \|M_k - M_{k-1}\|^2$$

This implies that, for each k , M_k must minimize on S its distance to the mid-point $(M_{k-1} + M_{k+1})/2$.

According to Ekeland's Hopf-Rinow theorem (J. Diff. Geo. 1979), under suitable assumptions, minimizing geodesics (that may not exist) are generically unique.



Edelstein's theorem: in a Hilbert space, generically a point has a unique projection (closest point) on a given closed bounded subset.



AN INFINITE DIMENSIONAL EXAMPLE : THE (SEMI-) GROUP OF VOLUME-PRESERVING MAPS

Consider a bounded domain D in \mathbb{R}^d (this could be generalized to a Riemannian manifold) and the Hilbert space $H = L^2(D, \mathbb{R}^d)$. Let $VPM(D)$ be the semi-group of all volume-preserving maps

$$VPM(D) = \left\{ M \in H, \int_D q(M(x)) dx = \int_D q(x) dx, \forall q \in C(\mathbb{R}^d) \right\}$$

which is a closed subset of the Hilbert space $H = L^2(D, \mathbb{R}^d)$, included in a sphere, not compact nor convex.

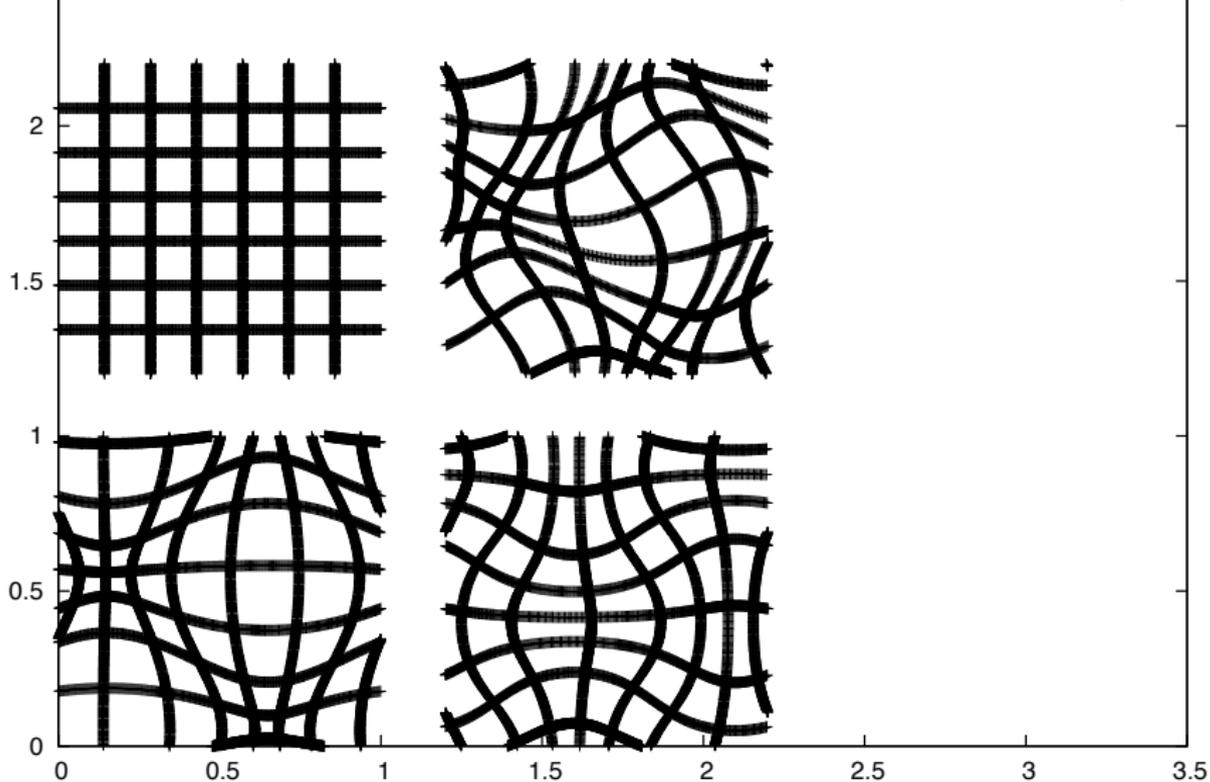
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N.B. This semi-group contains, as a dense subset, the group of orientation and volume preserving diffeomorphisms $SDiff(D)$ of D , provided $d \geq 2$.



Three maps of the (periodized) square: guess which one is volume-preserving!

A discontinuous volume-preserving map

**A discontinuous volume-preserving map
namely the rigid permutation of 16 sub-cells.**



THE CLOSEST POINT PROBLEM

Given a map $T \in H = L^2(D, \mathbb{R}^d)$, a closest point $M \in \text{VPM}(D)$ must solve the saddle point problem

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This is trivially bounded from below by the corresponding sup-inf problem which is equivalent to the concave problem

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$$= \sup_p \int_D (p^c(T(x)) + p(x)) dx, \quad p^c(y) = \inf_{m \in D} \frac{1}{2} |m - z|^2 - p(m)$$

A MONGE-AMPERE-KANTOROVICH SOLUTION

THEOREM Let μ and ν respectively be the Lebesgue measure on D and its image ν by the given map T . Assume ν to be absolutely continuous w.r.t. the Lebesgue measure.

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VLADIMIR ARNOLD

Sur la géométrie différentielle des groupes de Lie de dimension infinie et ses applications à l'hydrodynamique des fluides parfaits

Annales de l'institut Fourier, tome 16, n° 1 (1966), p. 319-361.

http://www.numdam.org/item?id=AIF_1966__16_1_319_0

XXI. Nous n'avons donc qu'à équaler ces forces accélératrices avec les accélérations actuelles que nous venons de trouver, & nous obtiendrons les trois équations suivantes :

$$P - \frac{1}{q} \left(\frac{dp}{dx} \right) = \left(\frac{du}{dt} \right) + u \left(\frac{du}{dx} \right) + v \left(\frac{du}{dy} \right) + w \left(\frac{du}{dz} \right)$$

$$Q - \frac{1}{q} \left(\frac{dp}{dy} \right) = \left(\frac{dv}{dt} \right) + u \left(\frac{dv}{dx} \right) + v \left(\frac{dv}{dy} \right) + w \left(\frac{dv}{dz} \right)$$

$$R - \frac{1}{q} \left(\frac{dp}{dz} \right) = \left(\frac{dw}{dt} \right) + u \left(\frac{dw}{dx} \right) + v \left(\frac{dw}{dy} \right) + w \left(\frac{dw}{dz} \right)$$

Si nous ajoutons à ces trois équations premièrement celle, que nous a fournie la considération de la continuité du fluide :

$$\left(\frac{dq}{dt}\right) + \left(\frac{d.qu}{dx}\right) + \left(\frac{d.qv}{dy}\right) + \left(\frac{d.qw}{dz}\right) = 0.$$

Si le fluide n'étoit pas compressible, la densité q seroit la même en Z , & en Z' , & pour ce cas on auroit cette équation :

$$\left(\frac{du}{dx}\right) + \left(\frac{dv}{dy}\right) + \left(\frac{dw}{dz}\right) = 0.$$

qui est aussi celle sur laquelle j'ai établi mon Mémoire latin allégué ci-dessus.

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THEOREM Let $(M_t \in \text{VPM}(D))$ be a solution of the Euler equations

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Then, for sufficiently short intervals $[t_0, t_1]$ (*), among all curves along $\text{VPM}(D)$ that coincide with (M_t) at $t = t_0, t_1$, (M_t) minimizes

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(*) If we assume the domain D and the (modified) pressure field $x \rightarrow \lambda \frac{|x|^2}{2} - p_t(x)$ to be both convex, for some $\lambda \in \mathbf{R}$, it is sufficient that $(t_1 - t_0)^2 \lambda < \pi^2$.

THE MINIMIZING GEODESIC PROBLEM

The (constant speed) minimizing geodesic problem can be written as a saddle point problem, just by using a time-dependent Lagrange multiplier to relax the constraint for M_t to belong to $VPM(D)$

$$\inf_M \sup_p \int_{t_0}^{t_1} \int_D \left\{ \frac{1}{2} \left| \frac{dM_t(\mathbf{x})}{dt} \right|^2 - p_t(M_t(\mathbf{x})) + p_t(\mathbf{x}) \right\} dx dt$$

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This is trivially bounded from below by

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which naturally leads to a dual least action principle

INCOMPRESSIBLE OPTIMAL TRANSPORT

The dual problem is concave

$$\sup_{\mathbf{p}} \inf_{\mathbf{M}} \int_{t_0}^{t_1} \int_{\mathbf{D}} \left\{ \frac{1}{2} \left| \frac{d\mathbf{M}_t(\mathbf{x})}{dt} \right|^2 - \mathbf{p}_t(\mathbf{M}_t(\mathbf{x})) + \mathbf{p}_t(\mathbf{x}) \right\} d\mathbf{x} dt$$

and reads (after a short calculation)

$$\sup_{\mathbf{p}} \int_{\mathbf{D}} \mathbf{J}_{\mathbf{p}}(\mathbf{M}_{t_0}(\mathbf{x}), \mathbf{M}_{t_1}(\mathbf{x})) d\mathbf{x} + \int_{t_0}^{t_1} \int_{\mathbf{D}} \mathbf{p}_t(\mathbf{x}) d\mathbf{x} dt$$

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with
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with $\mathbf{J}_{\mathbf{p}}(\mathbf{y}, \mathbf{z}) = \inf \int_{t_0}^{t_1} \left(\frac{1}{2} \left| \frac{d\xi_t}{dt} \right|^2 - \mathbf{p}_t(\xi_t) \right) dt$ where the infimum is taken over all curves $\xi_t \in \mathbf{D}$ such that $\xi_{t_0} = \mathbf{y} \in \mathbf{D}$, $\xi_{t_1} = \mathbf{z} \in \mathbf{D}$.



THIS IS A GENERALIZATION OF KANTOROVICH 1942 OPTIMAL TRANSPORT THEORY, ALSO SIMILAR TO WEAK KAM THEORY



Jellyfish! a more and more frequent (almost) incompressible optimal transport problem...

APPROXIMATE MINIMIZING GEODESICS

DEFINITION Let us assume D to be convex, fix $t_0 = 0$, $t_1 = 1$ and consider two maps $M_0, M_1 \in \text{VPM}(D)$. We say that $(M_t^\epsilon) \in \text{SDiff}(D)$ is an ϵ -minimizing geodesic if

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where $\frac{1}{2}d(M_0, M_1)^2$ denotes the maximal dual action. The existence of such approximations is in no way trivial and is a consequence of a key density result due to A. Shnirelman (GAFA 1994) for Y.B. "generalized incompressible flows" (JAMS 1991).

THE MAIN RESULT ON MINIMIZING GEODESICS: EXISTENCE OF A UNIQUE ACCELERATION

MAIN THEOREM Let us assume D to be convex, with $d \geq 3$, fix $t_0 = 0$, $t_1 = 1$ and consider two maps $M_0, M_1 \in \text{VPM}(D)$. Then, there is a **UNIQUE** pressure-gradient Dp_t such that for all (M_t^ϵ) ϵ -minimizing geodesics, we have in the sense of distributions

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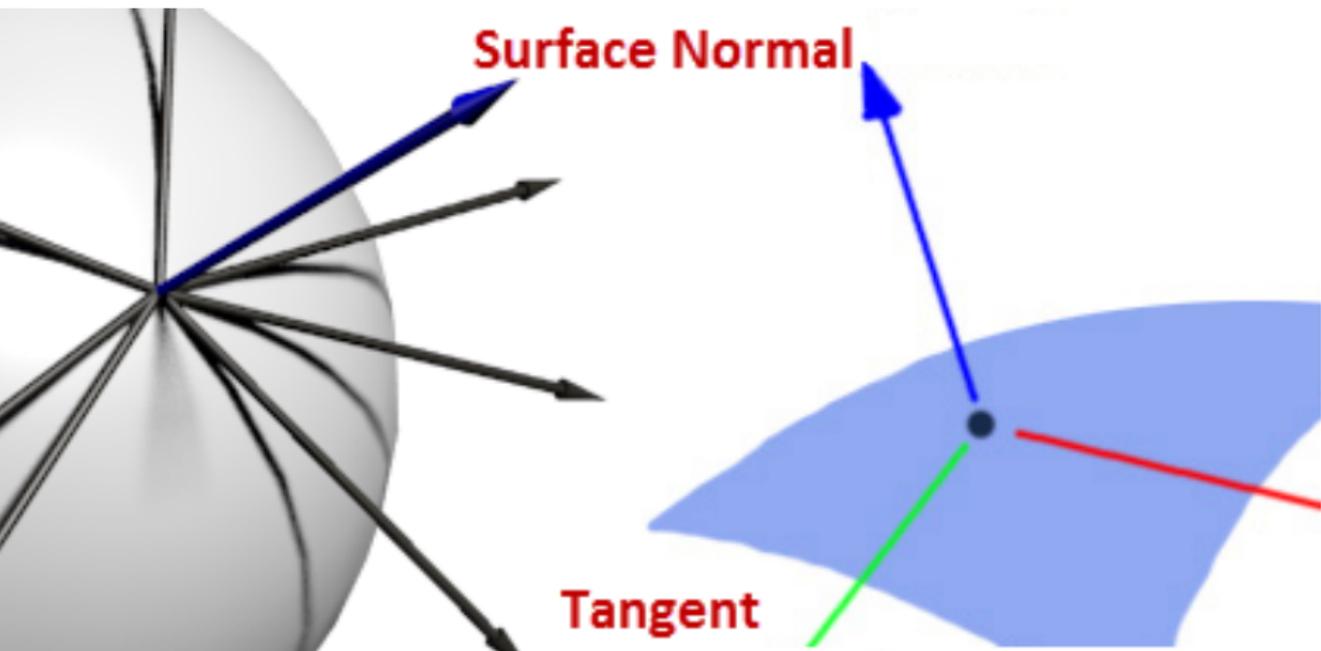
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In addition p belongs to the functional space $L_t^2(BV_x)_{\text{loc}}$
This result essentially goes back to YB CPAM 1999, with substantial improvements in Ambrosio-Figalli ARMA 2008. It is a combination of solving the dual least action problem and using Shnirelman's density result for "generalized flows", GAFA 1994.



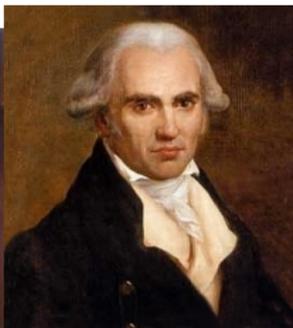
Uniqueness of the acceleration for minimizing geodesics along the (infinite dimensional) semi-group of volume-preserving maps, in the case of incompressible fluids.

There is no similar results for the minimizing geodesics along the (finite dimensional) group of orthogonal transforms, in the case of rigid solids.

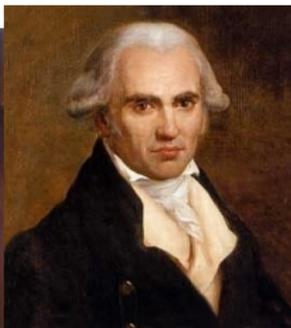
Toward modern art!



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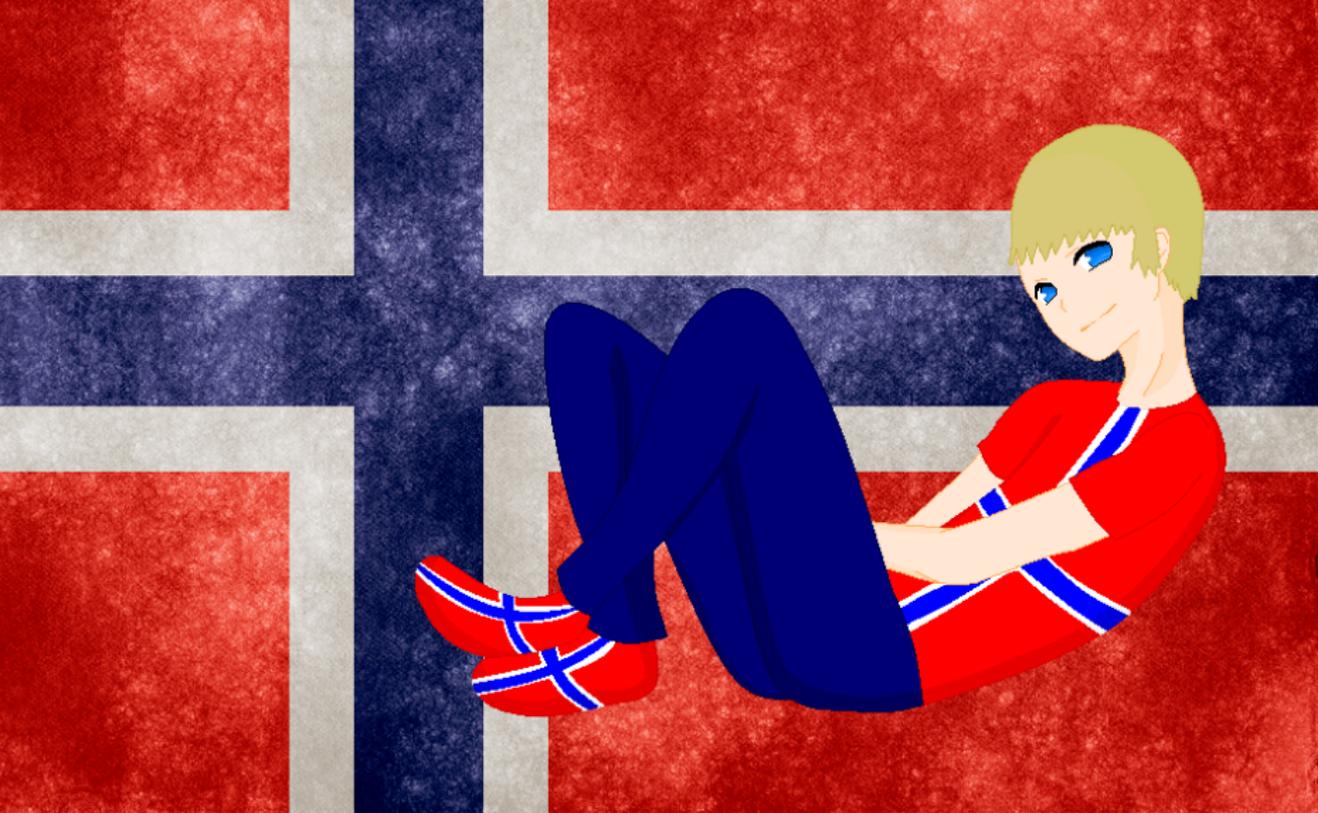
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Leonard, Gaspard, Leonid and ...CédrIvar?



Ivar younger than ever! Happy birthday!
(more conventional art)

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MINIMIZING GEODESICS AND CONVEXITY

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OTHER GEOMETRIC ANALYSIS ISSUES

GEODESIC COMPLETENESS This amounts to globally solving the initial value problem for the Euler equations. This is an outstanding problem for nonlinear evolution PDEs, which has not been discussed in this lecture. (You are welcome to ask questions after the talk!)

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MINIMIZING GEODESICS Shnirelman has proven (Math USSR Sb 1986) that existence of minimizing geodesics along $\text{SDiff}(D)$ may fail when $d \geq 3$. Remarkably enough, as already seen, the case $d \geq 3$ turns out to be "easy", with a crucial use of the convex structure of the dual problem. However the Hopf-Rinow theorem has not been proven in this framework. The case $d = 2$ is clearly linked to symplectic geometry and seems extremely difficult: a fascinating strategy has been developed by Shnirelman, by adding braid constraints to the minimization problem, which certainly deserves further investigations.