# Quelques contributions à l'étude qualitative et quantitative de modèles de la physique et de la biologie <br> Soutenance d'habilitation à diriger les recherches <br> Coordonnée par Jean Dolbeault 

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## What I like to (try to) do ...

$\rightarrow$ Study qualitatively and quantitatively models from physics and biology.
$\rightarrow$ Accent is put on nonlocal models, which have become more and more important and remain very difficult to study.
$\rightarrow$ Try to design and/or expand flexible methods for this kind of problems.
Of course, this a very general (and too big of a) deal. In the past few years, I have worked on ...
(1) Progagation phenomena in nonlocal models from ecology: Bramson corrections, accelerations.
(c) Trend to equilibrium and scaling limits in kinetic theory.

## 2

# Propagation in nonlocal reaction-diffusion models 



Propagation in nonlocal reaction-diffusion models
1 - Bramson delay in the nonlocal Fisher-KPP equation

## The logarithmic delay for Fisher-KPP

The most historical reaction-diffusion equation for population dynamics is..

$$
\begin{aligned}
& u_{t}=u_{x x}+u(1-u) \\
& u(0, x)=u_{0}
\end{aligned}
$$


... because it is known to exhibit front propagation since Fisher, KPP, Aronson-Weinberger, Fife-McLeod...

- With probabilistic techniques, Bramson ('78, ' 83 ) showed that if $u_{0}$ is compactly supported, the front of $u$ is located at

$$
X(t)=2 t-\frac{3}{2} \ln t+s_{0}
$$

where $s_{0}$ is a shift depending only on $u_{0}$.

- See $2 t$ as the position of a traveling wave, and $\frac{3}{2} \ln t$ as the delay due to the fact that the initial condition $u_{0}$ is compactly supported, so that the solution lags behind the traveling wave.


## The Hamel Nolen Roquejoffre Ryzhik strategy

These proofs have been simplified in recent years by Roberts (probabilistic approach) and Hamel-Nolen-Ryzhik-Roquejoffre ('12, '13).

Main strategy : Linearised problem with a Dirichlet condition at well chosen spots to create sub- and super- solutions.



Needs: comparison principles, precise quantitative estimates.

## A model with nonlocal competition

Consider a situation for which the competition (e.g. for resources) is nonlocal, with a kernel $\Phi$.

$$
\begin{aligned}
& u_{t}=u_{x x}+u(1-\Phi \star u) \\
& u(0, x)=u_{0}
\end{aligned}
$$

where

$$
\int_{\mathbb{R}} \Phi(x) d x=1, \quad \text { and } \quad \Phi(x)=\Phi(-x) \text { for all } x \in \mathbb{R}
$$

such that

$$
A_{\Phi}^{-1}(1+|x|)^{-r} \leq \Phi(x) \leq A_{\Phi}(1+|x|)^{-r}
$$

for all $x \in \mathbb{R}$, with some positive constants $r \in(1, \infty)$ and $A_{\phi}>0$.
Known: Propagation in a weak sense at speed 2 (Hamel-Ryzhik), uniform in time $L^{\infty}$ bound, non easy behaviour at the back (wave trains ...), steady states and travelling waves (sometimes!).

No comparison and maximum principles available.
References. Hamel-Ryzhik ('14), Berestycki-Nadin-Perthame-Ryzhik ('09).

## Logarithmic delay for the non-local Fisher-KPP equation

Question: Is the Bramson correction also true here and if yes, how to prove it?
Theorem (B., Henderson, Ryzhik ('17))
Take $u_{0}$ compactly supported and $\Phi \asymp|\cdot|^{-r}$.
$\odot$ If $r>3$, then the solution $u$ propagates with the $-\frac{3}{2} \ln (t)$ logarithmic delay.

- If $r=3$, then the solution u propagates with a larger logarithmic delay between $-S_{\phi} \ln (t)$ and $-s_{\phi} \ln (t)$.
$\odot$ If $r \in(1,3)$, then the delay is algebraic between $c_{\phi} t^{\frac{3-r}{1+r}}$ and $C_{\phi} t^{\frac{3-r}{1+r}}$.
Elements of proof:
- A local-in-time Harnack inequality of the form

$$
u(T, x+y) \leq C\|u\|_{L^{\infty}([t, T]) \times \mathbb{R}}^{1-\frac{1}{p}} u(T, x)^{\frac{1}{p}} e^{\alpha t+\frac{\beta y^{2}}{t}}
$$

to estimate

$$
\Phi \star u \lesssim \ln \left(\frac{M}{u}\right)^{1-r}
$$

- Adapt the H-N-R-R strategy to the local equation with a Gompertz type nonlinearity.

Heuristics for the exponent $\frac{3-r}{1+r}$

(1) Since $e(t)=o(t)$, we get $\lim _{t \rightarrow+\infty} \frac{d(t)}{e(t)}=0$. This gives, for $t$ large,

$$
d^{\prime}(t) \lesssim e(t)^{1-r} \lesssim t^{\frac{1-r}{2}} d(t)^{\frac{1-r}{2}} \Longrightarrow d(t) \lesssim t^{\frac{3-r}{1+r}} .
$$

(2) We deduce also $e(t) \gtrsim t^{\frac{2}{1+r}}$.

## Conclusions and related topics

$\triangleright$ New results for nonlocal KPP © ©
$\triangleright$ Keep in mind the local-in-time Harnack inequality for later ...
$\triangleright$ This lead to study more precisely travelling waves and delay for ...

$$
\begin{aligned}
& u_{t}=u_{x x}+u\left(1-A\left(\ln \left(\frac{\nu}{u}\right)\right)^{1-r}\right), \\
& u(0, x)=u_{0}
\end{aligned}
$$

Theorem (B., Henderson ('21))

- If $r>3$, then the delay is $\frac{3}{2} \log t$.
- If $r=3$, then the delay is $\left(1+\frac{1}{2} \sqrt{1+4 A}\right) \log t$.
- If $r \in(1,3)$, then the delay is $\Theta_{r} A^{\frac{2}{1+r}} t^{\frac{3-r}{1+r}}$, with $\Theta_{r}=\psi(0)$, where $\psi$ solves

$$
\begin{aligned}
& \psi^{\prime}=\frac{y}{1+r}-\sqrt{\frac{y^{2}}{(1+r)^{2}}+A y^{1-r}-\frac{3-r}{1+r} \psi}, \\
& \psi\left((1+r)^{\frac{2}{1+r}}\right)=(1+A) \frac{(1+r)^{\frac{3}{1+r}}}{3-r} .
\end{aligned}
$$

Propagation in nonlocal reaction-diffusion models
2 - Cane toads equation and related topics

## In short...

- We will discuss non-local reaction-diffusion-mutation models inspired by evolution in cane toads populations in Australia.
- Important feature : the propagation is actively influenced by a microscopic structure of the population : the leg-length/motility.
- Aim: We seek a precise description of the propagation, in particular, estimates of finite or infinite speeds of propagation.


## Evolution of dispersal in cane toads populations (e.g.)




- Speed increased by 5 .
- At the edge, faster toads in majority.
$\odot$ Spatial sorting : Dynamic selection of traits along the invasion.

We need models with both space and dispersion variables.

Reference. M. Urban et al (2008).

## Data of acceleration

Data from Urban et al. (Am. Nat. 2008): $1.63 \pm 0.13$.



Figure: Position of the front with years - Section Gordonvale-Timber Creek, for which spatial sorting is presumably the main effect.

Reference. M. Urban et al (2008).

## Modelling the cane toads invasion

$$
\begin{gathered}
t \in \mathbb{R}^{+}: \text {time, } \quad x \in \mathbb{R}: \text { space variable, } \quad \theta \in \Theta: \text { dispersal ability. } \\
\text { mutations, } \quad \text { reproduction rate. } \\
\begin{cases}n_{t}=\theta n_{x x}+r \alpha n_{\theta \theta}+r n(1-\rho), & (t, x, \theta) \in \mathbb{R}^{+} \times \mathbb{R} \times \Theta \\
\rho(t, x)=\int_{\Theta} n\left(t, x, \theta^{\prime}\right) d \theta^{\prime}, & (t, x) \in \mathbb{R}^{+} \times \mathbb{R}\end{cases}
\end{gathered}
$$

Neumann boundary conditions in $\Theta:=[\underline{\theta}, \bar{\theta}] \subset(0, \infty]$.
Crucial difference with standard Fisher - KPP:
No full maximum/comparison principles available

References. Desvillettes et al. ('04), Champagnat et al. ('07), Bénichou et al. ('12)

## Propagation for the Cauchy problem with bounded traits

Theorem (B., Henderson, Ryzhik ('16))
Assume that $\Theta$ is bounded and $n_{0} \sim \mathbb{1}_{[-\infty, 0] \times \Theta}$. Then there exists $m_{0}$ such that for all $\varepsilon \in\left(0, m_{0}\right)$, there is a positive constant $C_{\varepsilon}$ such that

$$
\liminf _{t \rightarrow \infty} \inf _{x \leq c_{*} t-\frac{3}{2 \lambda_{*}} \log (t)-C_{\varepsilon}} n(t, x) \geq m_{0}-\varepsilon
$$

$$
\limsup _{t \rightarrow \infty} \sup _{x \geq c_{*} t-\frac{3}{2 \lambda_{*}} \log (t)+C_{\varepsilon}} n(t, x) \leq \varepsilon
$$



See also. B. - Calvez ('14) (travelling waves).

## Acceleration result: local case

From now on $\Theta$ in unbounded: $\Theta=[\underline{\theta}, \infty)$. Consider first the local cane toads counterpart:

$$
n_{t}=\theta n_{x x}+r \alpha n_{\theta \theta}+r n(1-\mathrm{n})
$$

Theorem (B., Henderson, Ryzhik ('15))
Let $n$ the unique solution of the LOCAL cane toads equation. Fix any constant $m \in(0,1)$.

$$
\lim _{t \rightarrow \infty} \frac{\max \{x \in \mathbb{R}: \exists \theta \in \Theta, n(t, x, \theta)=m\}}{t^{3 / 2}}=\frac{4}{3} r \alpha^{1 / 4}
$$

Proof hinges on: linearized equation and comparison principle (NOT available for non-local problem)

See also. Berestycki et al. ('15) : same result with probability techniques.

## The trajectories

The only natural scaling to make in the linearised cane toads equation is

$$
(t, x, \theta) \mapsto\left(\frac{t}{\varepsilon}, \frac{x}{\varepsilon^{3 / 2}}, \frac{\theta}{\varepsilon}\right) \quad \Longrightarrow \quad \varepsilon w_{t}^{\varepsilon}=\varepsilon^{2} \theta w_{x x}^{\varepsilon}+\varepsilon^{2} w_{\theta \theta}^{\varepsilon}+w^{\varepsilon}
$$

Hopf-Cole transformation $w^{\varepsilon}=\exp \left(-\frac{\varphi^{\varepsilon}}{\varepsilon}\right)$, so that

$$
\varphi_{t}^{\varepsilon}+\theta\left|\varphi_{x}^{\varepsilon}\right|^{2}+\left|\varphi_{\theta}^{\varepsilon}\right|^{2}+1=\varepsilon \theta \varphi_{x x}^{\varepsilon}+\varepsilon \varphi_{\theta \theta}^{\varepsilon},
$$

and obtain, in the formal limit as $\varepsilon \rightarrow 0$, the Hamilton-Jacobi equation

$$
\varphi_{t}+\theta\left|\varphi_{x}\right|^{2}+\left|\varphi_{\theta}\right|^{2}+1=0 .
$$

We obtain...
$\triangleright$ an explicit formula for $\varphi$,

$$
\varphi(t, x, \theta)=\frac{1}{4 t}\left(\theta+Z(x, \theta)^{2}\right)^{2}-t, \quad \text { where } Z^{3}+3 \theta Z+3 x=0
$$

$\triangleright$ explicit Lagrangian trajectories.

## Upper and lower bounds

Upper bound: explicit super-solution (somewhat miraculously)


Lower bound: the moving ball technique.

$\triangleright$ Take an optimal Lagrangian trajectory given by the HJ equation,
$\triangleright$ Slide a suitable bump over this trajectory,
$\triangleright$ Use "time-dependent" Dirichlet principal eigenelements to maintain enough mass in the bump.

## Acceleration result for the nonlocal equation

Theorem (B., Henderson, Ryzhik ('15))
Let $u$ the unique solution of the cane toads equation. Fix any constant $m \in(0,1)$.

$$
\frac{8}{3 \sqrt{3 \sqrt{3}}} r \alpha^{1 / 4} \leq \limsup _{t \rightarrow \infty} \frac{\max \{x \in \mathbb{R}: \rho(t, x)=m\}}{t^{3 / 2}} \leq \frac{4}{3} r \alpha^{1 / 4} .
$$

Not sharp in two ways:

- Only lim sup : comes from proof by contradiction argument
- $\frac{4}{3}-\frac{8}{3 \sqrt{3 \sqrt{3}}} \sim .16$ : can (should?) not follow previous optimal trajectories !

Improved later by Calvez et al. refining the trajectories to take into account the nonlinearity: the nonlocal nonlinearity slows down the propagation!

See also. Berestycki et al. ('15) : propagation in a modified cane toads model with a windowed non-linearity.

## A model with a mortality trade-off

We take into account a penalization of very large traits on the reproduction rate (via a mortality trade-off).
$t \in \mathbb{R}^{+}:$time, $\quad x \in \mathbb{R}$ : space variable, $\quad \theta \in \Theta$ : dispersal ability.

$$
\begin{cases}n_{t}=\theta n_{x x}+r \alpha n_{\theta \theta}+r n(1-m(\theta)-\rho), & (t, x, \theta) \in \mathbb{R}^{+} \times \mathbb{R} \times \Theta \\ \rho(t, x)=\int_{\Theta} n\left(t, x, \theta^{\prime}\right) d \theta^{\prime}, & (t, x) \in \mathbb{R}^{+} \times \mathbb{R}\end{cases}
$$

with Neumann boundary conditions in $\theta \in \Theta:=[\underline{\theta},+\infty) \subset \mathbb{R}_{+}^{*}$.

$$
m(\underline{\theta})=0, \quad m \text { is increasing, } \quad \lim _{\theta \rightarrow+\infty} m(\theta)=+\infty .
$$

See also. Chan et al ('15)

## The spreading result

Denote by $\gamma_{\infty}$ the principal Neumann eigenvalue of $\alpha Q_{\theta \theta}+(1-m) Q$.
Theorem (B., Chan, Henderson, Kim ('17))
$\odot \gamma_{\infty} \leq 0 \quad \Longrightarrow \quad$ Extinction
$\odot \gamma_{\infty}>0 \Longrightarrow$ Propagation
$\triangleright \lim _{\theta \rightarrow+\infty} \frac{m(\theta)}{\theta}>0 \Longrightarrow \quad$ Finite speed of propagation, (explicit speed, travelling waves, linear spreading).
$\triangleright \frac{\mathrm{m}(\theta)}{\theta} \underset{\theta \rightarrow+\infty}{\searrow} 0 \Longrightarrow$ Acceleration. There exist $\underline{\text { a, }}$, such that,

$$
\liminf _{t \rightarrow \infty} \inf _{x \leq \underline{a} \eta(t)^{3 / 2}} \rho(t, x)>0 \quad \text { and } \quad \lim _{t \rightarrow \infty} \sup _{x \geq \bar{a} \eta(t)^{3 / 2}} n(t, x, \cdot)=0 \text {. }
$$

where $\int_{0}^{\eta(t)} \sqrt{m(s)} d s=t$.

## Numerics with $m \sim \theta^{p}, p=\frac{1}{3}, p=\frac{2}{3}$.

Theorem: $p<1 \Longrightarrow$ Acceleration regime: we have $\eta(t) \sim C t^{\frac{2}{2+p}}$, and thus the Cauchy problem spreads at $t^{\frac{3}{2+p}}$.


Figure: Cauchy problem at times (from top to bottom) $t=10, t=30, t=50$. Left column: $p=\frac{1}{3}$. Right column: $p=\frac{2}{3}$. Propagation at a super-linear rate.

## Numerics with $m \sim \theta^{p}, p=1, p=\frac{4}{3}$

Theorem: $p \geq 1 \Longrightarrow$ Linear regime : travelling wave solutions and the Cauchy problem spreads linearly.


Figure: Cauchy problem at times $t=10, t=30, t=50$. Left column: $p=1$. Right column: $p=\frac{4}{3}$. Propagation at a linear rate.

## Upper and lower bounds

Upper bound: Li-Yau estimates. The Lagrangian

$$
\zeta=\inf _{Z(0)=(y, \eta), Z(t)=(x, \theta), Z \in C^{0,1,1}([0, t])}\left\{\int_{0}^{t}\left(\frac{\left|\dot{Z}_{1}\right|^{2}}{4 Z_{2}}+\frac{\left|\dot{Z}_{2}\right|^{2}}{4}+m\left(Z_{2}\right)\right) d s\right\} .
$$

allows to estimate from above and gives for $\theta \leq \eta(t)$,

$$
u \lesssim \exp \left\{C t-\frac{\zeta}{2}\right\}
$$

The Hamilton-Jacobi solution is not necessarily a supersolution! Lower bound: the moving ball technique.


Main difference with standard toads:
Explicit trajectories not available, taking a reasonable path is fine.

Reference. P. Li, S.T. Yau, (1986).

## Perspectives and related topics

$\triangleright$ We got quantitative estimates on acceleration phenomena appearing in biology. More information on the (flattening) profiles?
$\triangleright$ Related but different, we got with Coville and Legendre quantitative acceleration results (rates and flattening) on

$$
u_{t}=P . V \cdot\left(\int_{\mathbb{R}}[u(t, y)-u(t, x)] J(x-y) d y\right)+u^{\beta}(1-u)
$$

where $J$ is a jump operator with a fat-tailed measure $J: J(z) \approx \frac{1}{|z|^{1+2 s}}$
Theorem (B., Coville, Legendre ('21))
Assume that

$$
\beta<1+\frac{1}{2 s-1} .
$$

Then for any $\lambda \in(0,1)$, the level line $x_{\lambda}(t)$ accelerates with the following rate,

$$
x_{\lambda}(t) \asymp_{\lambda} t^{\frac{\beta}{2 s(\beta-1)}} .
$$

# Scaling limits and hypocoercivity in kinetic theory 

## In short...

- We will talk about kinetic theory. More precisely, long time behaviour of linear kinetic equations coming originally from physics but that have now plenty of applications.
- Schematically, imagine that we observe a density of particules that "run" with some velocity, and "reorientate" due to internal processes or interaction with the environment.
- The specificity of the models we look at is that particules ...
(1) will not be confined in space $\odot$,
© will change their velocity to a high velocity with a "large" probability.


## An example: the run and tumble process of E. Coli.



Persistent motion, with two phases, alternately:
$\rightarrow$ straight run (deterministic),

$$
\dot{X}=V
$$

$\rightarrow$ change of velocity (random).
Every $\tau$ (Poissonian time), random choice of $V$ following a density $M$.

The main equation of this process is a kinetic equation.


## The models at hand

Density of particules $f(t, x, v)$ : time $t \in \mathbb{R}^{+}$, position $x \in \mathbb{R}^{d}$ and velocity $v \in \mathbb{R}^{d}$.

$$
\begin{aligned}
& \partial_{t} f+v \cdot \nabla_{x} f=\mathcal{L} f, \\
& f(0, \cdot, \cdot)=f^{\text {in }}
\end{aligned}
$$

Three types of reorientation operators:

- the generalized Fokker-Planck

$$
\mathcal{L} f=\nabla_{v} \cdot\left(M \nabla_{v}\left(M^{-1} f\right)\right),
$$

- the linear Boltzmann operator, or scattering collision operator

$$
\mathcal{L} f=\int_{\mathbb{R}^{d}} b\left(\cdot, v^{\prime}\right)\left[f\left(v^{\prime}\right) M(\cdot)-f(\cdot) M\left(v^{\prime}\right)\right] d v^{\prime},
$$

- the fractional Fokker-Planck operator of exponent $s \in(0,2)$.

$$
\mathcal{L} f=\Delta_{v}^{\frac{s}{2}} f+\nabla_{v} \cdot(E f)
$$

All satisfy

$$
\operatorname{Ker} \mathcal{L}=\operatorname{Span}(M)
$$

## Two crucial parameters...

First one: $M$ decays algebraically with an exponent $\alpha$.

$$
\forall v \in \mathbb{R}^{d}, \quad M(v)=c_{\alpha}\lfloor v\rceil^{-d-\alpha} \quad \text { where } \quad\lfloor v\rceil=\left(1+|v|^{2}\right)^{\frac{1}{2}} .
$$

Second one: The operator $\mathcal{L}$ looses a weight $\beta$.

- Weighted coercivity inequality

$$
-\operatorname{Re}\langle\mathcal{L} \varphi, \varphi\rangle_{L^{2}\left(M^{-1}\right)} \geq \lambda\left\|\varphi-\left(\int_{\mathbb{R}^{d}} \varphi\left(v^{\prime}\right)\left\lfloor v^{\prime}\right\rceil^{-\beta} d v^{\prime}\right) M\right\|_{L^{2}\left(\lfloor v\rceil^{-\beta} M^{-1}\right)}^{2}
$$

- Write formally as $\mathrm{B}[f]-\nu(v) f$ and define $-\beta$ as the exponent at infinity of the function $\nu$.

| Fokker-Planck | Scattering | Levy-Fokker-Planck |
| :---: | :---: | :---: |
| $\beta_{\mathrm{FP}}=2$ | $\int \mathrm{~b}\left(v, v^{\prime}\right) M\left(v^{\prime}\right) d v^{\prime} \sim\|v\|^{-\beta \mathbf{s c}}$ | $\beta_{\text {LFP }}=s-\alpha$ |

# Scaling limits and hypocoercivity in kinetic theory <br> 1- Scaling limits 

## Fractional limit, of not fractional limit, that is the question!

Claim: Take an initial data $f^{\text {in }} \in L^{2}\left(M^{-1} d x d v\right)$ and rescale space and time:

$$
\theta(\varepsilon) \partial_{t} f_{\varepsilon}+\varepsilon v \cdot \nabla_{x} f_{\varepsilon}=\mathcal{L} f_{\varepsilon} .
$$

Formally,

$$
\mathrm{f}_{\varepsilon} \longrightarrow \mathrm{M} \rho .
$$

## What we want to do:

$\rightarrow$ Find the relevant time change $\theta$ such that $\rho$ satisfies a proper limit equation.
$\rightarrow$ Study quantitatively the macroscopic limit $\varepsilon \rightarrow 0$. Provide rates of convergence and explicit constants.
$\rightarrow$ Have a unified approach (as much as possible...) working for a wide type of $\mathcal{L}$ 's.

## Existing works ...

- Take a Gaussian $M$ and a scattering operator. Then

$$
\theta(\varepsilon) \sim \varepsilon^{2} \quad\left(\text { and } \quad x \sim \varepsilon^{-1}\right)
$$

and leads to a diffusion equation for $\rho$ :

$$
\partial_{t} \rho=\nabla_{x} \cdot\left(A \nabla_{x} \rho\right)
$$

Larsen-Keller'74, Degond-Goudon-Poupaud'00.

- Roughly, if $M$ is a power law and has enough moments the limit is still diffusive. If not, the diffusion matrix $A$ is infinite!
- More precisely Mellet, Mischler and Mouhot considered

$$
\mathcal{L} f(v)=\int_{\mathbb{R}^{d}}\left[f\left(v^{\prime}\right) M(v)-f(v) M\left(v^{\prime}\right)\right]\lfloor v\rceil^{-\beta}\left\lfloor v^{\prime}\right\rceil^{-\beta} d v d v^{\prime}
$$

with $\beta>0$ and $\alpha \in(0,2+\beta)$. Then

$$
\theta(\varepsilon)=\varepsilon^{\zeta:=\frac{\alpha+\beta}{1+\beta}} \quad \text { and } \quad \partial_{t} \rho=\kappa \Delta_{x}^{\frac{\zeta}{2}} \rho \text {. }
$$

- Result reproved with different methods : Mellet'10 (moment method), Ben Abdallah-Mellet-Puel'11 (modified Hilbert expansion).


## Fokker-Planck, around Puel et al. and Fournier et al.

New activity from mid-2010s on around M. Puel \& collaborators and around Fournier and Tardif with probabilistic methods. Take

$$
\mathcal{L} f(v):=\nabla_{v} \cdot\left(M \nabla_{v}\left(\frac{f}{M}\right)\right)
$$

- Case $\alpha>4$ in Nasreddine-Puel'15 (standard diffusion),
- Critical case $\alpha=4$ in Cattiaux-Nasreddine-Puel'19 (standard diffusion with time scaling $\left.\varepsilon^{2}|\ln \varepsilon|\right)$ by probabilistic method
- Case $\alpha \in(0,4)$ in dimension $d=1$ (fractional diffusion) in Lebeau-Puel'19 by PDE method and the study of a spectral problem reminiscent of Ellis-Pinsky'75 seminal work,
- Case $\alpha \in(0,4)$ in dimension $d=1$ in Fournier-Tardif '19 and then dimension $d \geq 2$ treated in Fournier-Tardif '20 (fractional diffusion).

$$
\left.\theta(\varepsilon)=\varepsilon^{\frac{\alpha+2}{3}} \quad \text { (and } \quad x \sim \varepsilon^{-1}\right)
$$

## Scaling function and diffusion coefficient

Define the diffusion exponent

$$
\zeta=\zeta(\alpha, \beta):= \begin{cases}2 & \text { when } \alpha \in[2+\beta,+\infty] \\ \frac{\alpha+\beta}{1+\beta} & \text { when } \alpha \in[0,2+\beta)\end{cases}
$$

and the scaling function

$$
\theta(\varepsilon):= \begin{cases}\varepsilon^{\zeta} & \text { when } \alpha \in(-\beta,+\infty] \backslash\{0,2+\beta\}, \\ \varepsilon^{\zeta}|\ln \varepsilon| & \text { when } \alpha=2+\beta, \\ \frac{\varepsilon^{\zeta}}{|\ln \varepsilon|} & \text { when } \alpha=0,\end{cases}
$$

Note that the threshold $\alpha=2+\beta$ between standard and fractional diffusion corresponds to whether or not $[\cdot\rceil^{-\beta} \mathrm{M}$ has finite variance.

## The abstract result

Theorem (B., Mouhot '20)
Take a weak solution $f \in L_{t}^{\infty}\left([0,+\infty) ; L_{x, v}^{2}\left(M^{-1}\right)\right)$ with initially, say,

$$
\begin{aligned}
& \left\|\frac{f_{\varepsilon}}{M}(0, \cdot, \cdot)-r_{\varepsilon}(0, \cdot)\right\|_{-\beta} \lesssim \theta(\varepsilon)^{\frac{1}{2}}\left\|\frac{f_{\varepsilon}}{M}(0, \cdot, \cdot)\right\|, \\
& \lim _{\varepsilon \rightarrow 0} r_{\varepsilon}(0, \cdot):=r(0, \cdot) \text { in } H^{-\zeta}\left(\mathbb{R}^{d}\right) .
\end{aligned}
$$

Under some assumptions presented later on, on $[0, T]$,

$$
\lim _{\varepsilon \rightarrow 0} \frac{f_{\varepsilon}}{M}=r, \text { where } r \text { solves } \partial_{t} r=\kappa \Delta_{x}^{\frac{\zeta}{2}} r,
$$

with explicit topologies, rates of convergence and coefficients.


## Prepare a smart attack... : construction of a fluid mode

With a structural hypothesis on $\mathcal{L}$, for $\eta \in\left(0, \eta_{0}\right)$ there is a unique eigenpair,
Eigenvector $\phi_{\eta} \in L_{v}^{2}\left(\lfloor\cdot\rceil^{-\beta} M\right) \quad$ Eigenvalue $\mu(\eta) \in\left(0, r_{0}\right)$
solving, with $L h:=M^{-1} \mathcal{L}(M h)$,

$$
-L^{*} \phi_{\eta}-i \eta(v \cdot \sigma) \phi_{\eta}=\mu(\eta)\lfloor v\rceil^{-\beta} \phi_{\eta} \quad \text { with } \quad \int_{\mathbb{R}^{d}} \phi_{\eta}(v)\lfloor v\rceil^{-\beta} M(v) d v=1 .
$$

Moreover, the branch $\left(\phi_{\eta}, \mu(\eta)\right)$ connects to $(1,0)$ as $\eta \rightarrow 0$, with

$$
\left\|\phi_{\eta}-1\right\|_{-\beta} \lesssim \mu(\eta)^{\frac{1}{2}}
$$

## ... that you can explain on a small picture!



## The main computation...

Following a strategy a la Ellis-Pinsky and Lebeau-Puel,
Denote $h_{\varepsilon}:=\frac{f_{\varepsilon}}{M} \in L_{x, v}^{2}(M)$. Fourier-transform in $x$ to get on $\hat{h}_{\varepsilon}(t, \xi, v)$

$$
\theta(\varepsilon) \partial_{t} \hat{h}_{\varepsilon}=L \hat{h}_{\varepsilon}+i \varepsilon(v \cdot \xi) \hat{h}_{\varepsilon}
$$

Denote $\xi=:|\xi| \sigma$ and $\eta:=\varepsilon|\xi|$. Test (in $v$ ) against $M \phi_{\eta}$,

$$
\begin{aligned}
\theta(\varepsilon) \frac{d}{d t}\left\langle\hat{h}_{\varepsilon}, \phi_{\eta}\right\rangle & =\left\langle L \hat{h}_{\varepsilon}+i \varepsilon(v \cdot \xi) \hat{h}_{\varepsilon}, \phi_{\eta}\right\rangle=\left\langle\hat{h}_{\varepsilon}, L^{*}\left(\phi_{\eta}\right)+i \varepsilon(v \cdot \xi) \phi_{\eta}\right\rangle \\
& =-\mu(\eta)\left\langle\hat{h}_{\varepsilon},\lfloor v\rceil^{-\beta} \phi_{\eta}\right\rangle
\end{aligned}
$$

Then,

$$
\left\langle\hat{h}_{\varepsilon},\lfloor v\rceil^{-\beta}\right\rangle=\hat{r}_{\varepsilon}+\text { small }, \quad\left\langle\hat{h}_{\varepsilon}, \phi_{\eta}\right\rangle=\left\langle 1, \phi_{\eta}\right\rangle \hat{r}_{\varepsilon}+\text { small }
$$

and thus, roughly, $\partial_{t} \hat{r} \approx-\lim _{\varepsilon \rightarrow 0}\left(\frac{\mu(\varepsilon \xi)}{\theta(\varepsilon)}\right) \hat{r}$.
Scaling of $\mu$ determines $\theta$ and then the limit equation!

## Heuristics about the scaling ...

Start from

$$
\mu(\eta)=\eta \int_{\mathbb{R}^{d}}(v \cdot \sigma) \operatorname{lm}\left(\phi_{\eta}\right) M(v) d v
$$

- Either you can phone your dearest friend Lebesgue ...

$$
\mu(\eta) \sim \eta^{2} \int_{\mathbb{R}^{d}}(v \cdot \sigma)\left(\lim _{\eta \rightarrow 0} \frac{\operatorname{Im}\left(\phi_{\eta}\right)}{\eta}\right) M(v) d v .
$$

- Or you can't, since there is a "sliding hump phenomenon", and you rescale!

$$
\phi_{\eta}(u):=\phi_{\eta}\left(\eta^{-\frac{1}{1+\beta}} u\right)
$$

and then

$$
\mu(\eta) \propto \eta^{\frac{\alpha+\beta}{1+\beta}} \int_{\mathbb{R}^{d}}(u \cdot \sigma)\left(\lim _{\eta \rightarrow 0} \operatorname{Im}\left(\Phi_{\eta}(u)\right)\right)|u|^{-d-\alpha} d v .
$$

Final comment: hypothesis are (in particular) on the size of $\Phi_{\eta}$.

# Scaling limits and hypocoercivity in kinetic theory <br> 2 - Decay to zero and hypocoercivity 

## What is the question?

Claim: If the initial data has finite mass, $f^{\text {in }} \in L^{1}(d x d v)$, then the only integrable equilibrium (i.e. $L^{1}(d x d v)$ ) to

$$
\begin{aligned}
& \partial_{t} f+v \cdot \nabla_{x} f=\mathcal{L} f, \\
& f(0, \cdot, \cdot)=f^{\text {in }}
\end{aligned}
$$

is $f \equiv 0$.

## What we want to do:

$\rightarrow$ Study quantitatively the convergence to zero. Provide rates of convergence and explicit constants.
$\rightarrow$ Have a flexible method for this kind of problems as a preliminary brick to nonlinear problems.

## A result (among a few similar others)

Theorem (B., Dolbeault, Lafleche ('20))
Let $d \geq 2, \alpha>0$ and assume that $\beta$ and $\alpha$ are such that

$$
\alpha+\beta>0, \quad \alpha+\beta \neq 2 .
$$

For any $k \in(0, \alpha)$,

$$
\|f\|_{L^{2}\left(M^{-1} d x d v\right)}^{2} \lesssim \begin{cases}(1+t)^{-\frac{d}{\zeta}}\left\|f^{\text {in }}\right\|_{L^{2}\left(M^{-1}\right) \cap L^{1}}^{2} & \text { if } \beta \leq 0, \\ (1+t)^{-\min \left\{\frac{d}{\zeta}, \frac{k}{|\beta|}\right\}}\left\|f_{0}\right\|_{\left.L^{2}(L v)^{k} M^{-1}\right) \cap L^{1}}^{2} & \text { if } \beta>0 .\end{cases}
$$

## Remarks

$\rightarrow d=1$ also covered with a slight change.
$\rightarrow$ Any $\alpha, \beta$, with $\alpha>0$ and $\alpha+\beta>0$ covered.
$\rightarrow$ Use of $L^{2}\left(\lfloor v\rceil^{k} M^{-1} d x d v\right)$ norms only (no Sobolev).

## But roughly, what is and why is hypocoercivity?

Start with the basic $L^{2}\left(M^{-1}\right)$ energy estimate:

$$
\frac{1}{2} \frac{d}{d t}\|f\|_{L^{2}\left(M^{-1} d x d v\right)}^{2} \leq-\lambda\left\|\varphi-\left(\int_{\mathbb{R}^{d}} \varphi\left(v^{\prime}\right)\left\lfloor v^{\prime}\right\rceil^{-\beta} d v^{\prime}\right) M\right\|_{L^{2}\left(\lfloor v\rceil^{-\beta} M^{-1}\right)}^{2} .
$$

One cannot get any sort of decay strictly from here!

Started by Villani's memoir and with now a large literature (Villani, Mouhot, Neumann, Dolbeault, Schmeiser ....):
the intertwist between $\mathcal{L}$ and $v \cdot \nabla_{x}$ allows to recover a decay.
How: Re-casting the Dolbeault - Mouhot - Schmeiser method!

$$
\|f\|_{L^{2}\left(M^{-1}\right)}^{2} \quad \sim \quad \frac{1}{2}\|f\|_{L^{2}\left(M^{-1}\right)}^{2}+\delta \operatorname{Re}\langle\mathrm{A} f, f\rangle
$$

## The strategy and ingredients of the proof

(1) Mode by mode analysis. Take Fourier in $x$.

$$
\partial_{t} \hat{f}+i(v \cdot \xi) \hat{f}=\mathcal{L} \hat{f},
$$

(2) Mode by mode hypocoercivity functional. Define a new operator $A$ by

$$
A_{\xi}:=\frac{1}{\lfloor v\rceil^{2}} \Pi \frac{(-i v \cdot \xi)\lfloor v\rceil^{-\beta}}{1+\lfloor v\rceil^{2|1-\beta|}|\xi|^{2}}
$$

and the entropy functional by $\mathrm{H}_{\xi}[f]:=\frac{1}{2}\|\hat{f}\|^{2}+\delta \operatorname{Re}\left\langle\mathrm{A}_{\xi} \hat{f}, \hat{f}\right\rangle$.

- Mode by mode and then full energy estimate

$$
-\frac{d}{d t} \mathrm{H}[f]=-\langle f, \mathcal{L} f\rangle+\delta \int_{\mathbb{R}^{d}} \mathrm{R}_{\xi}[\hat{f}] d \xi
$$

with

$$
\mathrm{R}_{\xi}[\hat{f}] \gtrsim \mathcal{K}_{1}(\xi)\|\Pi \hat{f}\|^{2}-\mathcal{K}_{2}(\xi)\|(1-\Pi) \hat{f}\|_{\eta}^{2} .
$$

(9) Conservation of weighted $L^{2}$ norms and interpolation yields to an ODE of the form:

$$
H^{\prime} \leq-\phi(t) H^{\ominus} .
$$

## A summary (and other results)

$\triangleright$ These results are part of other results with spatial confinement (mainly weak)

|  | $V \equiv 0$ | $V \sim \gamma \ln (\|x\|)$ | $\underset{\alpha \in(0,1)}{\sim}\|x\|^{\alpha}$ | $V \underset{\alpha \geq 1}{\sim}\|x\|^{\alpha}$ |
| :---: | :---: | :---: | :---: | :---: |
| $M \lesssim e^{-\lfloor v\rceil}$ | $\begin{gathered} t^{-\frac{d}{2}} \\ \text { BDMS } \end{gathered}$ | $t_{B D L S}^{-\frac{d-\gamma}{2}}$ | $\begin{aligned} & e_{C a t^{b}}^{-\lambda t^{b}} \end{aligned}$ | $\begin{aligned} & e^{-\lambda t} \\ & \text { DMS } \end{aligned}$ |
| $M \underset{\alpha \in(0,1)}{e^{-\lfloor v\rceil^{\alpha}}}$ | $\begin{gathered} t^{-\min \left(\frac{d}{2}, \frac{k}{\beta}\right)} \\ B D L \end{gathered}$ | Open | Open | Open |
| $M \asymp \underset{\alpha>0}{\lfloor v]^{-d-\alpha}}$ | $\begin{gathered} t^{-\min \left(\frac{d}{\zeta}, \frac{k}{\beta_{+}}\right)} \\ B D L \end{gathered}$ | Open | Open | Open |

## Thank you for your attention!



