

# Propagation in kinetic reaction-transport equations

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# Kinetic reaction-transport equations

Kinetic density  $f(t, x, v)$ : time  $t$ , position  $x$  and velocity  $v$ .

Space density

$$\rho := \int_V f(v) dv,$$

Set of velocities

$$V = [-v_{\max}, v_{\max}],$$

$$\text{with } v_{\max} \leq +\infty.$$

3 ingredients :

- Run at velocity  $v$  = transport operator:  $\partial_t + v\partial_x$ ,
- Tumbling events = velocity jump process:  $\frac{1}{\tau} (M(v)\rho - f)$ ,
- Growth of the population = monostable nonlinearity:  $r\rho (M(v) - f)$ .

Altogether,

$$\partial_t f + v\partial_x f = \frac{1}{\tau} (M(v)\rho - f) + r\rho (M(v) - f)$$

Here,  $M$  is a given distribution which satisfies

$$\int_V M(v) dv = 1, \quad \int_V v M(v) dv = 0, \quad \int_V v^2 M(v) dv = \theta.$$

## What we want to do :

- Study qualitatively and quantitatively propagation phenomena in kinetic reaction-transport equations.
- Are there special effects due to considering populations at the "mesoscopic" scale ?

We study the propagation from two points of view :

- 1 First approach : Study of (non-)existence of travelling wave solutions,
- 2 Second approach : Geometric optics point of view.

# In Search of Kinetic Travelling Waves

$$\partial_t f + v \partial_x f = \frac{1}{\tau} (M(v) \rho - f) + r \rho (M(v) - f)$$

The equilibrium states: 0 and  $M(v)$ .

## Definition

A travelling wave solution is of the form

$$f(t, x, v) = \mu(\xi = x - ct, v),$$

$$\text{Speed : } c \in \mathbb{R}^+, \quad \text{Profile : } \mu \in \mathcal{C}^2(\mathbb{R} \times V, \mathbb{R}^+).$$

$$\text{Far field conditions :} \quad \mu(-\infty, \cdot) = M, \quad \mu(+\infty, \cdot) = 0.$$

Main equation :

$$(v - c) \partial_\xi \mu = \frac{1}{\tau} (M(v) \nu - \mu) + r \nu (M(v) - \mu), \quad \xi \in \mathbb{R}, v \in V.$$

where  $\nu$  is the macroscopic density associated to  $\mu$ , that is  $\nu(\xi) = \int_V \mu(\xi, v) dv$ .

# Why should we expect travelling waves ?

Macroscopic limit : We look at the situation when reorientations are much more frequent than reaction:

$$\mathbf{r} \mapsto (r\varepsilon^2).$$

$M$  is unbiased  $\rightarrow$  Parabolic scaling  $(t, x) \mapsto (\frac{t}{\varepsilon^2}, \frac{x}{\varepsilon})$  :

$$\varepsilon^2 \partial_t f + \varepsilon v \partial_x f = \frac{1}{\tau} (M(v)\rho - f) + r\varepsilon^2 \rho (M(v) - f).$$

Then formally,

$$\lim_{\varepsilon \rightarrow 0} f^\varepsilon(t, x, v) = M(v)\rho(t, x),$$

The macroscopic limit is (at least formally) the **Fisher-KPP equation**

$$\partial_t \rho = \tau \theta \partial_{xx} \rho + r \rho (1 - \rho)$$

# Travelling waves for the Fisher-KPP equation (1937)

Combining **reaction** and **diffusion** creates propagation :

Theorem (Kolmogorov, Petrovsky, Piskunov, 1937)

- There exists a **minimal speed**  $c^* := 2\sqrt{r\theta}$  such that for all speed  $c \geq c^*$ , there exists a travelling wave solution (  $\rho(t, x) := \bar{\rho}(x - ct)$  ) of speed  $c$ .
- If the initial data has compact support then the front propagates with the minimal speed  $c^*$ .

(Fisher, KPP, Kanel, Fife and McLeod, Aronson and Weinberger ...)

**The minimal speed  $c^*$  :**

The front is created by small populations at the edge that reproduce almost exponentially. Seeking exponential decay in **the linearized equation** :

$$\rho(t, x) := e^{-\lambda(x - c(\lambda)t)} \implies c(\lambda) = \theta\lambda + \frac{r}{\lambda} \geq 2\sqrt{r\theta} := c^*.$$

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**References.** R.A. Fisher, *The advance of advantageous genes*, (1937),  
D.G. Aronson et al. *Nonlinear diffusion in population genetics ...*, 1975.  
A.N. Kolmogorov et al. *Etude de l'équation de la diffusion ...*, (1937).

# Existence of travelling waves for the kinetic model

- 1 Perturbative approach in the parabolic limit  $(t, x, r) \mapsto (\frac{t}{\varepsilon^2}, \frac{x}{\varepsilon}, r\varepsilon^2)$

## Theorem (Cuesta, Hittmeir, Schmeiser)

Assume that  $V$  is compact. Let the wave speed satisfy  $c \geq 2\sqrt{r\theta}$ . For  $\varepsilon$  small enough, there exists a travelling wave solution of speed  $c$ .

- 2 Existence result in the kinetic regime:

## Theorem (B., Calvez, Nadin)

Assume that  $V$  is compact. Suppose that  $M$  is continuous and positive.

- 1 There exists a speed  $c^* \in (0, v_{\max})$  such that there exists a travelling wave solution of speed  $c$  for all  $c \in [c^*, v_{\max})$ .
- 2 The travelling wave is nonincreasing with respect to the space variable.
- 3 There exists no travelling wave of speed  $c \in [0, c^*)$ .

# Elements of proof

- ① Find the minimal speed  $c^*$  : Given a spatial decay  $\lambda \in \mathbb{R}^+$ , we seek solutions of the linearized problem of type

$$f(t, x, v) = e^{-\lambda(x-c(\lambda)t)} Q_\lambda(v).$$

Associated speed :  $c(\lambda) \in \mathbb{R}^+$ ,      Expected profile at the edge :  $Q_\lambda(v)$ .

## Proposition

We have  $c^* = \min_{\lambda>0} c(\lambda)$ , where  $c(\lambda)$  is a solution of

$$\int_V \underbrace{\frac{(1 + \tau r)M(v)}{1 + \tau \lambda(c(\lambda) - v)}}_{=Q_\lambda(v)} dv = 1.$$

- ② Key tool : Comparison principle.

We can define, thanks to the dispersion relation, for  $c \in (c^*, v_{\max})$ , an explicit couple of sub- and super- solutions.



# Further properties

## 1 Spreading at finite speed ( a la Aronson-Weinberger)

1 For all  $c > c^*$ ,

$$(\forall v \in V) \quad \lim_{t \rightarrow +\infty} \left( \sup_{x \geq ct} f(t, x, v) \right) = 0,$$

2 For all  $c < c^*$ ,

$$(\forall v \in V) \quad \lim_{t \rightarrow +\infty} \left( \sup_{x \leq ct} |M(v) - f(t, x, v)| \right) = 0,$$

2 Dynamical stability of the waves : *Rather explicit* weight  $\phi(\xi, v)$  such that a travelling wave profile is *weakly linearly stable* in  $L^2 (e^{-2\phi(\xi, v)} d\xi dv)$ .

# Obstruction

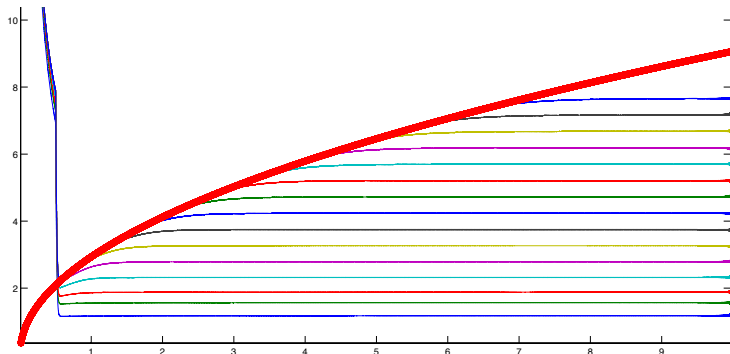
The dispersion relation for  $\lambda \in \mathbb{R}^+$

$$\int_V \frac{(1 + \tau r)M(v)}{1 + \tau\lambda(c(\lambda) - v)} dv = 1.$$

has **no solution** when  $V$  is unbounded ( $v_{\max} = +\infty$ ).

# Approximation of $v_{max} = +\infty$ : speed as a function of time

→ Gaussian equilibrium :  $M(v) = C(v_{max}) \exp\left(-\frac{v^2}{2}\right) \mathbf{1}_{|v| \leq v_{max}}$



Conjecture :

$$c(t) \approx \sqrt{t} \quad \Rightarrow \quad x(t) \approx t^{\frac{3}{2}}$$

# Acceleration phenomena

- Fisher-KPP with initial decay slower than exponential :  
F. Hamel, L. Roques, *Fast propagation for KPP equations with slowly decaying initial conditions*, (2010).
- Accelerated propagation in fractionnal diffusion equations :
  - X. Cabré, J.-M. Roquejoffre, *Propagation de fronts dans les équations de Fisher-KPP avec diffusion fractionnaire*, (2009).
  - X. Cabré, J.-M. Roquejoffre, *The influence of fractional diffusion in Fisher-KPP equations*, (2013).
  - A.-C. Coulon, J.-M Roquejoffre, *Transition between linear and exponential propagation in Fisher-KPP type reaction-diffusion equations*, (2012).
- Acceleration in integro-differential equations with slowly decaying kernel :  
J. Garnier, *Accelerating solutions in integro-differential equations*, (2011).

# Infinite speed of propagation

Assume that :  $\forall v \in \mathbb{R}, \quad M(v) > 0.$

Theorem (B., Calvez, Nadin)

Assume that there exists  $\gamma \in (0, 1)$  such that

$$\forall x \leq 0, \quad f(0, x, v) \geq \gamma M(v).$$

Then, one has, *for all*  $c > 0$ ,

$$\lim_{t \rightarrow +\infty} \sup_{x \leq ct} |M(v) - f(t, x, v)| = 0.$$

Sketch of proof.

$\lim_{v_{\max} \rightarrow +\infty} c^*(v_{\max}) = +\infty$  and a sub-solution using the truncated problem.  $\square$

## Rate of acceleration when $M$ is a Gaussian on $V = \mathbb{R}$

Using a sub- and super- solutions technique, we prove

Theorem (B., Calvez, Nadin)

Let  $M(v) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{v^2}{2}\right)$ . Under suitable hypothesis on the initial data, there exist two explicit constants  $c_1$  and  $c_2$  such that

$$\lim_{t \rightarrow +\infty} \left( \inf_{x \leq c_1 t^{3/2}} \rho(t, x) \right) \geq \frac{1}{2}, \quad \lim_{t \rightarrow +\infty} \left( \sup_{x \geq c_2 t^{3/2}} \rho(t, x) \right) = 0.$$

Proposition

$$c_1 := \left( \frac{r}{r + \frac{3}{2}} \right)^{\frac{3}{2}} \leq \underbrace{\frac{\left(\frac{2}{3}r\right)^{\frac{3}{2}}}{1+r}}_{\text{Expected constant}^a} \leq \sqrt{2r} =: c_2.$$

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<sup>a</sup>See later.

# Construction of the sub-solution

- Idea : The free transport operator sends **very few particles with very high velocity** at the edge of the front. They are **redistributed**, and their density **grows exponentially fast**.

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**Reference.** J. Garnier, *Accelerating solutions in integro-differential equations*, (2011).

The sub-solution has to solve :

$$\partial_t \underline{g} + v \partial_x \underline{g} + \underline{g} \leq \left(1 + \frac{r}{2}\right) M(v) \rho_{\underline{g}}.$$

① **Transport :**

$$g_2 = \frac{1}{2} M(v) e^{-\frac{x}{v}}, \quad \text{if } v > \frac{x}{t},$$

and zero elsewhere, solves

$$\partial_t g_2 + v \partial_x g_2 + g_2 = 0.$$

Partial mass contained in the branch  $v > \frac{x}{t}$ :

$$\mu_2(t, x) = \frac{1}{2} \int_{\frac{x}{t}}^{\infty} M(v) e^{-\frac{x}{v}} dv.$$

② **Redistribution & Growth :** In the area  $0 < v < \frac{x}{t}$ , the partial mass is denoted by  $\mu_1(t, x)$ . It solves,

$$\partial_t \mu_1 + \mu_1 = \left(1 + \frac{r}{2}\right) \left( \min \left( \mu_1, \frac{1}{2} \right) \int_0^{\frac{x}{t}} M(v) dv + \mu_2 \right).$$



The sub-solution has to solve :

$$\partial_t \underline{g} + v \partial_x \underline{g} + \underline{g} \leq 0 \quad .$$

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$$\partial_t \mu_1 + \mu_1 = \left(1 + \frac{r}{2}\right) \left( \min \left( \mu_1, \frac{1}{2} \right) \int_0^{\frac{x}{t}} M(v) dv + \mu_2 \right).$$

## Spreading : Estimation of $\mu_2$ and then $\mu_1$

### Lemma

*The following estimate holds true,*

$$\mu_2(t, x) \geq \frac{1}{r_2(x)} \exp\left(-\frac{3}{2}x^{2/3}\right), \quad \text{if } x < t^{3/2}.$$

We define the zone

$$\mathcal{Y}_t = \left\{x : x \leq (\alpha t)^{3/2}\right\}.$$

Estimation of  $\mu_1$  for  $x \in \mathcal{Y}_t$ :

$$\mu_1(t, x) \gtrsim \frac{1}{\sqrt{t}} \exp\left(-\frac{3}{2}\left((\alpha t)^{3/2}\right)^{2/3}\right) e^{r(1-\alpha)t}.$$

For suitable  $\alpha$ , for large times, the front has already passed through  $\mathcal{Y}_t$ .

### Remark

"Just" need to estimate  $\int_{\frac{x}{t}}^{\infty} M(v) e^{-\frac{x}{v}} dv$  !

# Conclusions

- Bounded velocities :
  - Minimal speed of propagation,
  - Profiles given by a spectral problem,
  - Linear spreading.

*As for the Fisher-KPP equation.*

- Unbounded velocities :
  - Accelerated propagation,
  - Almost exact rate in the Gaussian case ( $\sim t^{\frac{3}{2}}$ ),

**Unexpected result** *since the diffusive limit is the Fisher-KPP equation.*

# Hamilton-Jacobi approach

A method based on Hamilton-Jacobi equations has been used to study

- ① Front propagation in models structured only by the **space variable**:

Authors : Barles, Evans, Souganidis ... (89-94)

- ② Dynamics of most favorable traits in populations structured only by a **structural variable**:

Authors : Barles, Champagnat, Diekmann, Jabin, Lorz, Mirrahimi, Mischler, Perthame ...

**Aim** : Use this method to describe propagation phenomena in kinetic equations (populations structured by both **space variable** and **velocity**).

# Geometric point of view - Fisher-KPP case

Hyperbolic scaling:  $(t, x) \rightarrow (\frac{t}{\varepsilon}, \frac{x}{\varepsilon})$ :

$$(KPP_{\varepsilon}) \quad \varepsilon \partial_t \rho^{\varepsilon} = \varepsilon^2 \theta \Delta \rho^{\varepsilon} + r \rho^{\varepsilon} (1 - \rho^{\varepsilon}).$$

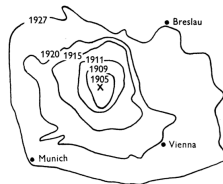
Hopf-Cole :  $\rho^{\varepsilon} = \exp(-\varepsilon^{-1} \varphi^{\varepsilon})$ .

Equation for  $\varphi^{\varepsilon}$  :

$$\partial_t \varphi^{\varepsilon} + \theta |\nabla_x \varphi^{\varepsilon}|^2 + r = \varepsilon \theta \Delta \varphi^{\varepsilon} + r \rho^{\varepsilon}.$$

When  $\varepsilon \rightarrow 0$ , the sequence  $\varphi^{\varepsilon}$  converges towards the **viscosity solution** of the following **constrained Hamilton-Jacobi equation**

$$\min(\partial_t \varphi^0 + \theta |\nabla_x \varphi^0|^2 + r, \varphi^0) = 0.$$



If

$$\varphi^0(0, x) = \begin{cases} 0 & \text{if } x = 0, \\ +\infty & \text{else,} \end{cases}$$

then

$$\varphi^0(t, x) = \max \left( \frac{x^2}{4\theta t} - rt, 0 \right),$$

The **nullset** of  $\varphi^0$  gives the information about the propagation:

$$\varphi^0(t, x) = 0 \quad \implies \quad |x| \leq 2\sqrt{r\theta} \, t.$$

Locally on

- $\text{Int}(\varphi^0 = 0)$ ,  $\lim_{\varepsilon \rightarrow 0} \rho^\varepsilon = 1$ .
- $\text{Int}(\varphi^0 > 0)$ ,  $\lim_{\varepsilon \rightarrow 0} \rho^\varepsilon = 0$ .

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**References.** M.I. Freidlin, *Geometric optics approach ...*, (1986)

L.C. Evans and P.E. Souganidis, *A PDE approach to geometric ...*, (1989)

# In the kinetic framework with bounded velocities.

Hyperbolic scaling :  $(t, x, v) \rightarrow (\frac{t}{\varepsilon}, \frac{x}{\varepsilon}, v)$

$$\varepsilon (\partial_t f^\varepsilon + v \cdot \nabla_x f^\varepsilon) = \frac{1}{\tau} (M(v) \rho^\varepsilon - f^\varepsilon) + r \rho^\varepsilon (M(v) - f^\varepsilon),$$

By analogy with Fisher-KPP, our **kinetic WKB ansatz** writes

$$f^\varepsilon(t, x, v) = M(v) e^{-\frac{\varphi^\varepsilon(t, x, v)}{\varepsilon}}.$$

New equation for  $\varphi^\varepsilon$  :

$$\tau (\partial_t \varphi^\varepsilon + v \cdot \nabla_x \varphi^\varepsilon) - 1 = -(1 + \tau r) \int_V M(v) e^{\frac{\varphi^\varepsilon(v) - \varphi^\varepsilon(v')}{\varepsilon}} dv' + \tau r \rho^\varepsilon,$$

→ Can we pass to the limit ? Does it make a difference with the macroscopic case ?



# Passing to the limit.

## Theorem (B. & Calvez)

Let  $V = [-v_{\max}, v_{\max}]$ . Suppose that the initial data is well-prepared,

$$\forall (x, v) \in \mathbb{R} \times V, \quad \varphi^\varepsilon(0, x, v) = \varphi_0(x),$$

Then  $(\varphi^\varepsilon)_\varepsilon$  converges locally uniformly towards  $\varphi^0$ , where  $\varphi^0$  **does not depend on  $v$** . Moreover  $\varphi^0$  is the unique viscosity solution of the constrained Hamilton-Jacobi equation

$$\begin{cases} \min \{ \partial_t \varphi^0 + \mathcal{H}(\nabla_x \varphi^0), \varphi^0 \} = 0, & \forall (t, x) \in \mathbb{R}_+^* \times \mathbb{R}, \\ \varphi^0(0, x) = \varphi_0(x), & x \in \mathbb{R}. \end{cases}$$

We combine **kinetic equations** and **viscosity solutions**!

## Sketch of proof

$$\tau (\partial_t \varphi^\varepsilon + v \cdot \nabla_x \varphi^\varepsilon) - 1 = -(1 + \tau r) \int_V M(v) e^{\frac{\varphi^\varepsilon(v) - \varphi^\varepsilon(v')}{\varepsilon}} dv' + \tau r \rho^\varepsilon,$$

- 1 Uniform Lipschitz estimates give the locally uniform convergence of  $\varphi^\varepsilon$  (up to extraction).
- 2 The boundedness of

$$\int_V M(v) e^{\frac{\varphi^\varepsilon(v) - \varphi^\varepsilon(v')}{\varepsilon}} dv'$$

forces in the limit

$$(\forall v, v' \in V) \quad \varphi^0(v) - \varphi^0(v') \leq 0,$$

an this implies the independence of  $v$  in the limit  $\varepsilon \rightarrow 0$ .

# About the Hamiltonian.

→ Looks like homogenization theory :  $x$  slow variable,  $v$  fast variable.

Now, write formally

$$\varphi^\varepsilon(t, x, v) = \varphi^0(x) - \varepsilon \ln \left( \frac{Q(t, x, v)}{M(v)} \right) + \mathcal{O}(\varepsilon),$$

**Homogenization:** being given  $\nabla_x \varphi^0$ , find  $\partial_t \varphi^0$  as an eigenvalue of a cell problem in the velocity space:

$$(1 - \tau (\partial_t \varphi^\varepsilon + v \cdot \nabla_x \varphi^\varepsilon)) Q(v) = (1 + \tau r) M(v) \int_V Q(v') dv'$$

Explicit solution in this case:

$$\int_V \frac{(1 + \tau r) M(v')}{1 - \tau \left( \underbrace{\partial_t \varphi^\varepsilon}_{-\mathcal{H}(\nabla_x \varphi^0)} + v' \cdot \nabla_x \varphi^\varepsilon \right)} dv' = 1.$$

The procedure can be written with a more general setting:

$$M(v)\rho - f \quad \longrightarrow \quad P(f) - \Sigma(v)f.$$

where  $P$  has a maximum principle.

- The equation writes

$$\min \{ \partial_t \varphi^0 + \mathcal{H}(\nabla_x \varphi^0) + r, \varphi^0 \} = 0,$$

- The Hamiltonian is obtained after solving a **spectral problem** in the velocity variable via a Krein-Rutman type argument :  
"For all  $p \in \mathbb{R}^n$ , there exists a unique  $\mathcal{H}(p)$  such that there exists a positive normalized eigenvector  $Q_p \in L^1(V)$  such that

$$\forall v \in V, \quad \mathcal{L}(Q_p)(v) + (v \cdot p) Q_p(v) = \mathcal{H}(p) Q_p(v)."$$

- $\mathcal{H}$  is globally **Lipschitz** with respect to  $p$  : It keeps in mind the finite speed of propagation at the kinetic level. Performing the diffusion limit first gives  $\theta|p|^2$ .

And if  $V = \mathbb{R}$  and  $M$  is a Gaussian ?

**The hyperbolic scaling is not relevant.**

The only interesting scaling is

$$(t, x, v) = \left( \frac{t'}{\varepsilon}, \frac{x'}{\varepsilon^{3/2}}, \frac{v'}{\varepsilon^{1/2}} \right).$$

Theorem (B., Calvez, Grenier, Nadin)

Assume  $r = 0$ . Then the limit system when  $\varepsilon \rightarrow 0$  shall be :

$$\left\{ \begin{array}{l} \max \left( \partial_t \varphi^0 + v \cdot \nabla_x \varphi^0 - 1, \varphi^0 - \min_{w \in \mathbb{R}^n} \varphi^0 - \frac{|v|^2}{2} \right) = 0, \\ \partial_t \left( \min_{w \in \mathbb{R}^n} \varphi^0 \right) \leq 0, \\ \partial_t \left( \min_{w \in \mathbb{R}^n} \varphi^0 \right) = 0, \quad \text{if } \operatorname{argmin}(\varphi^0)(t, x) = \{0\}. \\ \varphi^0(0, x, v) = \varphi_0(x, v). \end{array} \right.$$

# Sketch of proof

The equation to solve is (when  $r = 0$ ):

$$\partial_t \varphi^\varepsilon + v \cdot \nabla_x \varphi^\varepsilon = 1 - \frac{1}{\sqrt{2\pi\varepsilon}} \int_{\mathbb{R}^n} \exp\left(\frac{\varphi^\varepsilon(v) - \varphi^\varepsilon(v') - |v|^2/2}{\varepsilon}\right) dv',$$

Uniform bounds imply, as  $\varepsilon \rightarrow 0$ ,

$$(\forall v, v') \quad \varphi^0(v) \leq \varphi^0(v') + \frac{|v|^2}{2} \quad \implies \quad \varphi^0(v) \leq \min_{v' \in \mathbb{R}} \varphi^0(v') + \frac{|v|^2}{2}$$

**Non-local** constraint!

→ The minimum value is attained at  $v = 0$ .

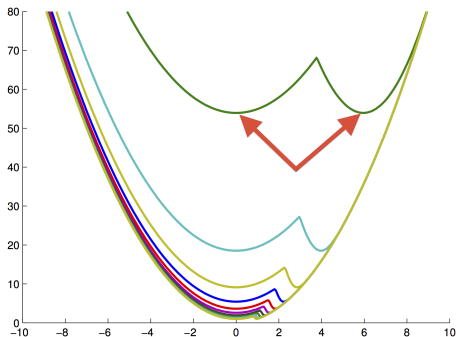
→ Free transport in the unconstrained area:

$$\partial_t \varphi^0 + v \cdot \nabla_x \varphi^0 - 1 = 0.$$

Problem: dynamics of the minimum value  $\min_v \varphi^0(t, x, v)$ ?

# Numerical illustration

It can vary only if there is another minimum point,  $v^* \neq 0$ , in the unsaturated area !.



Time snapshots of the velocity profile (fixed  $x$ )

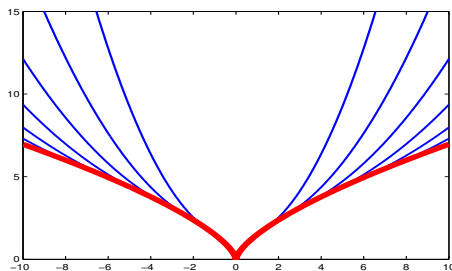
# Fundamental solution of the limit system

Initial data:

$$\varphi^0(0, x, v) = \mathbf{0}_{x=0} + \mathbf{0}_{v=0}.$$

The minimum value satisfies:

$$\min_v \varphi^0(t, x, v) = \min_{0 \leq s \leq t} \left( \frac{x^2}{2s} + s \right) = \begin{cases} \frac{3}{2}|x|^{2/3} & \text{if } |x| \leq t^{3/2} \\ \frac{|x|^2}{2t^2} + t & \text{if } |x| \geq t^{3/2} \end{cases}$$



Time snapshots of the minimum value  $\min_v \varphi^0(t, x, v)$



## Front acceleration when $r > 0$ .

The equation is :

$$\partial_t \varphi^\varepsilon + v \cdot \nabla_x \varphi^\varepsilon = 1 - (1+r) \int_{\mathbb{R}^n} \frac{1}{\sqrt{2\pi\varepsilon}} e^{\frac{\varphi^\varepsilon - \varphi'^\varepsilon - |v|^2/2}{\varepsilon}} dv' + \frac{r}{\sqrt{\varepsilon}} \int_{\mathbb{R}^n} e^{-\frac{\varphi'^\varepsilon}{\varepsilon}} dv'.$$

Constraint coming from the nonlinear problem :  $\min_{v \in \mathbb{R}} \varphi^0(t, x, v) \geq 0$ .

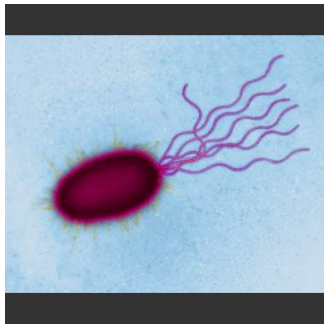
We can prove that we can proceed as for the Fisher-KPP equation case:

We truncate the fundamental solution of the linearized limit system such that it satisfies the constraint.

We obtain

$$\min_{v \in \mathbb{R}} \varphi^0 = 0 \quad \implies \quad \frac{3}{2} ((1+r)x)^{\frac{2}{3}} = rt \quad \implies \quad x = \frac{\left(\frac{2}{3}r\right)^{\frac{3}{2}}}{1+r} t^{\frac{3}{2}}.$$

Thank you for your attention ...



*... and happy 40<sup>th</sup> birthday to you, Francis !*