

A kinetic eikonal equation



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We consider the following **kinetic equation with BGK relaxation operator**

$$\partial_t f + v \cdot \nabla_x f = M(v)\rho - f, \quad (t, x, v) \in \mathbb{R}_+ \times \mathbb{R}^n \times V, \quad (1)$$

where $f(t, x, v)$ denotes the density of particles moving with speed $v \in V$ at time t and position x . The function $\rho(t, x)$ denotes the macroscopic density of particles:

$$\rho(t, x) = \int_V f(t, x, v) dv, \quad (t, x) \in \mathbb{R}_+ \times \mathbb{R}^n.$$

Here V denotes a **bounded symmetric subset of \mathbb{R}^n** . The Maxwellian M is symmetric and satisfies:

$$\int_V M(v) dv = 1, \quad \int_V v M(v) dv = 0, \quad \int_V v^2 M(v) dv = \theta^2.$$

The hydrodynamic limit of the BGK equation

We focus on the **large scale hyperbolic limit** $(t, x) \rightarrow (\frac{t}{\varepsilon}, \frac{x}{\varepsilon})$, $\varepsilon \rightarrow 0$. The kinetic equation (1) reads as follows in the new scaling:

$$\partial_t f^\varepsilon + v \cdot \nabla_x f^\varepsilon = \frac{1}{\varepsilon} (M(v)\rho^\varepsilon - f^\varepsilon), \quad (t, x, v) \in \mathbb{R}_+ \times \mathbb{R}^n \times V. \quad (2)$$

We introduce of the following Hopf-Cole transformation:

$$f^\varepsilon(t, x, v) = M(v) e^{-\frac{\varphi^\varepsilon(t, x, v)}{\varepsilon}}.$$

where **we expect the phase φ^ε to become independent of v as $\varepsilon \rightarrow 0$** .

The Hamilton-Jacobi equation

Theorem 1. Let $V \subset \mathbb{R}^n$ be **bounded** and symmetric, and $M \in L^1(V)$ be nonnegative and symmetric. Then φ^ε converges (locally) uniformly towards φ^0 , where φ^0 does not depend on v . Moreover φ^0 is the **viscosity solution of the following Hamilton-Jacobi equation**:

$$\int_V \frac{M(v)}{1 - \partial_t \varphi^0(t, x) - v \cdot \nabla_x \varphi^0(t, x)} dv = 1, \quad (t, x) \in \mathbb{R}_+ \times \mathbb{R}^n. \quad (3)$$

The denominator of the integrand is positive for all $v \in V$.

The last observation in Theorem 1 is **not compatible with an unbounded velocity set**.

Explicit computations of the effective Hamiltonian.

Using the implicit function theorem, equation (3) rewrites as $\partial_t \varphi^0 + H(\nabla_x \varphi^0) = 0$, where H is the **effective Hamiltonian**. **The effective Hamiltonian is convex.**

- We can compute the effective Hamiltonian H in one dimension for a constant Maxwellian $M \equiv \frac{1}{2}$ on $V = (-1, 1)$. We obtain $H(p) = \frac{p - \tanh(p)}{\tanh(p)}$.

- When $M(v) = \frac{1}{2}(\delta_1 + \delta_{-1})$, though it is not a L^1 function, we are able to obtain the relativistic hamiltonian $H(p) = \frac{\sqrt{1+4p^2}-1}{2}$.

Kinetic Eikonal vs Classical Eikonal

We obtain a Hamilton-Jacobi equation which differs from the classical eikonal equation, see the Figure below. This is unexpected since the formal limit of equation (2) at order $O(\varepsilon)$ is the heat equation with small diffusivity:

$$\partial_t \rho^\varepsilon = \varepsilon \theta^2 \Delta_x \rho^\varepsilon, \quad (t, x) \in \mathbb{R}_+ \times \mathbb{R}^n.$$

It is well-known that the phase $\phi^\varepsilon = -\varepsilon \log \rho^\varepsilon$ satisfies in the limit $\varepsilon \rightarrow 0$ the classical eikonal equation in the sense of viscosity solutions [4, 3]:

$$\partial_t \phi^0 + \theta^2 |\nabla_x \phi^0|^2 = 0. \quad (4)$$

We only have asymptotic equivalence between the two approaches for small $|p|$ by Taylor expansion: $H(p) \sim \theta^2 |p|^2$.

Elements of the proof

Step 1. Existence and uniform bounds.

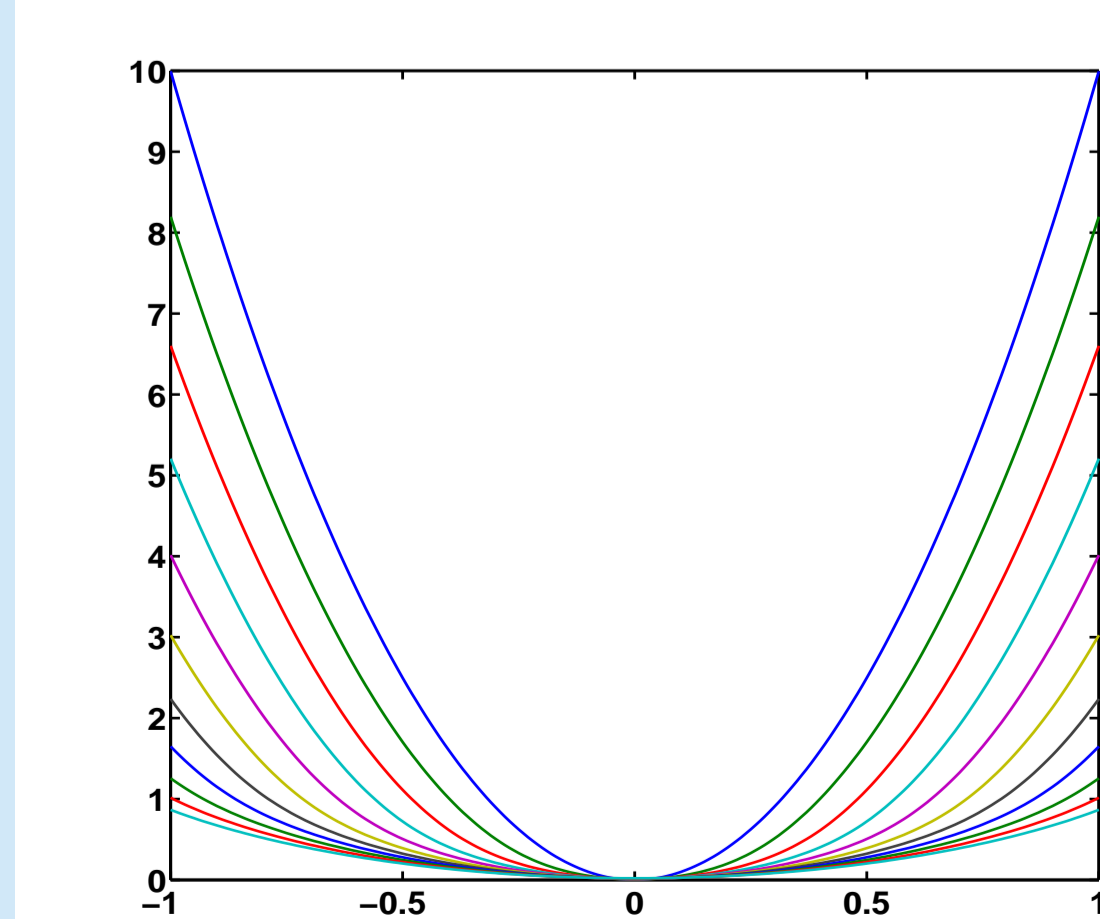
Proposition 1. Let $V \subset \mathbb{R}^n$ be a bounded subset. Assume $M \in L^1(V)$ and $\varphi_0 \in W^{1,\infty}(\mathbb{R}^n)$. The kinetic equation has a unique solution $\varphi^\varepsilon \in W^{1,\infty}(\mathbb{R}_+ \times \mathbb{R}^n \times V)$ uniformly in ε (locally in time).

Step 2. Viscosity solution procedure.

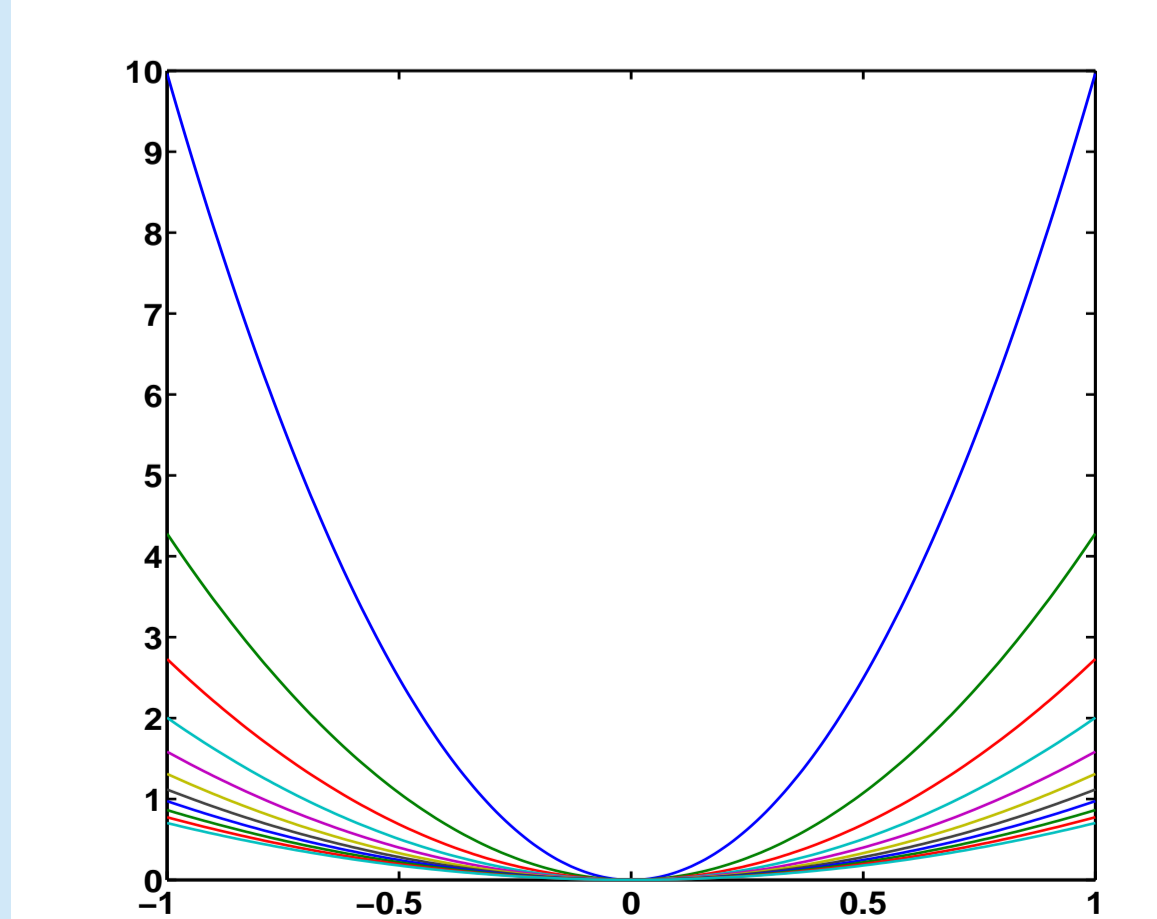
1. **Locally uniform convergence.** We can extract from the family $(\varphi^\varepsilon)_\varepsilon$ a locally uniformly converging subsequence. We denote by φ^0 the limit. We prove that φ^0 does not depend on v .
2. **Viscosity solution and corrector term.** Let $\psi^0 \in C^2(\mathbb{R}_+ \times \mathbb{R}^n)$ be a test function such that $\varphi^0 - \psi^0$ has a local maximum at (t^0, x^0) . We define a corrector term η depending on ε , as in the Evans perturbed test function method [2]: $\psi^\varepsilon = \psi^0 + \varepsilon \eta$.
3. **Maximum principle.** We prove the subsolution property thanks to an adapted maximum principle.

References

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- [2] L.C. Evans, *The perturbed test function method for viscosity solutions of nonlinear PDE*, Proc. Roy. Soc. Edinburgh Sect. A 111, 359-375 (1989).
- [3] L.C. Evans and P.E. Souganidis, *A PDE approach to geometric optics for certain semilinear parabolic equations*, Indiana Univ. Math. J. 38, 141-172 (1989).
- [4] M.I. Freidlin, *Geometric optics approach to reaction-diffusion equations*, SIAM J. Appl. Math. 46, 222-232 (1986).



KINETIC EIKONAL



CLASSICAL EIKONAL

COMPARISON BETWEEN THE KINETIC EIKONAL EQUATION (3) AND THE CLASSICAL EIKONAL EQUATION (4), WITH A CONSTANT MAXWELLIAN ON $V = (-1, 1)$.