A kinetic Fisher-KPP equation : traveling waves and front acceleration.

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UMPA - ENS de Lyon

La Londe les Maures - 2012

Introduction.

2) Traveling waves when V is bounded

3 Finally, what happens when V is unbounded?



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How do bacteria move ...

The bacteria E. Coli moves thanks to flagella :





and with a so-called *run and tumble* process : straight swimming for 1*s* and change of direction for 0.1*s*.

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From Howard Berg's lab

Collective migration

Bacterial traveling pulses :



The kinetic point of view is the most relevant for this situation.

Saragosti J, Calvez V, Bournaveas N, Buguin A, Silberzan P, et al. (2010) Mathematical Description of Bacterial Traveling Pulses. PLoS Comput Biol 6(8)

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Introduction.

Kinetic equations

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- Probability density of bacteria f(t, x, v) at time t, position x and speed v. Total density $\rho := \int_V f(v) dv$.
- The velocity set V : symmetric, bounded or unbounded.

The model (e.g. Schmeiser and al, 2010):

$$\underbrace{\varepsilon \partial_t f + v \partial_x f}_{\text{Free run}} = \underbrace{\frac{1}{\varepsilon} \left(M(v)\rho - f \right)}_{Tumbling} + \underbrace{\varepsilon r\rho \left(M(v) - f \right)}_{\text{Growth with saturation}}$$
(1)

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where the Maxwellian M on the space V satisfies

$$\int_{V} M(v)dv = 1, \qquad \int_{V} vM(v)dv = 0, \qquad \int_{V} v^{2}M(v)dv = D.$$
(2)

Aim of the talk : traveling waves

Formally, in the limit $\varepsilon \rightarrow 0$, ρ satisfies the classical Fisher-KPP equation (1937) :

$$\partial_t \rho - D \partial_{xx} \rho = r \rho (1 - \rho).$$
 (3)

It is now well known that (3) admits traveling waves solutions with minimal speed $c_{KPP} = 2\sqrt{rD}$.

Aim of the talk : Discuss existence and stability of traveling fronts for (2), for all values of ε (i.e. in the full kinetic regime).

Plan.



- 2 Traveling waves when V is bounded
- \bigcirc Finally, what happens when V is unbounded?



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2 Traveling waves when V is bounded

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Without loss of generality, we assume that V = [-1; 1].

Definition

We say that a function f(t, x, v) is a traveling front solution of speed $c \in \mathbb{R}^+$ of equation (1) if it can be written $f(t, x, v) = \mu (\xi = x - ct, v)$, where the profile $\mu \in C^2 (\mathbb{R} \times V)$ is nonnegative, satisfies $\mu (-\infty, \cdot) = M$, $\mu (+\infty, \cdot) = 0$, and μ solves

$$\varepsilon(\mathbf{v}-\mathbf{c}\varepsilon)\partial_{\xi}\mu = (M(\mathbf{v})\nu-\mu) + r\varepsilon^{2}\nu\left(M(\mathbf{v})-\mu\right), \qquad \xi \in \mathbb{R}, \ \mathbf{v} \in \mathbf{V}.$$
(4)

where ν is the macroscopic density associated to μ , that is $\nu(\xi) = \int_{V} \mu(\xi, \mathbf{v}) d\mathbf{v}$.

Existence result

Theorem

Assume that $\varepsilon > 0$ and that $\operatorname{Supp}(M) = [-1, 1]$. There exists a minimal speed $c^*(\varepsilon) \in (0, \frac{1}{\varepsilon})$ such that there exists a traveling wave solution of (1) of speed c for $c \in [c^*(\varepsilon), \frac{1}{\varepsilon}]$. Moreover, this traveling wave is nonincreasing with respect to x.

This is *not* a perturbative result from the Fisher-KPP equation.

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Finding the speed : Dispersion relation

- As for the Fisher-KPP equation, the rate of exponential decay in space and the speed are given by the linearized problem at the edge of the front. In this case, we have $D\lambda^2 c\lambda + r = 0$.
- Similarly, looking for a solution of the linearized problem of type $e^{-\lambda\xi}Q(v)$ yields the following **spectral problem**: For all λ , find $c(\lambda)$ such that there exists a Maxwellian Q_{λ} such that

$$\forall v \in V, \quad (1 + \varepsilon \lambda (c(\lambda)\varepsilon - v)) Q_{\lambda}(v) = (1 + r\varepsilon^2) \int_{V} M(v) Q_{\lambda}(v) dv. \quad (5)$$

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Proposition

For all $\varepsilon > 0$, the minimal speed $c^*(\varepsilon)$ is given by $c^*(\varepsilon) = \min_{\lambda > 0} c(\lambda)$ where $c(\lambda)$ is for all λ a solution of the following dispersion relation :

$$(1+r\varepsilon^2)\int_V \frac{M(v)}{1+\varepsilon\lambda(c(\lambda)\varepsilon-v)}\,dv=1\,.$$
(6)

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This relation is *not* compatible with and unbounded velocity set.

Remarks on the results

- The existence result is proved using a sub- and super-solutions technique (see e.g. Berestycki and Hamel).
- **②** We can provide estimates for the critical speed $c^*(\varepsilon)$. In particular,

Proposition

Assume that
$$\operatorname{Supp}(M) = [-1, 1]$$
, then $c^*(\varepsilon) \xrightarrow[\varepsilon \to 0]{} 2\sqrt{rD} := c_{\operatorname{KPP}}$.





\bigcirc Finally, what happens when V is unbounded?



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Numerical simulations



Figure: Evolution of the speed of the front for different values of the maximal speed. The Maxwellian here is a Gaussian : $M(v) = C(V_{max}) \exp\left(-\frac{v^2}{2}\right)$. "Bell" initial condition.

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Concluding remarks.

- When V is bounded we construct traveling wave profiles. The speed is obtained through a dispersion relation.
- On the contrary, when V is unbounded, accelaration pattern is observed.

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Conclusion.

Thank you for your attention !



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References

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