

Stochastic control (course 2)

Chap I Feynman-Kac

• SDE: in \mathbb{R}^d ($d \geq 1$)

$$\begin{cases} dX_s = b(s, X_s) ds + \sigma(s, X_s) dW_s \\ X_t = x \end{cases}$$

- (H1) {
- $(t, x) \in [0, T] \times \mathbb{R}^d$ initial condition
 - $(W_s)_{0 \leq s \leq T}$ Brownian motion, m -d.
 - $b: [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^d$
 - $\sigma: [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^{d \times m}$ } continuous
- Hyp 1 $\exists L > 0$ s.t. $\forall s \in [0, T], \forall x, y \in \mathbb{R}^d$
- $$|b(s, x) - b(s, y)| + |\sigma(s, x) - \sigma(s, y)| \leq L|x - y|$$

[Theo (Cauchy-Lipschitz)]

$\exists!$ sol $(X_s^{t,x})_{0 \leq s \leq T}$ sol to (SDE)

ie

$$X_s^{t,x} = x + \int_t^s b(u, X_u^{t,x}) du + \int_t^s \sigma(u, X_u^{t,x}) dW_u$$

$\forall s \in [t, T]$

• Cost

$$v(t, x) = \mathbb{E} \left[\underbrace{\int_t^T f(s, X_s^{t,x}) ds}_{\text{running cost}} + \underbrace{g(X_T^{t,x})}_{\text{terminal cost}} \right]$$

where: • $f: (0, T) \times \mathbb{R}^d \rightarrow \mathbb{R}$
 (H2) • $g: \mathbb{R}^d \rightarrow \mathbb{R}$ $\left\{ \begin{array}{l} \text{continuous} \\ \& \text{bounded} \end{array} \right.$

and $|f(s, x) - f(s, y)| + |g(x) - g(y)| \leq L|x - y|$
 $\forall s \in (0, T], x, y \in \mathbb{R}^d$

Lemma: v is Lipschitz in x uniformly in t .

because:

• $\exists c > 0$ s.t.

$$\mathbb{E} \left[\sup_{s \in [t, T]} |X_s^{t,x} - X_s^{t,y}|^2 \right] \leq c|x - y|^2$$

(see course 1)

• So

$$\begin{aligned} |v(t, x) - v(t, y)| &\leq \mathbb{E} \left[\int_t^T |f(s, X_s^{t,x}) - f(s, X_s^{t,y})| ds \right. \\ &\quad \left. + |g(X_T^{t,x}) - g(X_T^{t,y})| \right] \\ &\leq \mathbb{E} \left[L \int_t^T |X_s^{t,x} - X_s^{t,y}| ds \right. \\ &\quad \left. + L |X_T^{t,x} - X_T^{t,y}| \right] \end{aligned}$$

$$\leq L(T+1) \mathbb{E} \left[\sup_{0 \leq s \leq T} |X_s^{t_2, n} - X_s^{t_1, n}| \right]$$

$$\leq L(T+1) C^{1/2} |x-y|. \quad \square$$

Lemma 2: v is $\frac{1}{2}$ Hölder continuous in t independently of x .

Proof: $0 \leq t_1 < t_2 \leq T$,

$$|v(t_1, x) - v(t_2, x)| =$$

$$\left| \mathbb{E} \left[\int_{t_1}^T f(s, X_s^{t_1, n}) ds + g(X_T^{t_1, n}) \right] - \int_{t_2}^T f(s, X_s^{t_2, n}) ds - g(X_T^{t_2, n}) \right|$$

$$\leq \mathbb{E} \left[\int_{t_1}^{t_2} |f(s, X_s^{t_1, n})| ds \right]$$

$$+ \mathbb{E} \left[\int_{t_2}^T |f(s, X_s^{t_1, n}) - f(s, X_s^{t_2, n})| ds \right]$$

$$+ \mathbb{E} \left[|g(X_T^{t_1, n}) - g(X_T^{t_2, n})| \right]$$

$$\leq \|f\|_{\infty} (t_2 - t_1)$$

$$+ L(T+1) \mathbb{E} \left[\sup_{t_2 \leq s \leq T} |X_s^{t_1, n} - X_s^{t_2, n}| \right]$$

$$\leq \|f\|_{\infty} (t_2 - t_1) + L(T+1) C (t_2 - t_1)^{1/2}$$

$$\leq \left(\|f\|_{\infty} T^{1/2} + L(T+1)C \right) (t_2 - t_1)^{1/2}$$

Lemma 3: v is bd by
 $|v(t, x)| \leq (T \|f\|_\infty + \|g\|_\infty)$.

Theo (Dynamic programming) Fix $t \in [0, T]$
 For any stopping time $\tau \in [t, T]$,
 we have

$$v(t, x) = \mathbb{E} \left[\int_t^\tau f(s, X_s^{t, x}) ds + v(\tau, X_\tau^{t, x}) \right]$$

Proof: $f \equiv 0$, $\tau = t_2 \in [t, T]$
 deterministic.

$$\begin{aligned} v(t, x) &= \mathbb{E} \left[g(X_T^{t, x}) \right] \\ &= \mathbb{E} \left[g(X_T^{t_2}, X_{t_2}^{t, x}) \right] \\ &= \mathbb{E} \left[\mathbb{E} \left(g(X_T^{t_2}, X_{t_2}^{t, x}) \mid \mathcal{F}_{t_2} \right) \right] \\ &\stackrel{\text{(Markov prop)}}{\downarrow} \mathbb{E} \left[\mathbb{E} \left(g(X_T^{t_2}, y) \mid \mathcal{F}_{t_2} \right) \right]_{y = X_{t_2}^{t, x}} \\ &= \mathbb{E} \left[v(t_2, X_{t_2}^{t, x}) \right] \end{aligned}$$

• Set $\mathcal{L}\varphi(t, u) =$
 $b(t, u) \cdot \nabla \varphi(t, u) + \frac{1}{2} \text{Tr}(\sigma \sigma^T(t, u) \mathcal{D}^2 \varphi(t, u))$

Theo (Feynman-Kac 1)

Assume that

$$v(t, u) = \mathbb{E} \left[\int_t^T f(s, X_s^{t, u}) ds + g(X_T^{t, u}) \right]$$

is $C^{1,2}$.

Then v solves

$$\begin{cases} \partial_t v(t, u) + \mathcal{L}v(t, u) + f(t, u) = 0 \\ \text{in }]0, T) \times \mathbb{R}^d \\ v(T, u) = g(u) \text{ in } \mathbb{R}^d \end{cases}$$

Ex: $d=1$, $b \equiv 0$, $\sigma \equiv 1$, $f \equiv 0$

$$\begin{cases} dX_s = dW_s \\ X_t = x \end{cases} \Rightarrow X_s = x + W_s - W_t$$

If $v(t, u) = \mathbb{E} \left[g(x + W_T - W_t) \right]$

is $C^{1,2}$, then v solves the

heat eq:

$$\begin{cases} \partial_t v + \frac{1}{2} \partial_{uu} v = 0 \text{ in } (0, T) \times \mathbb{R} \\ v(T, u) = g(u) \text{ in } \mathbb{R}. \end{cases}$$

Proof of F-K formula I:

~~Hyp #~~. $f \equiv 0$, $u \in C_b^{1,2}$ ($\partial_t u, \nabla u$
 Fix $t \in]0, T)$, $h > 0$ small,

use the dynamic programming:

$$u(t, x) = \mathbb{E} \left[u(t+h, X_{t+h}^{t,x}) \right]$$

$$\text{Itô's formula} = \mathbb{E} \left[\cancel{u(t, x)} + \int_t^{t+h} (\partial_t u + \mathcal{L}u)(t, X_s) ds + \int_t^{t+h} \underbrace{\nabla u(t, X_s) \sigma(t, X_s)}_{\text{red line}} dW_s \right]$$

$$0 = \mathbb{E} \left[\int_t^{t+h} (\partial_t u + \mathcal{L}u)(t, X_s) ds \right]$$

Divide by $h > 0$ and let $h \rightarrow 0^-$

then $X_s^{t,x} \rightarrow x$

$$\Rightarrow 0 = (\partial_t u + \mathcal{L}u)(t, x).$$

• General case ($f \neq 0$, $u \in C^{1,2}$).

let $\tau = \inf \{ s \in [t, T] : X_s^{t,x} \notin B(x, 1) \}$.

Then τ is a stopping time (with

$$\tau = T \text{ if } X_s^{t,x} \in B(x, 1) \forall s \in [t, T].$$

For $h > 0$ small, set $\tau_h = \inf \{ t+h, \tau \}$.

DPP \Rightarrow

$$\begin{aligned}
 \cancel{v(t, x)} &= \mathbb{E} \left[\int_t^{\tau_h} f(s, X_s) ds + v(\tau_h, X_{\tau_h}^{t, u}) \right] \\
 &= \mathbb{E} \left[\cancel{v(t, u)} + \int_t^{\tau_h} (\partial_t v + \mathcal{L}v + f)(s, X_s) ds \right. \\
 &\quad \left. + \int_t^{\tau_h} \underbrace{\cancel{\partial v(s, X_s)} \sigma(s, X_s) dW_s}_{\text{bd in } (0, \tau] \times B(x, 1)} \right]
 \end{aligned}$$

$$\begin{aligned}
 \text{So } 0 &= \mathbb{E} \left[\int_t^{\tau_h} (\partial_t v + \mathcal{L}v + f)(s, X_s) ds \right] \\
 (*) \quad 0 &= \mathbb{E} \left[\frac{1}{h} \int_t^{\tau_h} (\partial_t v + \mathcal{L}v + f)(s, X_s) ds \right]
 \end{aligned}$$

$$\xrightarrow{h \rightarrow 0^+} (\partial_t v + \mathcal{L}v + f)(t, u)$$

Req: $\mathbb{P}(\tau_h \neq h) \xrightarrow{h \rightarrow 0^+} 0$

because $\tau_h = \inf\{\tau, t+h\}$
 where $\tau = \inf\{\tau \in [t, T] \mid X_\tau \notin B(x, 1)\}$

As $X_t = x$ and $s \mapsto X_s$ is continuous. So $\tau > t$ a.s.

Coming back to (*):

$$0 = \mathbb{E} \left[\frac{1}{h} \int_t^{t+h} (\partial_t v + \mathcal{L}v + f) ds \mathbb{1}_{\tau_h = t+h} \right]$$

\downarrow a.s.

$$\begin{aligned}
 & + \frac{1}{h} \int_t^{t+h} \underbrace{(\gamma_u + \alpha_u + f)}_{bd} ds \underbrace{\mathbb{1}_{\{\tau \neq t+h\}}}_{\substack{\downarrow \\ \text{a.s.} \\ 0}} \\
 \rightarrow & (\gamma_t + \alpha_t + f)(t, x).
 \end{aligned}$$

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$$\begin{aligned}
 0 & = \mathbb{E} \left[\frac{1}{h} \int_t^{t+h} (\gamma_u + \alpha_u)(s, X_s) ds \right] \\
 & = \mathbb{E} \left[\int_0^1 \underbrace{(\gamma_{t+uh} + \alpha_{t+uh})}_{bd} (t+uh, X_{t+uh}) du \right] \\
 & \xrightarrow{h \rightarrow 0} (\gamma_t + \alpha_t)(t, x)
 \end{aligned}$$

$u = t + uh$
 $\downarrow h \rightarrow 0^+$
 t
 $\downarrow h \rightarrow 0^+$
 $X_t = x$