

- e. Superdifferential = later
- Some classical properties of viscosity solutions

$$(HJ) \quad \nu v + H(x, Dv, D^2v) = 0 \quad \text{in } \mathbb{R}^d$$

- Equivalent definition:

Let $v : \mathbb{R}^d \rightarrow \mathbb{R}$ be continuous.
Then v is a subsolution of (HJ)

\Leftrightarrow for any test function $\varphi \in C^2(\mathbb{R}^d)$
s.t. $v - \varphi$ has local strict maximum
at $x \in \mathbb{R}^d$ with $v(x) = \varphi(x)$, then

$$\nu v(x) + H(x, D\varphi(x), D^2\varphi(x)) \leq 0.$$

(idem for supersolution)

Proof: $\boxed{\Leftarrow}$

Let $\varphi \in C^2(\mathbb{R}^d)$ s.t. $v - \varphi$ has a
max at $x \in \mathbb{R}^d$.

$$\text{Set } \tilde{\varphi}(y) = \varphi(y) + \frac{1}{2} |x-y|^2 + v(x) - \varphi(x).$$

Then $\tilde{\varphi} \in C^2(\mathbb{R}^d)$, $\tilde{\varphi}(x) = v(x)$. and

$$\begin{aligned} v(y) - \tilde{\varphi}(y) &= \underbrace{v(y) - \varphi(y)}_{\leq 0} - \frac{1}{2} |x-y|^2 - v(x) + \varphi(x) \\ &\leq v(x) - \varphi(x) - \frac{1}{2} |x-y|^2 - v(x) + \varphi(x) \\ &< 0 \quad \text{if } y \neq x, \quad \circ \quad y \neq x \end{aligned}$$

$$\Rightarrow \nu v(u) + H(x, D\tilde{\varphi}(u), D^2\tilde{\varphi}(u)) \leq 0$$

$\begin{matrix} \parallel \\ D\tilde{\varphi}(u) \end{matrix} \rightarrow \begin{matrix} \parallel \\ D^2\varphi(u) \end{matrix}$

\hookrightarrow ex 0.

□

Prop (Stability)

- Assume $H_n: \mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ is a sequence of continuous maps, non increasing with respect to the last variable and converges locally uniformly to H .

- Assume $v_n: \mathbb{R}^d \rightarrow \mathbb{R}$ is a seq. of viscosity sub-sol of $\nu v_n + H_n(x, Du_n, D^2v_n) = 0$ and that $v_n \rightarrow v$ locally uniformly. Then v sub-sol of the limit eq
 $\nu v + H(x, Du, D^2v) = 0$.

OK also
for super sol

Sketch of proof: Assume that $\psi - \varphi$ has a strict maximum at some $x \in \mathbb{R}^d$:
 $\begin{matrix} \nearrow \\ \text{local} \end{matrix}$

$$\exists r > 0, \quad \forall y \in B_r(x), \quad \begin{cases} v(y) - \varphi(y) < \\ v(x) - \varphi(x) \end{cases} .$$

Note that $\exists \eta > 0$ s.t.

$$\forall y \in \partial B_r(x)$$

$$v(y) - \varphi(y) \leq -\eta + v(x) - \varphi(x).$$

Then $\exists \eta_0$ large enough s.t. $\forall n \geq n_0$,

$$v_n(y) - \varphi(y) \leq -\eta_{1/2} + v_n(x) - \varphi(x)$$

$\forall y \in \partial B_n(x).$

R.H.S.: $\sup_{B_n(x)} v_n - \varphi = \max_{\overset{\circ}{B}_R(x)} v_n - \varphi$

let x_n point of $\max_{\overset{\circ}{B}_R(x)} v_n - \varphi$. ($x_n \in \overset{\circ}{B}_R(x)$)

Then as v_n visc. subsol

$$\gamma v_n(x_n) + H_n(x_n, Dv_n(x_n), D^2v_n(x_n)) \leq 0.$$

(Exo: $x_n \rightarrow x$)

$$\Rightarrow \gamma v(x) + H(x, Dv(x), D^2v(x)) \leq 0.$$

□

Exo: U is a subsol of

$$\gamma v + H(x, Dv, D^2v) = 0$$

$\Leftrightarrow -U$ is a supersol of

$$\gamma v + \tilde{H}(x, Dv, D^2v) = 0$$

where $\tilde{H}(x, p, A) = -H(x, -p, -A)$.

• Comparison principle:

"Subsolutions are below supersolutions"

Consequence: at most one visc. sol.

Theo: Let $H(x, p, A) =$

$$\sup_{a \in A} \left\{ -f(x, a) - b(x, a) \cdot p - \frac{1}{2} \operatorname{Tr}[\sigma^T(x, a) A] \right\}.$$

where f, b, σ satisfy our standing assumptions.

Let v be a viscosity sub of
 $(HJ) \quad \mathcal{R}w + H(u, Dw, D^2w) = 0$

and v is a viscosity super sol of (HJ)
 and v and u are bounded.

Then $v \leq u$.

(Proof: postponed. - difficult)

Corollary: There exists exactly
 one bd viscosity sol to (HJ) .

Proof: The value function v is
 a bd viscosity sol of (HJ) .

• Assume w is another bd sol.

Then ① v subsol of w super sol +
 v, w bd. By comparison $v \leq w$.

② Exchanging the roles of v and u
 $\Rightarrow v \leq u$

$$\text{So } u = v.$$

□

Ex: $d=1, 2u + |v_x| = 0. \quad (HJ)$

$v=0$ is the bd sol to (HJ)

But $v(x) = -e^{-2x}$ is also a
sol. but not bd..

Uniqueness for Eikonal eq:

Let $G \subset \mathbb{R}^d$ be open bounded

$$(HJ) \left\{ \begin{array}{l} u(x) + \|Du(x)\| = 1 \text{ in } G \\ u(x) = 0 \quad \forall x \in \partial G. \end{array} \right.$$

Superal

Subsol: ① if $u-\varphi$ has \max

at $x \in G \Rightarrow u(x) + |D\varphi(x)| \leq 1$

② $u(x) \leq 0 \quad \forall x \in G.$

(u is continuous on \overline{G})

Theo: (comparison principle)

If u is a subsol of v is a supersol of

\square (HJ) Then $v \leq u$ in \bar{G} .

Sketch of proof: By contradiction:

Assume that $\sup(v - u) =: M > 0$

Doubling of variation: for $\varepsilon > 0$ small

$$M_\varepsilon := \sup_{(x,y) \in \bar{\mathbb{R}} \times \bar{\mathbb{R}}} |u(x) - v(y) - \frac{1}{2\varepsilon} |x-y|^2|.$$

let $x_\varepsilon, y_\varepsilon$ be maximum point.

Ex 0: check $x_\varepsilon - y_\varepsilon \xrightarrow[\varepsilon \rightarrow 0]{} 0$, $u(x_\varepsilon) - v(y_\varepsilon) \rightarrow M_>0$.

\square and for $\varepsilon > 0$ small, $x_\varepsilon, y_\varepsilon \in G$.

• For $y = y_\varepsilon$, then

$$x \mapsto |u(x) - v(y_\varepsilon) - \frac{1}{2\varepsilon} |x-y_\varepsilon|^2|$$

has a max at x_ε . (test function)

$$\infty. \quad \varphi(x) = v(y_\varepsilon) + \frac{1}{2\varepsilon} |x-y_\varepsilon|^2$$

So as v sub ≥ 0 : $D\varphi(x_\varepsilon) = \frac{x_\varepsilon - y_\varepsilon}{\varepsilon}$.

$$(1) \quad u(x_\varepsilon) + \left| \frac{x_\varepsilon - y_\varepsilon}{\varepsilon} \right| \leq 0$$

In the same way, for $x = x_\varepsilon$

$$y \mapsto -u(x_\varepsilon) + v(y) + \frac{1}{2\varepsilon} |x_\varepsilon - y|^2$$

has a min at $y_\varepsilon \in G$

As v superadd

$$(2) \quad v(y_\varepsilon) + \left| -\frac{y_\varepsilon - x_\varepsilon}{\varepsilon} \right| \geq 0.$$

$$(1) - (2) \Rightarrow$$

$$v(x_\varepsilon) - v(y_\varepsilon) \leq 0.$$

$$\begin{matrix} \searrow \\ M > 0 \end{matrix}$$

liminf

