

# The fundamental solution of a nonlinear kinetic Fokker-Planck equation

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# Fundamental solution of a nonlinear kinetic equation

- 1 Introduction
- 2 The mass parameter
- 3 Comparison,  $L^1$ -contraction and consequences
- 4 Scalings and the four-step method

*Joint paper with Giovanni Brigati & Guillaume Carlier*  
*The fundamental solution of a nonlinear kinetic  
Fokker-Planck equation*  
[arXiv: 2603.26650](https://arxiv.org/abs/2603.26650)

# Fundamental solution of a nonlinear kinetic equation

We consider the nonlinear kinetic equation

$$\partial_t f + v \cdot \nabla_x f = \Delta_v f^m \quad (t, x, v) \in \mathbb{R}^+ \times \mathbb{R}^d \times \mathbb{R}^d \quad (\text{NKE})$$

The *pressure* variable

$$P := \frac{m}{1-m} f^{m-1}$$

solves

$$\partial_t P = (1-m) P \Delta_v P - |\nabla_v P|^2 - v \cdot \nabla_x P$$

Special (fundamental) solution: with  $A = \frac{1+d-dm}{3-d+dm}$

$$P_*(t, x, v) = \beta(t) + \frac{(1+A)}{2(1-A)t} \left( \left| v - \frac{x}{(1-A)t} \right|^2 + A \left| \frac{x}{(1-A)t} \right|^2 \right)$$

$$f_*(t, x, v) = \left( \frac{1-m}{m} P_*(t, x, v) \right)_+^{\frac{1}{m-1}}$$

$$m_1 := 1 - \frac{1}{d} < m < 1 \quad \text{or} \quad 1 < m < m_2 := 1 + \frac{1}{d}$$

## Intermediate asymptotics

The *fundamental solution*  $f_*$  governs the large time behaviour of all solutions of (NKE) with initial datum  $f_0$  such that

$$f_0 \in L^1(\mathbb{R}^d \times \mathbb{R}^d), \quad \|f_0\|_{L^1(\mathbb{R}^d \times \mathbb{R}^d)} = 1$$

$$g_{\gamma_1}(x, v - x) \leq f_0(x, v) \leq g_{\gamma_2}(x, v - x)$$

for any  $(x, v) \in \mathbb{R}^d \times \mathbb{R}^d$ , with  $(1 - m)\gamma_2 > (1 - m)\gamma_1 > 0$  and

$$g_\gamma(x, v) := \left( \frac{1-m}{m} \left( \gamma + \frac{1+A}{2} |v|^2 + \frac{1+A}{2} A |x|^2 \right) \right)_+^{\frac{1}{m-1}}$$

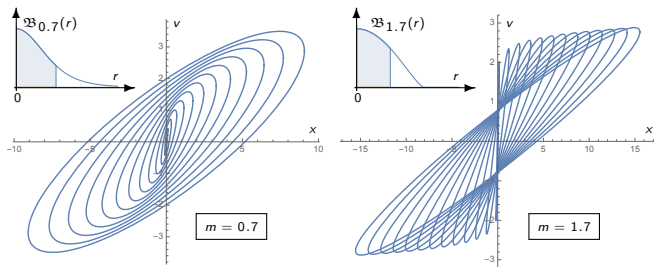
### Theorem

With  $d \geq 1$ ,  $m \in (m_1, 1) \cup (1, m_2)$  and  $1/2 < m < 3/2$  if  $d = 1$ ,

$$\lim_{t \rightarrow +\infty} \|f(t, \cdot, \cdot) - f_*(t, \cdot, \cdot)\|_{L^1(\mathbb{R}^d \times \mathbb{R}^d)} = 0$$

## Level lines on the phase space

The level lines of the *fundamental solution*  $f_\star$  are ellipses, which rotate and expand in the phase space  $\mathbb{R}^d \times \mathbb{R}^d \ni (x, v)$  as  $t$  increases



**Figure:** In dimension  $d = 1$ , the ellipse  $\mathfrak{E}_m(t)$  is represented in the phase space  $\mathbb{R}^d \times \mathbb{R}^d \ni (x; v)$  at times  $t = 0.1, t = 0.6, 1.1 \dots 6.1$  for  $m = 0.7$  (left) and  $m = 1.7$  (right). In the upper left corners, the Barenblatt profiles  $\mathfrak{B}_m(r) := (1 \pm r^2)_+^{1/(m-1)}$  are shown, with shaded areas corresponding to half of the mass. Here  $\pm$  denotes the sign of  $(1 - m)$  and  $r$  is such that  $r^2 = A|x|^2 + |v|^2$ : the function  $f_\star(t, \cdot, \cdot)$  has compact support if  $m > 1$

## Self-similar variables

*Intermediate asymptotics* are replaced by estimates of convergence after a *time-dependent rescaling* based on *self-similar variables*

$$f(t, x, v) = R(t)^{-d(1+A)} g\left(\log R(t), \frac{x}{R(t)}, \frac{v}{R(t)^A} - \frac{x}{R(t)}\right)$$

with initial datum  $g(0, x, v) = g_0(x, v) := f_0(x, v + x)$  and

$$R(t) = (R_0^{1-A} + (1-A)t)^{\frac{1}{1-A}} \quad \text{and} \quad A = \frac{1+d-dm}{3-d+dm}$$

If  $f$  is a solution of (NKE), then  $g$  solves

$$\partial_t g + v \cdot \nabla_x g - Ax \cdot \nabla_v g = \Delta_v g^m + (1+A) \nabla_v \cdot (vg)$$

### Lemma

Let  $d \geq 1$ . Then  $g_\gamma \in L^1(\mathbb{R}^d \times \mathbb{R}^d)$  if and only if  $m \in (m_1, 1) \cup (1, m_2)$ . In that range, (NKE) admits a fundamental solution  $f_\star$  corresponding to a stationary solution  $g_\star := \left(\frac{1-m}{m} (\gamma_\star + \frac{1+A}{2} |v|^2 + \frac{1+A}{2} A |x|^2)\right)_+^{\frac{1}{m-1}}$

# *Mass, contraction and comparison*

- 1 The mass parameter
- 2 Comparison,  $L^1$ -contraction and consequences
- 3 Scalings and the four-step method

# The mass parameter

Let  $f$  be an arbitrary nonnegative function in  $\mathcal{C}(\mathbb{R}^+; L^1(\mathbb{R}^d \times \mathbb{R}^d))$ ,  
 $M > 0$  a real number and

$$f_M(t, x, v) := M f(M^{2\zeta} t, M^\zeta x, M^{-\zeta} v) \text{ with } \zeta := -\frac{1}{4}(1-m)$$

## Lemma

*With the above notation,  $f_M$  solves (NKE) if and only if  $f$  solves (NKE)*

The condition  $\|g_\star\|_{L^1(\mathbb{R}^d \times \mathbb{R}^d)} = 1$  determines  $\gamma = \gamma_\star$  such that

$$\frac{2^d}{(\sqrt{A}(1-A))^d} \left| \frac{1-m}{m} \right|^{\frac{1}{m-1}} \gamma_\star^d \frac{m-m_1}{m-1} \int_{\mathbb{R}^d \times \mathbb{R}^d} (1 \pm |z|^2)_+^{\frac{1}{m-1}} dz = 1$$

# $L^1$ -contraction and Maximum Principle

## Lemma

Let  $d \geq 1$  and  $m \in (m_1, 1) \cup (1, m_2)$ . If  $f_1$  and  $f_2$  solve (NKE) in  $\mathcal{C}(\mathbb{R}^+; L^1(\mathbb{R}^d \times \mathbb{R}^d))$  in the sense of distributions, then  $t \mapsto \iint_{\mathbb{R}^d \times \mathbb{R}^d} (f_2(t, x, v) - f_1(t, x, v))_+ dx dv$  is nonincreasing

Here  $(\cdot)_+$  denotes the positive part

## Corollary

Let  $d \geq 1$  and  $m \in (m_1, 1) \cup (1, m_2)$ . If  $f_1$  and  $f_2 \in \mathcal{C}(\mathbb{R}^+; L^1(\mathbb{R}^d \times \mathbb{R}^d))$  solve (NKE) with initial data  $f_{1,0}$  and  $f_{2,0}$  such that  $f_{1,0} \leq f_{2,0}$  a.e., then  $f_1(t, \cdot, \cdot) \leq f_2(t, \cdot, \cdot)$  a.e. for all  $t \in \mathbb{R}^+$

# Uniqueness and mass conservation

Reminder:  $g_\gamma := \left( \frac{1-m}{m} \left( \gamma + \frac{1+A}{2} |v|^2 + \frac{1+A}{2} A |x|^2 \right) \right)^{\frac{1}{m-1}}$

## Proposition

(NKE) has at most one solution  $f$  in  $C(\mathbb{R}^+; L^1(\mathbb{R}^d \times \mathbb{R}^d))$  with initial datum  $f_0$  if  $f$  and  $g$  are related by the self-similar change of variables and

$$g_{\gamma_1}(x, v) \leq g(t, x, v) \leq g_{\gamma_2}(x, v)$$

Moreover  $\|f(t, \cdot, \cdot)\|_{L^1(\mathbb{R}^d \times \mathbb{R}^d)} = \|f_0\|_{L^1(\mathbb{R}^d \times \mathbb{R}^d)}$  for any  $t \geq 0$

Any solution  $f \in C(\mathbb{R}^+; L^1(\mathbb{R}^d \times \mathbb{R}^d))$  of (NKE) can be rewritten by solving the characteristics of the free transport operator as

$$\partial_t h = (\Delta_v - 2t \nabla_x \cdot \nabla_v + t^2 \Delta_x) h^m$$

where  $h(t, x, v) = f(t, x + tv, v)$

# Existence

## Proposition

Under our assumptions, (NKE) has a solution  $g$  in  $C(\mathbb{R}^+; L^1(\mathbb{R}^d \times \mathbb{R}^d))$

To  $g(t, x, v) = G(\sqrt{A} t, A^{1/4} x, A^{-1/4} v)$  such that

$$\partial_t G + v \cdot \nabla_x G - x \cdot \nabla_v G = \frac{1}{A} \Delta_v G^m + \frac{1+A}{\sqrt{A}} \nabla_v \cdot (v G)$$

A splitting scheme with  $G(t, \cdot) = S_n(t) G_0(\cdot)$ ,  $0 \leq t \leq \frac{1}{n}$ ,  $n \in \mathbb{N} \setminus \{0\}$

$$\begin{aligned} \frac{\partial G}{\partial t} &= 2 \left( \frac{1}{A} \Delta_v G^m + \frac{1+A}{\sqrt{A}} \nabla_v \cdot (v G) \right) & \text{if } 0 \leq t \leq \frac{1}{2n}, \\ \frac{\partial G}{\partial t} + 2(v \cdot \nabla_x G - x \cdot \nabla_v G) &= 0 & \text{if } \frac{1}{2n} \leq t \leq \frac{1}{n} \end{aligned}$$

- extend with  $(k, t) \in \mathbb{N} \times [0, 1/n]$  by  $G_n(t + \frac{k}{n}, x, v) = S_n(t) G_n(\frac{k}{n}, x, v)$
- conclude with Arzelà-Ascoli

## Scalings and the four-step method

A possible strategy for proving Theorem 1 is to adapt the *four-step method* using

$$f_\star(t, x, v) = t^{-d \frac{1+A}{1-A}} f_\star \left( 1, t^{-\frac{1}{1-A}} x, t^{-\frac{A}{1-A}} v \right)$$

for all  $t > 0$ , based on the  $L^1$ -preserving scale invariance  $f \mapsto f_\lambda$  with

$$f_\lambda(t, x, v) := \lambda^4 f \left( \lambda^{2(m-m_1)} t, \lambda^{m-m_3} x, \lambda^{m_2-m} v \right)$$

with  $m_1 = 1 - 1/d$  and  $m_2 = 1 + 1/d$  and  $m_3 := 1 - 3/d$

However regularity properties and hypoelliptic techniques are so far missing, which would be needed for compactness properties,

in order to identify  $f_\star$  as the unique possible limit as  $t \rightarrow +\infty$

Can we relax the condition on the behaviour of  $f_0 \in L^\infty(\mathbb{R}^d \times \mathbb{R}^d)$  as  $|x|^2 + |v|^2 \rightarrow \infty$  ?

# Entropy methods in self-similar variables

- Moments and relative entropy estimates
- Convergence in  $L^1$  and intermediate asymptotics
- Decay rates of the spatial density

*Joint paper with Giovanni Brigati & Guillaume Carlier*  
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arXiv: 2603.26650

## Moments and relative entropy estimates

$g_\star$  has finite mass for any  $m > m_1 = \frac{d-1}{d}$

$g_\star$  admits a moment  $(|x|^2 + |v|^2)$  only if  $m > \tilde{m}_1 = \frac{d}{d+1} > m_1$

The missing range is covered by considering the difference with  $g_\star$

### Lemma

Under our assumptions, the solution  $g$  is such that

$$\sup_{t \geq 0} \iint_{\mathbb{R}^d \times \mathbb{R}^d} (|x|^2 + |v|^2) |g(t, x, v) - g_\star(x, v)| dx dv < \infty$$

As  $(|x|^2 + |v|^2) \rightarrow \infty$ , the right-hand side is integrable iff  $m > m_1$

$$|g(t, x, v) - g_\star(x, v)| \leq g_{\gamma_2}(x, v) - g_{\gamma_1}(x, v) = O\left((|x|^2 + |v|^2)^{\frac{2-m}{m-1}}\right)$$

Relative entropy functional as in [Newman1984], [Ralston1984]

$$\mathcal{E}[g] := \mathcal{H}[g] - \mathcal{H}[g_\star]$$

with  $\mathcal{H}[g] := \iint_{\mathbb{R}^d \times \mathbb{R}^d} \left( \frac{g^m}{m-1} + \frac{1+A}{2} (|v|^2 + A|x|^2) g \right) dx dv$

## Relative entropy production

We shall write  $\mathcal{E}(t) = \mathcal{E}[g(t, \cdot, \cdot)]$

If  $m < 1$ , notice that

$$\mathcal{E}[g] = \frac{1}{m-1} \iint_{\mathbb{R}^d \times \mathbb{R}^d} (g^m - g_\star^m - m g_\star^{m-1} (g - g_\star)) dx dv$$

In the range  $m_1 < m \leq \tilde{m}_1$ , the relative entropy can be understood as the functional acting on  $w = g/g_\star$  given by

$$w \mapsto \frac{1}{m-1} \iint_{\mathbb{R}^d \times \mathbb{R}^d} (w^m - 1 - m(w-1)) g_\star^m dx dv$$

Cf. [BBDGV, 2009] for details.

### Lemma

If  $g$  is a solution, then

$$\frac{d}{dt} \mathcal{E}(t) = - \iint_{\mathbb{R}^d \times \mathbb{R}^d} g |\nabla_v Q - \nabla_v Q_\star|^2 dx dv$$

with pressure variables  $Q := \frac{m}{1-m} g^{m-1}$  and  $Q_\star := \frac{m}{1-m} g_\star^{m-1}$

# Convergence in $L^1$ ? Sketch of the proof (preliminaries)

The proof of Theorem 1 has to be completed by identifying the limit as  $t \rightarrow +\infty$  of the solution  $g$ : we have to prove that

$$\lim_{t \rightarrow +\infty} \|g(t, \cdot, \cdot) - g_\star\|_{L^1(\mathbb{R}^d \times \mathbb{R}^d)} = 0 \quad \text{and} \quad \lim_{t \rightarrow +\infty} \mathcal{E}(t) = 0$$

if  $g$  solves the equation

$$\lim_{t \rightarrow +\infty} \int_t^{+\infty} \iint_{\mathbb{R}^d \times \mathbb{R}^d} g |\nabla_v Q - \nabla_v Q_\star|^2 dx dv ds = 0$$

Let us define the *spatial density*  $\rho_g(t, x) := \int_{\mathbb{R}^d} g(t, x, v) dv$  and the corresponding *local equilibrium* by

$$\tilde{g}(t, x, v) := \left( \mu(t, x) + \frac{1-m}{2m} (1+A) |v|^2 \right)_+^{\frac{1}{m-1}}$$

where  $\mu(\tau, x) = \mu_1 (\rho_g(\tau, x))^{k-1}$ ,  $\frac{1}{k-1} = \frac{d}{2} + \frac{1}{m-1}$ , is found by inverting

$$\rho_g(t, x) = \int_{\mathbb{R}^d} \left( \mu(t, x) + \frac{1-m}{2m} (1+A) |v|^2 \right)_+^{\frac{1}{m-1}} dv$$

## Sketch of the proof (continued)

Gagliardo-Nirenberg + generalized Csiszár-Kullback inequalities

$$\int_{\mathbb{R}^d} g |\nabla_v Q - \nabla_v Q_\star|^2 dv \geq C \frac{\|g(t, x, \cdot) - \tilde{g}(t, x, \cdot)\|_{L^1(\mathbb{R}^d)}^2}{(\rho_g(t, x))^{2-k}}$$

With  $|g - \tilde{g}| = \rho_g^{1-k/2} \cdot |g - \tilde{g}| / \rho_g^{1-k/2}$  + Cauchy-Schwarz, we obtain

$$\lim_{t \rightarrow \infty} \int_t^{t+1} \|g(s, \cdot, \cdot) - \tilde{g}(s, \cdot, \cdot)\|_{L^1(\mathbb{R}^d \times \mathbb{R}^d)}^2 ds = 0$$

*Convergence in  $L^1$  to a stationary solution ?*

Assume  $m < 1$  and take any sequence  $(t_n)_{n \in \mathbb{N}}$  such that  $0 < t_n \rightarrow \infty$ ,

set  $g_n(t, x, v) := g(t_n + t, x, v)$ ,  $\tilde{g}_n(t, x, v) := \tilde{g}(t_n + t, x, v)$ ,  $\rho_n := \rho_{g_n}$

Averaging lemmas + boundedness of  $\rho_n^R(t, x) := \int_{\mathbb{R}^d} g_n(t, x, v) \psi_R(v) dv$

in  $H^{1/4}((0, 1) \times \mathbb{R}^d)$  + a.e. and  $L^1((0, 1) \times \mathbb{R}^d)$  convergence of  $(\rho_n)_{n \in \mathbb{N}}$

to some limit  $\rho_\infty$ : the limit  $g_\infty = \tilde{g}_\infty = g_\star$  solves

$$\partial_t g_\infty + v \cdot \nabla_x g_\infty - A x \cdot \nabla_v g_\infty = 0$$

## Intermediate asymptotics in various norms

*The convergence is not limited to  $L^1$*

By Hölder interpolation: general *intermediate asymptotics*

### Corollary

*Under our assumptions, if  $f$  solves (NKE) with initial datum  $f_0$  and  $p \in [1, \infty)$ , then*

$$\lim_{t \rightarrow +\infty} t^{d \frac{p-1}{p} \frac{1+A}{1-A}} \|f(t, x, v) - f_*(t, x, v)\|_{L^p(\mathbb{R}^d \times \mathbb{R}^d)} = 0$$

# *Consequences, linearization and formal results*

- Original variables: decay of the spatial density
- Formal diffusion limit
- Scalings, translations and Galilean invariance
- Linearization, eigenfunctions and asymptotic rates

## A classical estimate on the spatial density

Here we consider the *spatial density*  $\rho_f(t, x) = \int_{\mathbb{R}^d} f(t, x, v) dv$  and assume  $m > \tilde{m}_1$  (finite moments).

*Decay of the spatial density in original variables ?*

### Lemma

If  $g \in L^1_+(\mathbb{R}^d \times \mathbb{R}^d, |v|^2 dx dv) \cap L^\infty(\mathbb{R}^d \times \mathbb{R}^d, dx dv)$ , then we have

$$\|\rho_g\|_{L^{1+\frac{2}{d}}(\mathbb{R}^d)} \leq C_d \|g\|_{L^\infty(\mathbb{R}^d \times \mathbb{R}^d)}^{\frac{2}{d+2}} \left( \iint_{\mathbb{R}^d \times \mathbb{R}^d} |v|^2 g(x, v) dx dv \right)^{\frac{d}{d+2}}$$

with  $C_d := 2^{d/(d+2)} \frac{d+2}{2d} |\mathbb{S}^{d-1}|^{2/(d+2)}$

*Proof.* Notice  $\rho_g(x) \leq |\mathbb{S}^{d-1}| \|g\|_{L^\infty(\mathbb{R}^d \times \mathbb{R}^d)} \frac{R^d}{d} + \frac{1}{R^2} \int_{\mathbb{R}^d} |v|^2 g(x, v) dv$

- Minimize the r.h.s. on  $R > 0$
- Take the power  $(d+2)/d$  of both sides of the estimate
- Integrate w.r.t.  $x$

## Fast diffusion case: kinetic energy

• Fast diffusion case  $m < 1$ . Take  $\gamma = \gamma_\star \iff \iint_{\mathbb{R}^d \times \mathbb{R}^d} g_\star \, dx \, dv = 1$   
 $\mathcal{E}[g] = Z_m \iint_{\mathbb{R}^d \times \mathbb{R}^d} \phi(g/g_\star) g_\star^m \, dx \, dv$  with

$$\phi(s) := \frac{Z_m^{-1}}{m-1} (s^m - 1 - m(s-1)), \quad Z_m = \iint_{\mathbb{R}^d \times \mathbb{R}^d} g_\star^m \, dx \, dv$$

The function  $\phi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$  is invertible, with generalized inverse  $\psi$

### Lemma (Jensen's inequality)

If  $m \in (\tilde{m}_1, 1)$ , then we have

$$(1+A) \frac{1-m}{2m} \iint_{\mathbb{R}^d \times \mathbb{R}^d} |v|^2 g \, dx \, dv \leq Z_m \psi(Z_m^{-1} \mathcal{E}[g])$$

for any  $g \in L^1_+(\mathbb{R}^d \times \mathbb{R}^d, (1+|v|^2) \, dx \, dv) \cap L^m(\mathbb{R}^d \times \mathbb{R}^d, dx \, dv)$

• Porous medium case  $m < 1$  is simpler

$$\frac{1}{2} (1+A) \iint_{\mathbb{R}^d \times \mathbb{R}^d} |v|^2 g \, dx \, dv \leq \mathcal{E}[g] + \mathcal{H}[g_\star]$$

## Decay rates of the spatial density

If  $g$  is a solution, we learn that  $\|\rho_g(t, \cdot)\|_{L^{1+2/d}(\mathbb{R}^d)}$  is uniformly bounded in terms of  $g_0$

### Corollary

*Under our assumptions, if  $f$  is a solution of (NKE) with  $f_0 \in L^1_+(\mathbb{R}^d \times \mathbb{R}^d, (|x|^2 + |v|^2) dx dv) \cap L^\infty(\mathbb{R}^d \times \mathbb{R}^d)$ , then for any  $t > 0$ , we have*

$$\|\rho_f(t, \cdot)\|_{L^{1+\frac{2}{d}}(\mathbb{R}^d)} \leq C[f_0] (1 + (1 - A)t)^{-\frac{3-d+dm}{(d+2)(m-m_1)}}$$

*for some explicit constant  $C[f_0]$*

## Formal diffusion limit / overdamped regime

• With  $\varepsilon \rightarrow 0$  and  $2(dm - d + 1)\eta = 3$ ,

$$f(t, x, v) = \left( \frac{\varepsilon^{2\eta}}{R(\varepsilon t)} \right)^d h_\varepsilon \left( \varepsilon^2 \tau(\varepsilon t), \varepsilon^{\eta+1} x, \frac{\varepsilon^{\eta-1} v}{R(\varepsilon t)} \right)$$

$$R(s) = (1 + s/\alpha)^\alpha \quad \text{with } 1/\alpha = dm - d + 2 = d(m - m_c)$$

so that  $(\tau, x, v) \mapsto h_\varepsilon(\tau, x, v)$  solves

$$\varepsilon \frac{d\tau}{ds}(s) \partial_\tau h_\varepsilon + R(s) v \cdot \nabla_x h_\varepsilon = \frac{\sigma(s)}{\varepsilon} (\Delta_v h_\varepsilon^m + \nabla_v \cdot (v h_\varepsilon))$$

$\sigma(s) := (1 + s/\alpha)^{-1}$ ,  $\tau = \tau(s)$  to be chosen, and  $s = \varepsilon t$

• Formal *Hilbert expansion*

$$h_\varepsilon(\tau, x, v) \approx H(\tau, x, v) := \left( \mu(\tau, x) + \frac{1-m}{2m} |v|^2 \right)_+^{\frac{1}{m-1}}$$

$$\text{where } \rho(\tau, x) = \int_{\mathbb{R}^d} \left( \mu(\tau, x) + \frac{1-m}{2m} |v|^2 \right)_+^{\frac{1}{m-1}} dv = \left( \frac{\mu(\tau, x)}{\mu_1} \right)^{\frac{d}{2} + \frac{1}{m-1}}$$

$$\mu(\tau, x) = \mu_1 (\rho(\tau, x))^{k-1}, \quad k = 1 + 2\alpha(m-1)$$

local mass conservation :  $\rho_\varepsilon(\tau, x) := \int_{\mathbb{R}^d} h_\varepsilon(\tau, x, v) dv$  solves

$$\frac{1}{R} \frac{d\tau}{ds} \partial_\tau \rho_\varepsilon + \nabla_x \cdot j_\varepsilon = 0$$

flux  $j_\varepsilon(\tau, x) := \frac{1}{\varepsilon} \int_{\mathbb{R}^d} v h_\varepsilon(\tau, x, v) dv$

$$\frac{\varepsilon}{R} \frac{d\tau}{ds} \partial_\tau j_\varepsilon + \nabla_x \cdot \int_{\mathbb{R}^d} v \otimes v h_\varepsilon(\tau, x, v) dv = -\frac{\sigma}{R} j_\varepsilon$$

Standard heuristics apply: we drop the  $O(\varepsilon)$  term

$$-\frac{\sigma(s)}{R(s)} j_\varepsilon(\tau, x) \approx \nabla_x \cdot \int_{\mathbb{R}^d} v \otimes v H(\tau, x, v) dv = \nu_1 \nabla_x \cdot (\rho(\tau, x)^k)$$

for some explicit numerical constant  $\nu_1 > 0$

•  $\rho_\varepsilon \approx \rho$  solves the nonlinear diffusion equation

$$\partial_\tau \rho = \Delta_x \rho^k \quad \text{where} \quad \frac{1}{k-1} = \frac{1}{m-1} + \frac{d}{2}$$

in the limit as  $\varepsilon \rightarrow 0$  if we choose the time scale  $s \mapsto \tau(s)$  such that

$$\frac{d\tau}{ds} = \nu_1 \frac{R(s)^2}{\sigma(s)}$$

with the condition  $\tau(0) = 0$ , *i.e.*,

$$\tau(t) = \frac{\alpha \nu_1}{2(1+\alpha)} \left( (1 + t/\alpha)^{2(1+\alpha)} - 1 \right)$$

• *Self-similar Barenblatt-Pattle solution*, with  $1/\beta = d(k-1) + 2$

$$\rho(\tau, x) = (\tau/\beta)^{-d} \rho_\star((\tau/\beta)^{-\beta} x)$$

▷ Assuming that  $\alpha$  is positive, that is,  $m > m_c$ , we notice that  $k-1$  and  $m-1$  have the same sign because  $k-1 = 2\alpha(m-1)$

▷ This formal computation requires at least a second moment

$$m > \tilde{m}_1 = d/(d+1) \iff k > d/(d+2)$$

# From invariances to linearization and asymptotic modes

*A preliminary question: does the notion of fundamental solution make sense for non-centred initial data ?*

Non-centred Dirac distributions as initial data...

- Translations  $(x, v) \mapsto (x - x_0, v)$
- Galilean transformations  $(t, x, v) \mapsto (x - t v_0, v - v_0)$

## Proposition

*The function  $t \mapsto f_*(t, x - x_0 - t v_0, v - v_0)$  solves (NKE) with measure initial datum  $\delta(x - x_0, v - v_0)$  for any  $(x_0, v_0) \in \mathbb{R}^d \times \mathbb{R}^d$*

In self-similar variables, these transformations give rise to specific asymptotic behaviours of the solutions.

*Can we identify asymptotic behaviours through modes of the linearized evolution operator using the invariances of the equation ?*

## Linearized evolution operator and dissipation

Take  $g(t, x, v) = g_*(x, v) + \varepsilon h(t, x, v)$  and  $\varepsilon \rightarrow 0$

$$\partial_t h = \mathcal{L} h$$

where the *linearized operator*  $\mathcal{L}$  is defined by

$$\mathcal{L} h := m \Delta_v (g_*^{m-1} h) + (1 + A) \nabla_v \cdot (v h) - v \cdot \nabla_x h + A x \cdot \nabla_v h$$

We assume that  $\|g_*\|_{L^1(\mathbb{R}^d \times \mathbb{R}^d)} = 1$  and recall that

$$m (g_*(x, v))^{m-1} := \left( (1 - m) \left( \gamma_* + \frac{1+A}{2} |v|^2 + \frac{1+A}{2} A |x|^2 \right) \right)_+$$

▷ *Accretivity*

$$\frac{d}{dt} \iint_{\mathbb{R}^d \times \mathbb{R}^d} |h|^2 g_*^{m-2} dx dv = -2m \iint_{\mathbb{R}^d \times \mathbb{R}^d} g_* |\nabla_v (g_*^{m-2} h)|^2 dx dv$$

▷ The case  $m > 1$  raises various difficulties due to the compactness of the support of  $g_*$  and is omitted here

# Kernel

## Lemma

Let  $d \geq 1$  and  $m \in (m_1, 1)$

$$\text{Spec}(\mathcal{L}) \subset \{\lambda \in \mathbb{C} : \text{Re}(\lambda) \leq 0\}$$

and the kernel of  $\mathcal{L}$  is generated by  $h_0 := g_\star^{2-m}$

▷ Hint: take a derivative with respect to the mass parameter  $\gamma$  of the solution

$$g_\gamma(x, v) := \left( \frac{1-m}{m} \left( \gamma + \frac{1+A}{2} |v|^2 + \frac{1+A}{2} A |x|^2 \right) \right)_+^{\frac{1}{m-1}}$$

of the stationary equation

$$v \cdot \nabla_x g - A x \cdot \nabla_v g = \Delta_v g^m + (1+A) \nabla_v \cdot (v g) = 0$$

We can identify real eigenvalues of  $(-\mathcal{L})$  by constructing special solutions based on the invariances of (NKE) such that  $\mathcal{L}h + \lambda h = 0$  and

$$g(t, x, v) - g_*(x, v) = e^{-\lambda t} h(x, v) + o(e^{-\lambda t}) \quad \text{as } t \rightarrow +\infty$$

• *A mode based on scaling.* Take  $f_0(x, v) = f_*(t_0, x, v)$  with  $t_0 > 0$

$$h_1(x, v) = \frac{B}{m} (\gamma_* + (B + AC)|v|^2 + Cx \cdot v + A(B - C)|x|^2) h_0(x, v)$$

with  $B = (1 + A)/2$ ,  $1/C = d(1 - m)$  and eigenvalue  $\lambda_1 = 1 - A$

• *A mode based on translations with respect to  $v$  in the phase space*

$$\lambda_2 = A \text{ and } h_{2,i}(x, v) := (v_i - x_i) h_0(x, v)$$

• *A mode based on translations with respect to  $x$  in the phase space*

$$\lambda_3 = 1 \text{ and } h_{3,i}(x, v) := (v_i - Ax_i) h_0(x, v)$$

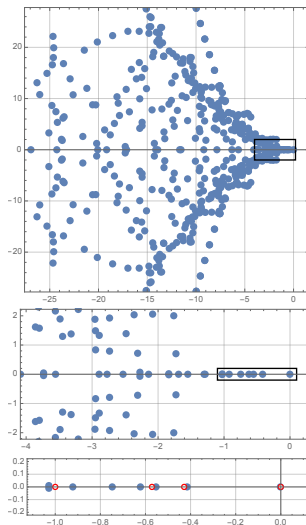
▷ *Conjecture.* For some values of  $m$ ,  $\mathcal{L}$  is sectorial and

$$\text{Spec}(\mathcal{L}) \setminus \{0\} \subset \{\lambda \in \mathbb{C} : \text{Re}(\lambda) \leq -\min\{A, 1 - A\}\}$$

▷ Simpler questions:  $\sup \{\text{Re}(\lambda) : \lambda \in \text{Spec}(\mathcal{L}) \setminus \{0\}\} < 0$ ? Is there some  $\lambda_* > 0$  such that  $\limsup_{t \rightarrow +\infty} e^{\lambda_* t} \mathcal{E}(t) < +\infty$ ? Which space?

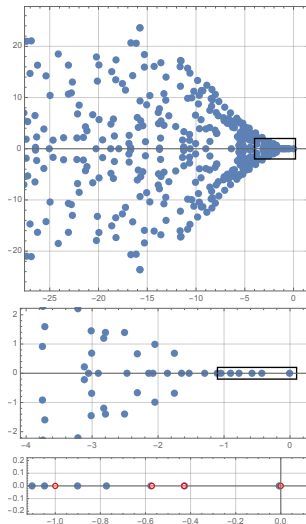
# Dirichlet BC in the rectangle $[-18, 18] \times [-28, 28]$

$m = 0.8, d = 1$



# Dirichlet BC in the ellipse with same volume

$$m = 0.8, d = 1$$



# Further results

- Gradient flows
- Existence and diffusion limits

# *Nonlinear kinetic FokkerPlanck equations as gradient flows of the free energy*

*Joint paper with Giovanni Brigati, Guillaume Carlier & Filippo  
Quattrocchi*

*Nonlinear kinetic Fokker-Planck equations as gradient flows  
of the free energy*  
arXiv: 2606.16315

## Nonlinear kinetic Fokker–Planck equation

Nonlinear kinetic Fokker–Planck equation ( $m > 1$ , porous medium case only)

$$\partial_t f + v \cdot \nabla_x f = \nabla_v \cdot (f (\nabla_v P_m(f) + v)) \quad (\text{kFP})$$

time  $t \geq 0$ , phase space  $\Gamma := \mathbb{R}^d \times \mathbb{R}^d \ni (x, v)$ , pressure variable  $P_m(f)$

$$P_m(f) := \frac{m}{m-1} f^{m-1}$$

$P_1(f) := \log f$  (case  $m = 1$ ): linear Vlasov–Fokker–Planck equation corresponding to the second-order Langevin stochastic equation

*Free energy and generalized Fisher information*

$$\mathcal{F}_m(f) := \iint_{\Gamma} \left( \frac{1}{m} P_m(f) + \frac{1}{2} |v|^2 \right) f \, dx \, dv$$

$$\mathcal{I}_m(f) := \iint_{\Gamma} |\nabla_v P_m(f) + v|^2 f \, dx \, dv$$

are such that, for smooth solution with sufficient decay properties,

$$\frac{d}{dt} \mathcal{F}_m(f(t, \cdot, \cdot)) = -\mathcal{I}_m(f)$$

# Transport by Vlasov, discrepancy and speed

Newton's equations associated to the force field  $F_t(x, v)$

$$x'(t) = v(t), \quad v'(t) = F_t(x(t), v(t))$$

Vlasov equation

$$\partial_t \mu_t + v \cdot \nabla_x \mu_t + \nabla_v \cdot (F_t \mu_t) = 0 \quad \text{in } \mathcal{D}'((0, T) \times \Gamma) \quad (\text{V})$$

$\mathcal{P}_2(\Gamma)$ : set of probability measures  $\mu$  with  $\iint_{\Gamma} (|x|^2 + |v|^2) d\mu < \infty$   
*Discrepancy* between  $\mu$  and  $\nu \in \mathcal{P}_2(\Gamma)$

$$d_T^2(\mu, \nu) := \inf_{(\mu_t, F_t)_{t \in [0, T]}} T \int_0^T \|F_t\|_{L^2(\mu_t)}^2 dt, \quad \mu_0 = \mu, \quad \mu_T = \nu$$

[Brigati, Maas, Quattrocchi] Optimisers are  $d_T$ -regular curves of measures  $(\mu_t)_t$  and one can define a *speed* by

$$|\mu'_t|_d := \lim_{h \rightarrow 0_+} \frac{d_h(\mu_t, \mu_{t+h})}{h}$$

## Chain rule for the free energy and gradient flow

For a smooth function  $f$  of  $(V)$

$$\nabla_v \cdot (f \nabla_v P_m(f)) = \Delta_v f^m, \quad \sqrt{f} \nabla_v P_m(f) = \frac{m}{m-1/2} \nabla_v (f^{m-1/2})$$

$$\mathcal{I}_m(f) = \iint_{\Gamma} \left( \left( \frac{2m}{2m-1} \right)^2 |\nabla_v (f^{m-1/2})|^2 + |v|^2 f - 2d f^m \right) dx dv$$

Weak solutions  $0 \leq f \in L^1_{\text{loc}}(\mathbb{R}^+; L^1(1 + |v|^2, \Gamma)) \cap L^m_{\text{loc}}(\mathbb{R}^+; L^m(\Gamma))$

### Theorem

Let  $m \in [1, 3/2]$  and  $T > 0$ . If  $\mu_t = f(t, \cdot, \cdot)$  solves  $(V)$  in  $\mathcal{P}_2(\Gamma)$  with  $\int_0^T (\mathcal{F}_m(\mu_t) + \mathcal{I}_m(\mu_t)) dt + \int_0^T \|F_t\|_{L^2(\mu_t)}^2 dt < \infty$ , for  $0 < a < b < T$  a.e.

$$\begin{aligned} \mathcal{F}_m(\mu_b) - \mathcal{F}_m(\mu_a) &= \int_a^b \iint_{\Gamma} F_t \cdot (\nabla_v P_m(\mu_t) + v) \mu_t dx dv dt \\ &\geq -\frac{1}{2} \int_a^b (|\mu'_t|_d^2 + \mathcal{I}_m(\mu_t)) dt \end{aligned}$$

with equality iff  $f$  solves  $(kFP)$  on  $[0, T]$ , in which case  $|\mu'_t|_d = \mathcal{I}_m(\mu_t)$

 (kFP) is the gradient flow of the free energy for our topology

# Minimising-movement scheme and maximal dissipation

A JKO type scheme  $\mu_0^{(h)} = \mu_0 \in \mathcal{P}_2(\Gamma)$  with  $\mathcal{F}_m(\mu_0) < \infty$

$$\begin{aligned} \mu_0^{(h)} &= \mu_0 \in \mathcal{P}_2(\Gamma) \quad \text{with} \quad \mathcal{F}_m(\mu_0) < \infty \\ \mu_{k+1}^{(h)} &\in \arg \min_{\nu \in \mathcal{P}_2(\Gamma)} \left( \mathcal{F}_m(\nu) + \frac{1}{2h} d_h^2(\mu_k^{(h)}, \nu) \right) \end{aligned} \quad (\text{JKO})$$

Piecewise constant interpolation:  $\mu_t^{(h)}$

## Theorem

Let  $m \geq 1$

- (JKO) is well-posed for any  $h \in (0, 1)$  and  $k \in \mathbb{N}$
- $(\mu_t^{(h)})_h$  relatively compact in  $L_{\text{loc}}^1(\mathbb{R}^+; L^1(\Gamma))$
- Up to the extraction of a sequence, any limit  $\mu = \lim_{h \rightarrow 0_+} \mu^{(h)}$  solves (kFP) in  $\mathcal{D}'(\mathbb{R}^+ \times \Gamma)$  with initial datum  $\mu_0$

# *Existence and diffusion limits*

*Joint paper with Emeric Bouin & Antoine Mellet*  
***Nonlinear kinetic Fokker-Planck equations: existence and  
diffusion limits***  
(work in progress)

# Nonlinear kinetic Fokker–Planck equation: existence

$$\frac{\partial f}{\partial t} + v \cdot \nabla_x f = \Delta_v f^m + \nabla_v \cdot (v f) \quad \text{with } t > 0, x \in \Omega, v \in \mathbb{R}^d$$

Moments and the free energy functional

$$\mathcal{M}_{a,b}[f] := \iint_{\Omega \times \mathbb{R}^d} (|x|^a + |v|^b) f_{\text{in}}(x, v) dx dv$$

$$\mathcal{F}[f] := \iint_{\Omega \times \mathbb{R}^d} \left( \frac{f^m}{m-1} + \frac{|v|^2}{2} f \right) dx dv$$

$$m_c := (d-2)/d, m_0 := d/(d+2) \text{ and } m_1 := (d-1)/d$$

## Theorem

Let  $\Omega = \mathbb{T}^d$  or  $\mathbb{R}^d$  with  $d \geq 1$  and assume that  $m \in (m_c, 1) \cup (1, +\infty)$ . For any initial condition  $f_{\text{in}} \in L^1_+ \cap L^\infty(\Omega \times \mathbb{R}^d)$  such that  $\mathcal{M}_{a,b}[f_{\text{in}}]$  is finite for some specific  $a$  and  $b$ , Equation (kFP) has a unique solution  $f \in L^\infty_{\text{loc}}(\mathbb{R}^+; L^1 \cap L^\infty(\Omega \times \mathbb{R}^d))$  with  $\nabla_v f^{q/2} \in L^2_{\text{loc}}(\mathbb{R}^+ \times \Omega \times \mathbb{R}^d)$  for all  $q > m$ . Moreover, if  $m > m_0$ , the solution  $f$  satisfies the entropy dissipation inequality

$$\mathcal{F}[f(t)] + \int_0^t \iint_{\Omega \times \mathbb{R}^d} f \left| v + \frac{m}{m-1} \nabla_v f^{m-1} \right|^2 dx dv dt \leq \mathcal{F}[f_{\text{in}}]$$

# Diffusion limit

$$\varepsilon^2 \frac{\partial f}{\partial t} + \varepsilon v \cdot \nabla_x f = \Delta_v f^m + \nabla_v \cdot (v f) \quad \text{with } t > 0, x \in \Omega, v \in \mathbb{R}^d$$

... limit as  $\varepsilon \rightarrow 0_+$  ? Local equilibrium with spatial density  $\rho$  (kFP $_\varepsilon$ )

$$G[\rho](v) := \left( \mu_1 \rho^{k-1} - \frac{m-1}{2m} |v|^2 \right)_+^{\frac{1}{m-1}}$$

## Theorem

Let  $\Omega = \mathbb{T}^d$  or  $\mathbb{R}^d$  with  $d \geq 1$  and assume that  $m \in (m_1, 1) \cup (1, +\infty)$ . Let  $f_{\text{in}} \in L^1(\Omega \times \mathbb{R}^d)$  be such that  $\mathcal{F}[f_{\text{in}}]$  is finite and  $0 \leq f_{\text{in}} \leq G[M]$  a.e. for some constant  $M > 0$  and, if  $\Omega = \mathbb{R}^d$ ,  $\mathcal{M}_{a,0}[f_{\text{in}}]$  is finite for some  $a \in (0, 1)$  if  $m < 1$  and  $a = 2$  if  $m > 1$ . For all  $T > 0$ , the solution  $f_\varepsilon$  to (kFP $_\varepsilon$ ) with initial condition  $f_{\text{in}}$  converges strongly in  $L^1((0, T) \times \Omega \times \mathbb{R}^d)$  to  $G[\rho]$  and  $\rho_\varepsilon := \int_{\mathbb{R}^d} f_\varepsilon(\cdot, \cdot, v) dv$  converges strongly in  $L^1((0, T) \times \Omega)$  to the solution  $\rho$  to

$$\partial_t \rho = \nu_1 \Delta \rho^k \quad \text{in } [0, T] \times \Omega \quad \text{where} \quad \frac{1}{k-1} = \frac{1}{m-1} + \frac{d}{2}$$

with initial condition  $\rho_{\text{in}} = \int_{\mathbb{R}^d} f_{\text{in}}(\cdot, v) dv$

These slides can be found at

<http://www.ceremade.dauphine.fr/~dolbeaul/Lectures/>  
▷ Lectures

The papers can be found at

<http://www.ceremade.dauphine.fr/~dolbeaul/Preprints/list/>  
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Thank you for your attention !