

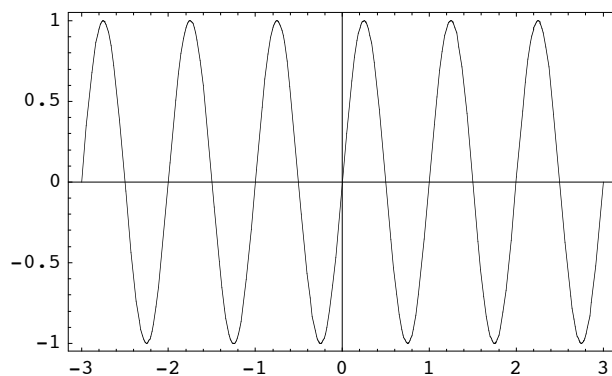
Travelling fronts in stochastic Stokes' drifts (1 / 3)

Adrien Blanchet, Jean Dolbeault,
and Michal Kowalczyk

```
Off[NIntegrate::"slwcon"]  
Off[General::"spell1"]  
Off[NIntegrate::"ncvb"]  
Off[NIntegrate::"ploss"]
```

The case of the sinusoidal function

```
 $\psi[x_] := \text{Sin}[2 \pi x]$   
Plot[ $\psi[x]$ , {x, -3, 3}, Frame → True];
```

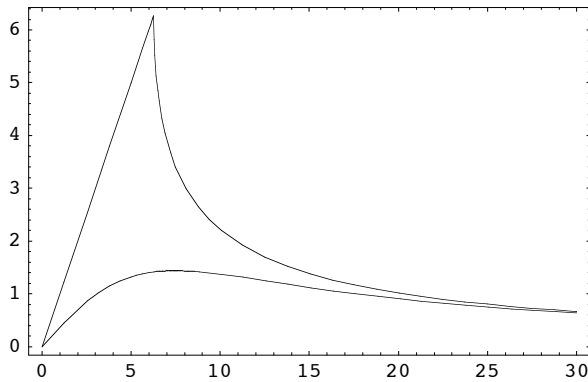


Speed of the center of mass

```

T[ω_] := NIntegrate[ $\frac{1}{\omega + \psi'[x]}$ , {x, 0, 1}]
Speed[ω_] := If[ω < 2 π, ω, ω - 1 / T[ω]]
a[ω_] := eω - 1
b[ω_] := NIntegrate[Exp[ψ[y] + ω * y], {y, 0, 1}]
c[ω_] := NIntegrate[Exp[-ψ[y] - ω * y], {y, 0, 1}]
d[ω_] := NIntegrate[x * Exp[ψ[t * x] + ω * t * x - ψ[x] - ω * x], {x, 0, 1}, {t, 0, 1}]
A[ω_] :=  $\frac{a[\omega]}{b[\omega] c[\omega] + a[\omega] d[\omega]}$ 
B[ω_] :=  $\frac{b[\omega]}{b[\omega] c[\omega] + a[\omega] d[\omega]}$ 
Velocity[ω_] := ω - A[ω]
Plot[{Speed[ω], Velocity[ω]}, {ω, 0, 30}, PlotRange -> All, Frame -> True];

```

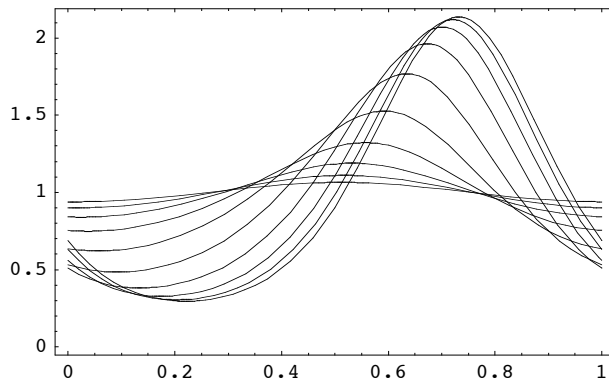


The solution of the doubly periodic problem (tilted Brownian ratchet)

```

g[z_, ω_] := Module[{M = {A[ω], B[ω]}},
  g[z] /.
  NDSolve[{g'[x] == M[[1]] - (ω + ψ'[x]) g[x], g[0] == M[[2]] Exp[-ψ[0]]}, g, {x, 0, 1}]
Show[Table[Plot[g[y, Exp[ $\frac{\text{Log}[100] k}{9}$ ]]], {y, 0, 1}, DisplayFunction -> Identity],
  {k, 0, 9}], DisplayFunction -> $DisplayFunction, Frame -> True];

```

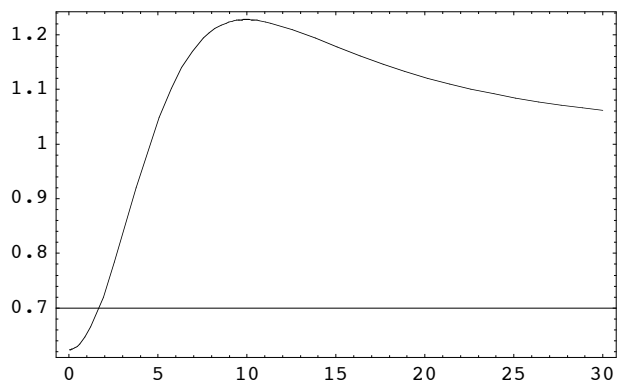


The effective diffusion coefficient

```

a1[ω_] := Module[{M = {A[ω], B[ω], Velocity[ω]}},
   $\frac{h1[1]}{e^{\omega} - 1}$  /. NDSolve[{g'[x] == M[[1]] - (ω + ψ'[x]) g[x],
    g[0] == M[[2]] Exp[-ψ[0]], h0'[x] == (ψ'[x] + M[[3]]) g[x], h0[0] == 0,
    h1'[x] == -(2 g[x] + h0[x]) Exp[ω x + ψ[x]], h1[0] == 0}, {g, h0, h1}, {x, 0, 1}][[1]]
κ[ω_] := Module[{M = {A[ω], B[ω], Velocity[ω], a1[ω]}},
  h2[1] /. NDSolve[{g'[x] == M[[1]] - (ω + ψ'[x]) g[x], g[0] == M[[2]] Exp[-ψ[0]],
    h0'[x] == (ψ'[x] + M[[3]]) g[x], h0[0] == 0, h1'[x] == -(2 g[x] + h0[x]) Exp[ω x + ψ[x]],
    h1[0] == 0, g1'[x] == -(2 g[x] + h0[x] + (ω + ψ'[x]) g1[x]), g1[0] == M[[4]] Exp[-ψ[0]],
    h2'[x] == (ψ'[x] + M[[3]]) g1[x], h2[0] == 1}, {g, h0, h1, g1, h2}, {x, 0, 1}][[1]]
Plot[κ[ω], {ω, 0.01, 30}, Frame → True];

```

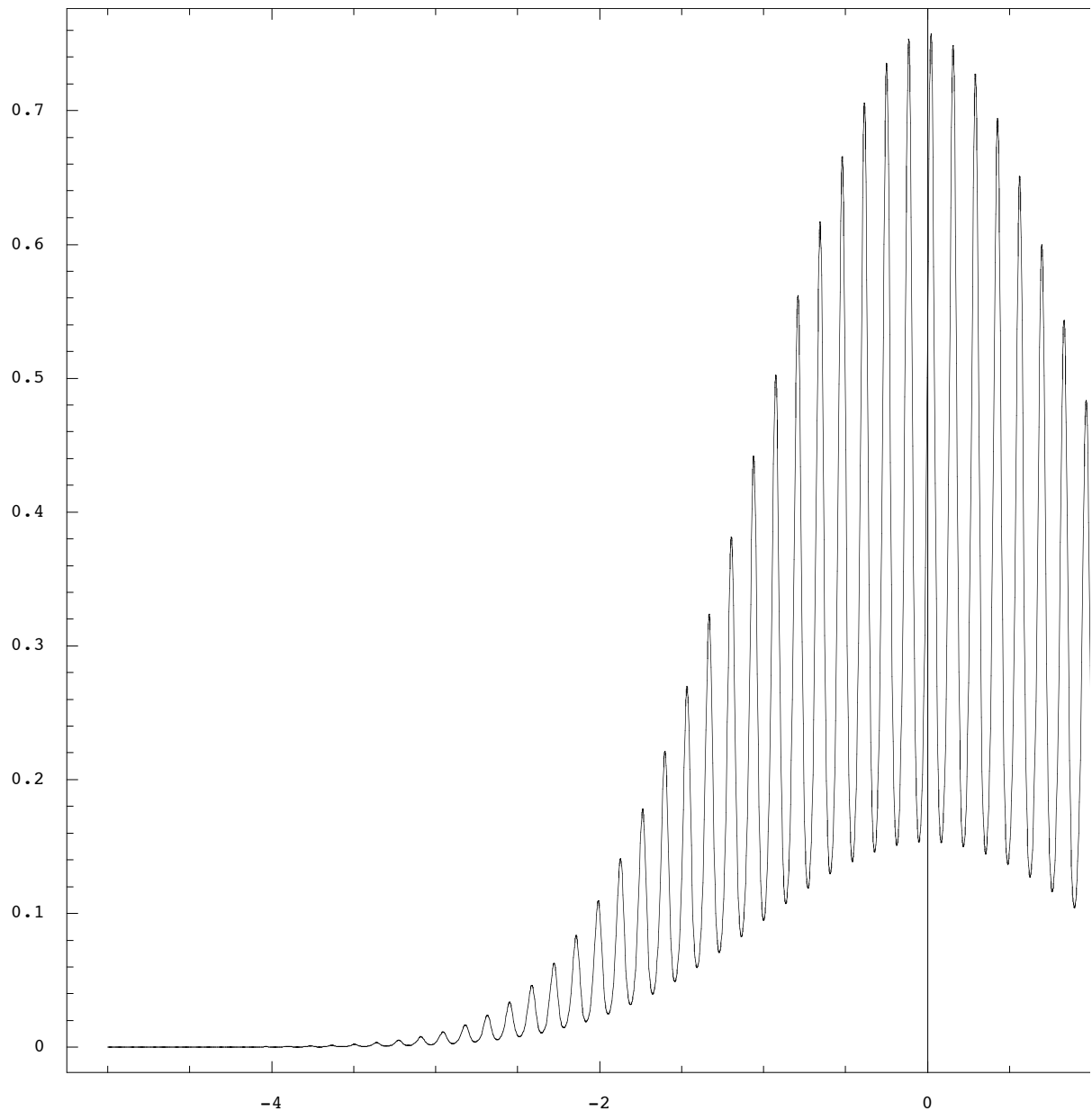


Intermediate asymptotics: the traveling front

```

Frac[x_] := 1 + x - Ceiling[x]
IA[t_, ω_] := Module[{M = {κ[ω], g[Frac[et x + (e2t - 1) A[ω] / 2], ω]}}, Plot[
  M[[2]]  $\frac{e^{-\frac{x^2}{2M[[1]]}}}{\sqrt{2\pi M[[1]]}}$ , {x, -5, 5}, PlotRange → All, Frame → True, PlotPoints → 250]]
IA[
  2,
  5];

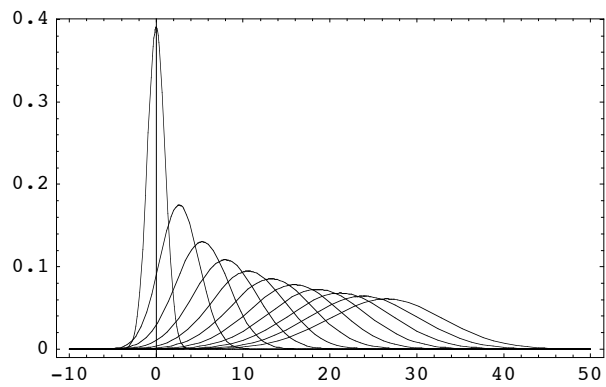
```



```

Profile[t_, ω_] := Module[{M = {κ[ω], Velocity[ω]}}, Plot[ $\frac{e^{-\frac{(x-M[[2])^2}{2 M[[1]] (1+2 t)}}}{\sqrt{2 \pi M[[1]] (1+2 t)}}$ ,
  {x, -10, 50}, PlotRange → All, Frame → True, DisplayFunction → Identity]]
Show[Table[Profile[n, 5], {n, 0, 20, 2}], DisplayFunction → $DisplayFunction];

```

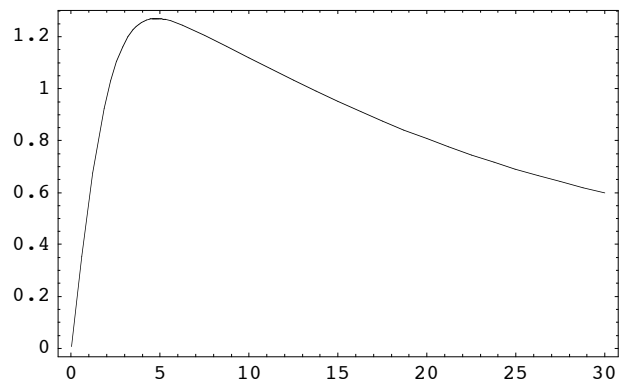


Computation of the Péclet number

```

Plot[ $\frac{\text{Velocity}[\omega]}{\kappa[\omega]}$ , {ω, 0.01, 30}, Frame → True];

```



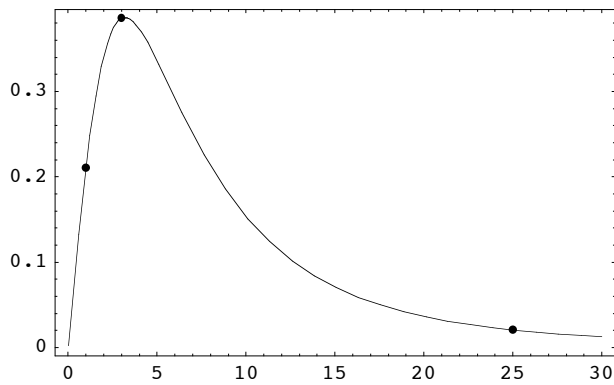
Computation of the Efficiency

```

Eff[ω_] := Module[{M = κ[ω]}, Evaluate[ $\frac{(\text{Velocity}[\omega])^2}{\omega M}$ ]]
Values = {1, 3, 25};
Table[
  {Values[[k]], Velocity[Values[[k]]], κ[Values[[k]]], Eff[Values[[k]]]}, {k, 1, 3}]
EffPoints = Table[{Values[[k]], Eff[Values[[k]]]}, {k, 1, 3}];
Show[Plot[Eff[ω], {ω, 0.01, 30}, Frame → True, DisplayFunction → Identity],
  ListPlot[EffPoints, PlotStyle → PointSize[0.015], DisplayFunction → Identity],
  DisplayFunction → $DisplayFunction];

{{1, 0.370027, 0.651926, 0.210024},
 {3, 0.981553, 0.83311, 0.385482}, {25, 0.748605, 1.08446, 0.0206705}}

```



```

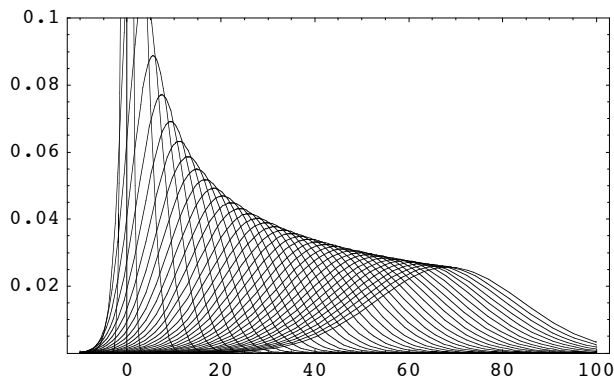
Profile[t_, ω_] := Module[{M = {κ[ω], Velocity[ω]}},
  Plot[ $\frac{e^{-\frac{(x-M[[2]] t)^2}{2 M[[1]] (1+2 t)}}}{\sqrt{2 \pi M[[1]] (1+2 t)}}$ , {x, -10, 100}, Frame → True, DisplayFunction → Identity]]

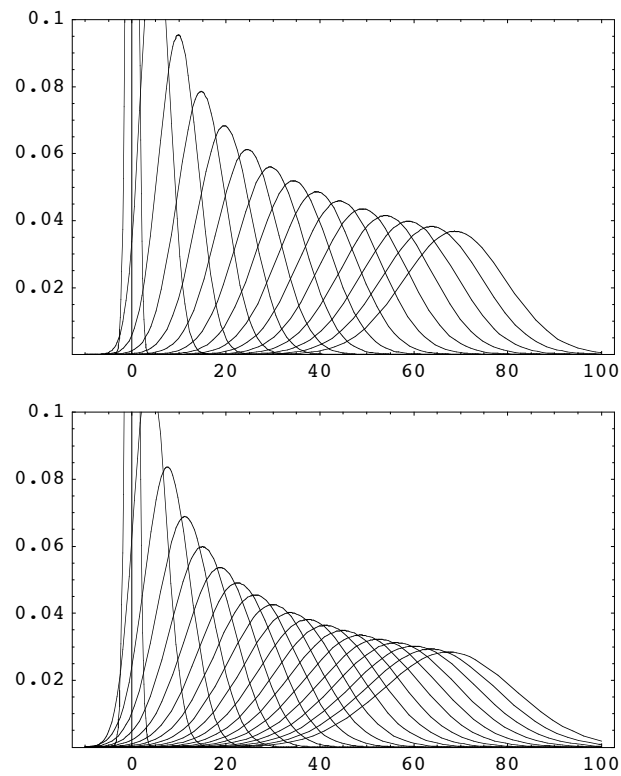
```

```

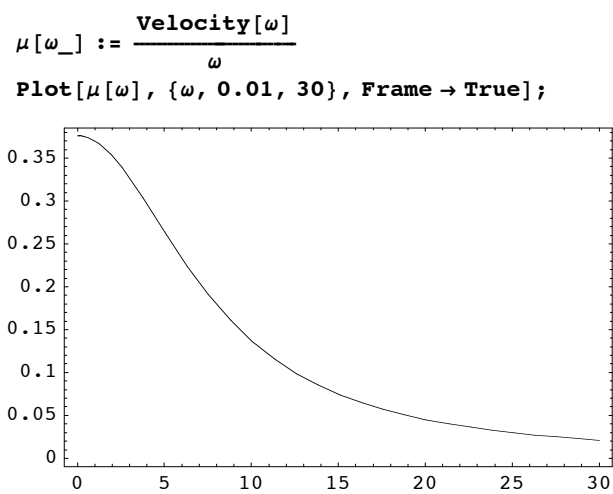
Front[ω_] := Show[Table[Profile[n, ω], {n, 0,  $\frac{70}{\text{Velocity}[\omega]}$ , 5}],
  DisplayFunction → $DisplayFunction, PlotRange → {All, {0, 0.1}}]
Show[Table[Front[Values[[k]]], {k, 1, 3}], DisplayFunction → Identity];

```





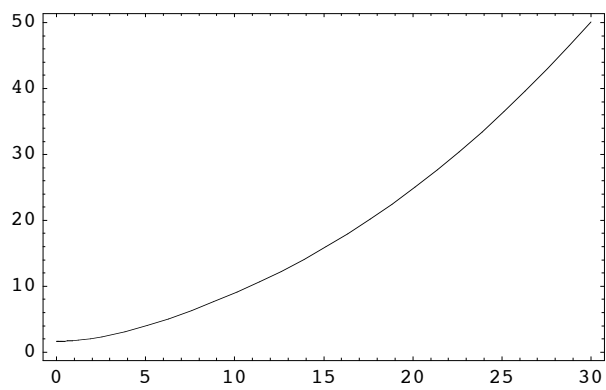
Computation of the mobility and violation of Einstein's relation



```
Off[Part::"partd"]
```

```
Einstein[ω_] := Module[{M = {κ[ω], μ[ω]}}, Evaluate[ $\frac{M[[1]]}{M[[2]]}$ ]]
```

```
Plot[Einstein[ω], {ω, 0.01, 30}, Frame → True];
```



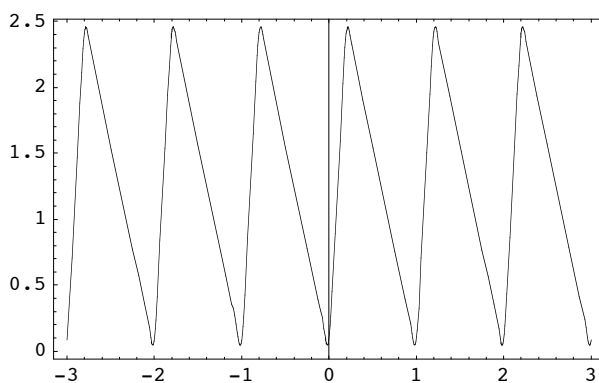
Travelling fronts in stochastic Stokes' drifts (2 / 3)

**Adrien Blanchet, Jean Dolbeault,
and Michal Kowalczyk**

```
Off[NIntegrate::"slwcon"]
Off[General::"spell1"]
Off[NIntegrate::"ncvb"]
Off[NIntegrate::"ploss"]
```

The case of the smooth sawtooth potential

```
Intensity = 5;  $\epsilon$  = 0.2; Nbre = 8;
Potential[x_] := If[x <  $\epsilon$ ,  $\frac{x}{\epsilon}$ ,  $\frac{1-x}{1-\epsilon}$ ]
Acoef = Table[NIntegrate[Potential[x] Sin[2  $\pi$  k x], {x, 0, 1}], {k, 1, Nbre}];
Bcoef = Table[NIntegrate[Potential[x] Cos[2  $\pi$  k x], {x, 0, 1}], {k, 1, Nbre}];
B0 = NIntegrate[Potential[x], {x, 0, 1}];
 $\psi$ [x_] := Intensity  $\left( \text{Sum}[Acoef[[k]] \text{Sin}[2 \pi k x], \{k, 1, Nbre\}] + \right.$ 
 $\left. \frac{B0}{2} + \text{Sum}[Bcoef[[k]] \text{Cos}[2 \pi k x], \{k, 1, Nbre\}] \right)$ 
Plot[ $\psi$ [x], {x, -3, 3}, Frame  $\rightarrow$  True];
```



Speed of the center of mass for positive values of ω

```

x /. FindRoot[ψ'[x] == 0, {x, 0.02, 0.1}];
ω0 = ψ'[x] /. FindRoot[ψ'[x] == 0, {x, 0.02, 0.1}];

T[ω_] := NIntegrate[ $\frac{1}{\omega - \psi'[x]}$ , {x, 0, 1}]

Speed[ω_] := If[ω < ω0, ω, ω - 1 / T[ω]]
a[ω_] := eω - 1
b[ω_] := NIntegrate[Exp[ψ[y] + ω * y], {y, 0, 1}]
c[ω_] := NIntegrate[Exp[-ψ[y] - ω * y], {y, 0, 1}]
d[ω_] := NIntegrate[x * Exp[ψ[t * x] + ω * t * x - ψ[x] - ω * x], {x, 0, 1}, {t, 0, 1}]

A[ω_] :=  $\frac{a[\omega]}{b[\omega] c[\omega] + a[\omega] d[\omega]}$ 
B[ω_] :=  $\frac{b[\omega]}{b[\omega] c[\omega] + a[\omega] d[\omega]}$ 
Velocity[ω_] := ω - A[ω]
Plog1 = Plot[{Log[1 + Speed[ω]], Log[1 + Velocity[ω]]},
  {ω, 0, 30}, PlotRange → All, DisplayFunction → Identity];

```

Speed of the center of mass for negative values of ω

```

Intensity = 5; ε = 0.8; Nbre = 8;
Potential[x_] := If[x < ε,  $\frac{x}{\epsilon}$ ,  $\frac{1-x}{1-\epsilon}$ ]
Acoef = Table[NIntegrate[Potential[x] Sin[2 π k x], {x, 0, 1}], {k, 1, Nbre}];
Bcoef = Table[NIntegrate[Potential[x] Cos[2 π k x], {x, 0, 1}], {k, 1, Nbre}];
B0 = NIntegrate[Potential[x], {x, 0, 1}];

ψ[x_] := Intensity (Sum[Acoef[[k]] Sin[2 π k x], {k, 1, Nbre}] +
 $\frac{B0}{2}$  + Sum[Bcoef[[k]] Cos[2 π k x], {k, 1, Nbre}])

x /. FindRoot[ψ'[x] == 0, {x, 0.02, 0.1}];
ω0 = ψ'[x] /. FindRoot[ψ'[x] == 0, {x, 0.02, 0.1}];

T[ω_] := NIntegrate[ $\frac{1}{\omega - \psi'[x]}$ , {x, 0, 1}]

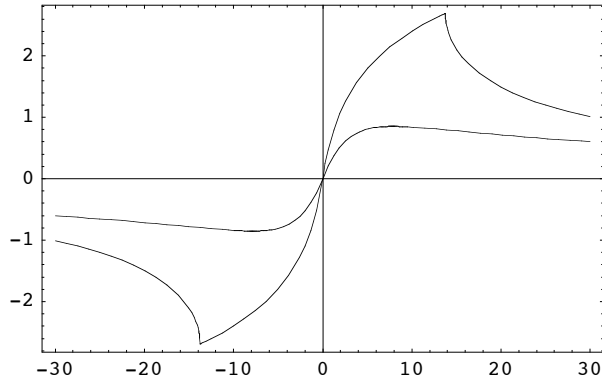
Speed[ω_] := If[ω < ω0, ω, ω - 1 / T[ω]]
a[ω_] := eω - 1
b[ω_] := NIntegrate[Exp[ψ[y] + ω * y], {y, 0, 1}]
c[ω_] := NIntegrate[Exp[-ψ[y] - ω * y], {y, 0, 1}]
d[ω_] := NIntegrate[x * Exp[ψ[t * x] + ω * t * x - ψ[x] - ω * x], {x, 0, 1}, {t, 0, 1}]

A[ω_] :=  $\frac{a[\omega]}{b[\omega] c[\omega] + a[\omega] d[\omega]}$ 
B[ω_] :=  $\frac{b[\omega]}{b[\omega] c[\omega] + a[\omega] d[\omega]}$ 
Velocity[ω_] := ω - A[ω]
Plog2 = Plot[{-Log[1 + Speed[-ω]], -Log[1 + Velocity[-ω]]},
  {ω, -30, 0}, PlotRange → All, DisplayFunction → Identity];

```

Plot of the speed of the center of mass for positive and negative values of ω

```
Show[Plog1, Plog2, Frame → True, DisplayFunction → $DisplayFunction];
```



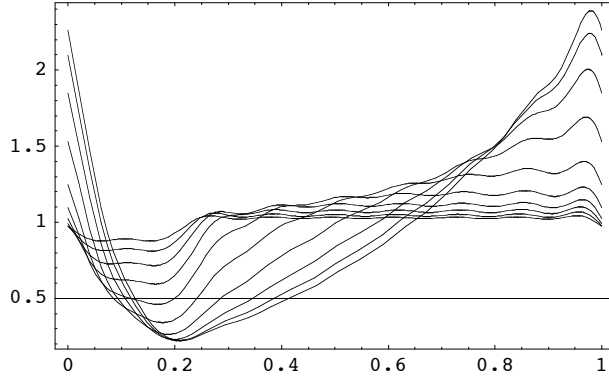
The solution of the doubly periodic problem (tilted Brownian ratchet)

```
Intensity = 5; ε = 0.2; Nbre = 8;
Potential[x_] := If[x < ε, x/ε, (1-x)/(1-ε)]
Acoef = Table[NIntegrate[Potential[x] Sin[2 π k x], {x, 0, 1}], {k, 1, Nbre}];
Bcoef = Table[NIntegrate[Potential[x] Cos[2 π k x], {x, 0, 1}], {k, 1, Nbre}];
B0 = NIntegrate[Potential[x], {x, 0, 1}];
ψ[x_] := Intensity (Sum[Acoef[[k]] Sin[2 π k x], {k, 1, Nbre}] +
  (B0/2 + Sum[Bcoef[[k]] Cos[2 π k x], {k, 1, Nbre}]))
x /. FindRoot[ψ'[x] == 0, {x, 0.02, 0.1}];
ω0 = ψ'[x] /. FindRoot[ψ'[x] == 0, {x, 0.02, 0.1}];
T[ω_] := NIntegrate[1/(ω - ψ'[x]), {x, 0, 1}]
Speed[ω_] := If[ω < ω0, ω, ω - 1/T[ω]]
a[ω_] := e^ω - 1
b[ω_] := NIntegrate[Exp[ψ[y] + ω * y], {y, 0, 1}]
c[ω_] := NIntegrate[Exp[-ψ[y] - ω * y], {y, 0, 1}]
d[ω_] := NIntegrate[x * Exp[ψ[t * x] + ω * t * x - ψ[x] - ω * x], {x, 0, 1}, {t, 0, 1}]
A[ω_] := a[ω]/(b[ω] c[ω] + a[ω] d[ω])
B[ω_] := b[ω]/(b[ω] c[ω] + a[ω] d[ω])
Velocity[ω_] := ω - A[ω]
```

```

Pltg[ω_] := Module[{M = {A[ω], B[ω]}}, Plot[
  Evaluate[g[z] /. NDSolve[{g'[x] == M[[1]] - (ω + ψ'[x]) g[x], g[0] == M[[2]] Exp[-ψ[0]]},
    g, {x, 0, 1}], {z, 0, 1}], DisplayFunction → Identity]]
Show[Table[Pltg[Exp[Log[100] k / 9]], {k, 0, 9}], DisplayFunction → $DisplayFunction,
  Frame → True, PlotRange → All];

```

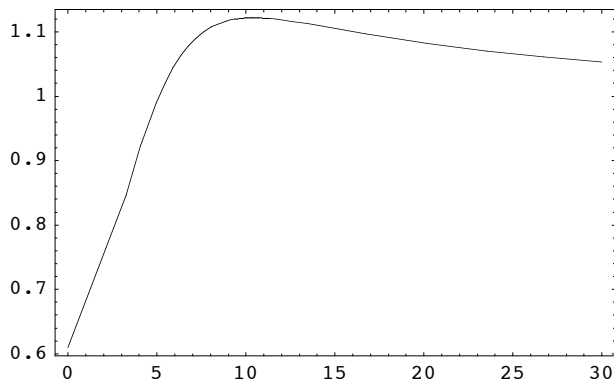


The effective diffusion coefficient

```

a1[ω_] := Module[{M = {A[ω], B[ω], Velocity[ω]}},
  h1[1] / (Exp[ω] - 1) /. NDSolve[{g'[x] == M[[1]] - (ω + ψ'[x]) g[x],
    g[0] == M[[2]] Exp[-ψ[0]], h0'[x] == (ψ'[x] + M[[3]]) g[x], h0[0] == 0,
    h1'[x] == -(2 g[x] + h0[x]) Exp[ω x + ψ[x]], h1[0] == 0}, {g, h0, h1}, {x, 0, 1}][[1]]
κ[ω_] := Module[{M = {A[ω], B[ω], Velocity[ω], a1[ω]}},
  h2[1] /. NDSolve[{g'[x] == M[[1]] - (ω + ψ'[x]) g[x], g[0] == M[[2]] Exp[-ψ[0]],
    h0'[x] == (ψ'[x] + M[[3]]) g[x], h0[0] == 0, h1'[x] == -(2 g[x] + h0[x]) Exp[ω x + ψ[x]],
    h1[0] == 0, g1'[x] == -(2 g[x] + h0[x] + (ω + ψ'[x]) g1[x]), g1[0] == M[[4]] Exp[-ψ[0]],
    h2'[x] == (ψ'[x] + M[[3]]) g1[x], h2[0] == 1}, {g, h0, h1, g1, h2}, {x, 0, 1}][[1]]
Plot[κ[ω], {ω, 0.01, 30}, Frame → True, PlotPoints → 10, PlotRange → All];

```



Travelling fronts in stochastic Stokes' drifts (3 / 3)

Adrien Blanchet, Jean Dolbeault,
and Michal Kowalczyk

Error function and definition of the efficiency

```
Integrate[ $\frac{e^{-\frac{x^2}{2}}}{\sqrt{2\pi}}$ , {x, -∞, -1}]

N[%]

 $\frac{1}{2} \operatorname{Erfc}\left[\frac{1}{\sqrt{2}}\right]$ 

0.158655

x0 = 3;
Pa =

Plot[ $\left\{\frac{e^{-\frac{x^2}{2}}}{\sqrt{2\pi}}, \frac{e^{-\frac{(x-x_0)^2}{2x_0^2}}}{\sqrt{2\pi}x_0}\right\}$ , {x, -7, 12}, PlotRange → All, DisplayFunction → Identity];

Pb = ListPlot[{{x0, -0.07}, {x0, 0.15}}, PlotJoined → True, DisplayFunction → Identity];

TableErf = Join[{{0, 0}, {-7, 0}}, Table[ $\left\{x, \frac{e^{-\frac{(x-x_0)^2}{2x_0^2}}}{\sqrt{2\pi}x_0}\right\}$ , {x, -7, 0, 0.04}]]];

Pc = Show[Graphics[{GrayLevel[0.5], Polygon[TableErf]}], DisplayFunction → Identity];
Show[Pa, Pb, Pc, DisplayFunction → $DisplayFunction, Ticks → None];
```

