## Large time asymptotics of nonlinear drift-diffusion systems with Poisson coupling

#### Piotr BILER

Mathematical Institute, University of Wrocław pl. Grunwaldzki 2/4, 50-384 Wrocław, Poland biler@math.uni.wroc.pl,

Jean DOLBEAULT
CEREMADE, U.M.R. C.N.R.S. no. 7534,
Université Paris IX-Dauphine
Pl. du Maréchal de Lattre de Tassigny,
75775 Paris Cédex 16, France
dolbeaul@ceremade.dauphine.fr

Peter A. MARKOWICH Institut für Mathematik, University of Vienna, Boltzmanngasse 9, A-1090 Wien, Austria Peter.Markowich@univie.ac.at

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#### Abstract

We study the asymptotic behavior as  $t \to +\infty$  of a system of densities of charged particles satisfying nonlinear drift-diffusion equations coupled by a damped Poisson equation for the drift-potential.

In plasma physics applications the damping is caused by a spatiotemporal rescaling of an "unconfined" problem, which introduces a harmonic external potential of confinement. We present formal calculations (valid for smooth solutions) which extend the results known in the linear diffusion case to nonlinear diffusion of e.g. Fermi-Dirac or fast diffusion/porous media type.

**Key words and phrases:** nonlinear drift-diffusion systems, asymptotic behavior of solutions, logarithmic Sobolev inequalities, fast diffusion, porous media

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#### 1 Introduction

Consider the system

$$u_{t} = \nabla \cdot (\nabla f(u) + u \nabla V + \beta(t) u \nabla \phi)$$

$$v_{t} = \nabla \cdot (\nabla f(v) + v \nabla V - \beta(t) v \nabla \phi)$$

$$\Delta \phi = v - u$$
(1.1)

in  $\mathbb{R}_t^+ \times \mathbb{R}_x^d$ ,  $d \ge 3$ , and assume that  $\beta$  is a nonnegative decreasing function of time t with  $\lim_{t \to +\infty} \beta(t) = 0$ . V is the exterior potential with  $V(x) \to +\infty$  as  $|x| \to +\infty$ . The initial data  $u_0 = u(t=0)$ ,  $v_0 = v(t=0)$  are assumed to be in  $L_+^1(\mathbb{R}_x^d)$ . The function f satisfies

$$f(0) = 0, \quad f'(s) > 0 \quad \forall s \in (0, \infty).$$
 (1.2)

The system (1.1) can be regarded as a model for a bipolar plasma, where both types of particles are confined by a potential V(x), and where the Poisson coupling (mean field) becomes asymptotically weaker as  $t \to +\infty$ . In the next section, we derive such a model by a spatio-temporal rescaling from a system without confinement and without damping of the mean field. The function f defines the density-pressure constitutive relation, which is taken equal for both particle species (cf [8]).

Note that the minimum principle implies u(t),  $v(t) \ge 0$  (since we assumed  $u_0, v_0 \ge 0$ ). We remark that for the following we always take the Newtonian potential  $\psi$  of g as solution of  $-\Delta \psi = g$  in  $\mathbb{R}^d$ .

In this paper the nonlinearities we have in mind are either

$$f(s) = s^m, \quad s \ge 0 \tag{1.3}$$

where the cases m < 1, m = 1 and m > 1 correspond to the fast diffusion equation, the heat equation (linear diffusion) and the porous media equation respectively, or the following diffusion equation corresponding to "physical" 3-dimensional flows in the Fermi-Dirac thermodynamical framework. Define, with  $\epsilon > 0$  a parameter,  $F: \mathbb{R} \to (0, \infty)$  by

$$F(\sigma) := \int_{\mathbb{R}^3_v} \frac{dv}{\epsilon + \exp(|v|^2/2 - \sigma)}.$$
 (1.4)

Clearly,  $F(-\infty) = 0$ ,  $F(\infty) = \infty$ . The nonlinearity f in (1.1) then reads

$$f(s) = sF^{-1}(s) - \int_0^s F^{-1}(\tau) d\tau, \quad 0 \le s < \infty$$
 (1.5)

(where  $F^{-1}$  denotes the inverse function of F).

Note that stationary solutions of the equation

$$z_t = \nabla \cdot (\nabla f(z) + z \nabla V) = \nabla \cdot (z(\nabla h(z) + \nabla V))$$

where h'(s) = f'(s)/s, are of the form

$$z(x) = \left(C - V(x)\right)_{+}^{1/(m-1)} \quad \text{if} \quad m \neq 1,$$

$$z(x) = C e^{-V(x)} \quad \text{if} \quad m = 1$$

for (1.3), and

$$z(x) = \int_{\mathbb{R}_n^3} \frac{dv}{\epsilon + C \exp(V(x) + |v|^2/2)}$$

for (1.4)-(1.5).

At the end of this introduction, let us mention a (nonexhaustive) list of references related to this work. Concerning the Gross logarithmic Sobolev inequalities in a PDE framework, we refer to [2] and references therein. The extension to the porous media or fast diffusion cases have been studied in [5, 6, 9]. For systems with a Poisson coupling and a linear diffusion, let us quote [2, 1, 3]. References [4, 7, 8] are relevant for the modelization and the analysis in the plasma physics or semiconductor context.

Notation. In the sequel the  $L^p(\mathbb{R}^d)$  norms shall be denoted by  $|\,.\,|_p$ .

# 2 Derivation from a drift-diffusion system without confinement

Systems of the form (1.1) can be obtained by a spatio-temporal rescaling from drift-diffusion systems without confinement, and with a nonlinear diffusion of power-law type.

Consider the system for the densities n and p of oppositely charged particles

$$n_{t} = \nabla \cdot (\nabla f(n) + n \nabla \psi)$$

$$p_{t} = \nabla \cdot (\nabla f(p) - p \nabla \psi)$$

$$\Delta \psi = p - n$$
(2.1)

where, with m > 0

$$f(s) = s^m \quad \text{for } s \ge 0, \tag{2.2}$$

and define u and v by

$$n(t,x) = \frac{1}{R^d(t)} u\left(\log R(t), \frac{x}{R(t)}\right),$$

$$p(t,x) = \frac{1}{R^d(t)} v\left(\log R(t), \frac{x}{R(t)}\right),$$
(2.3)

with an increasing function R > 0.

**Lemma 2.1** A solution  $\langle n,p \rangle$  of (2.1) (with f given by (2.2)) corresponds by the change of variables (2.3) to a solution  $\langle u,v \rangle$  of (1.1) if and only if

$$\dot{R}R^{d(m-1)+1} = 1$$
,  
 $V(x) = \frac{1}{2}|x|^2$ ,  
 $\beta(t) = R(t)^{2-d}$ . (2.4)

Moreover

$$\psi(t,x) = \frac{1}{R^{d-2}(t)} \phi\left(\log R(t), \frac{x}{R(t)}\right).$$

Note that  $\langle n, p \rangle$  and  $\langle u, v \rangle$  have the same initial data if R(0) = 1. Contrarily to (1.1), the strength of the Poisson coupling in (2.1) is assumed to be constant in time: the damping in (1.1) appears as a consequence of the rescaling.

## 3 Asymptotic (uncoupled) problem

Consider now the system (1.1) with  $\beta = 0$ . Both u and v then solve an equation of the form

$$z_t = \nabla \cdot (\nabla f(z) + z \nabla V), \quad z(0) = z_0 \ge 0.$$
 (3.1)

Formally we have

$$\int z(x,t) dx = \int z_0(x) dx \quad \text{for all } t > 0$$

(all the integrals are over  $\mathbb{R}^d$ , unless specified differently). Let

$$W[z] = \int [z(V + h(z)) - f(z)] dx$$
 (3.2)

with the enthalpy defined by

$$h(z) = \int_{1}^{z} \frac{f'(s)}{s} \, ds \,. \tag{3.3}$$

For a solution of (3.1), a standard computation (formally) gives

$$\frac{d}{dt}W[z](t) = \int [V + (h(z) + zh'(z) - f'(z))]z_t dx 
= -\int z |\nabla (V + h(z))|^2 dx.$$
(3.4)

Consider then a steady state  $z_{\infty}$  such that, for a constant  $C_z \in \mathbb{R}$  with

$$C_z \le \inf_{\mathbb{R}^d} V + h(\infty) \tag{3.5}$$

we have

$$z_{\infty}(x) = \tilde{h}^{-1}(C_z - V(x)).$$
 (3.6)

Here  $\tilde{h}^{-1}$  is the extension of  $h^{-1}$  given by

$$\widetilde{h}^{-1}(\sigma) = \left\{ \begin{array}{ccc} h^{-1}(\sigma) & \text{if} & \sigma \in (h(0^+), h(\infty)), \\ 0 & \text{if} & \sigma \leq h(0^+). \end{array} \right.$$

**Remark 3.1** In the fast diffusion / porous media cases (1.3)  $h(s) = m(s^{m-1}-1)/(m-1)$  is such that

$$h(0+) = -\infty$$
,  $h(\infty) = \frac{m}{m-1}$  if  $m < 1$ ,  
 $h(0+) = -\frac{m}{m-1}$ ,  $h(\infty) = +\infty$  if  $m > 1$ ,

while  $h(0+) = -\infty$  and  $h(\infty) = +\infty$  if m = 1. In the case (1.4)-(1.5) we have  $h(s) = F^{-1}(s)$ ,  $h(0+) = -\infty$  and  $h(\infty) = +\infty$ .

Note that (3.6) implies

$$V(x) + h(z_{\infty}(x)) = C_z$$
 if  $h(0^+) \le C_z - V(x)$   
and  $z_{\infty}(x) = 0$  if  $h(0^+) \ge C_z - V(x)$ . (3.7)

Assume now that V is such that for all  $C\in \inf_{\mathbb{R}^d}V+(h(0^+),h(\infty))$ 

$$\int \tilde{h}^{-1}(C - V(x)) dx < \infty. \tag{3.8}$$

Now let  $M < \infty$  satisfy

$$0 \le M \le \int \tilde{h}^{-1} \left( \inf_{\mathbb{R}^d} V + h(\infty) - V(x) \right) dx \tag{3.9}$$

(the right hand side may very well be  $+\infty$ !). Then the steady state  $z_{\infty}$  is uniquely determined by the requirement

$$\int z_{\infty}(x) \, dx = M \,. \tag{3.10}$$

Note that this is the case for all  $M \ge 0$  if  $f(s) = s^m$  with m > d/2 - 1 and  $V(x) = \frac{1}{2}|x|^2$  (cf [6]), or in the Fermi-Dirac case.

Assuming  $W[z_0] < +\infty$ , the entropy W[z](t) decays monotonically with respect to t, and under additional regularity assumptions, it was shown in [2, 5, 6, 9] that

$$\lim_{t \to +\infty} W[z](t) = W[z_{\infty}] \tag{3.11}$$

if

$$\int z_0 dx = \int z_\infty dx = M. \tag{3.12}$$

In the following, we define the relative entropy

$$W[z|z_{\infty}] = W[z] - W[z_{\infty}] \tag{3.13}$$

of the nonnegative states z,  $z_{\infty}$  with equal integrals.

#### Remark 3.2 Set

$$\widetilde{W}[z|z_{\infty}] = \int \left( \int_{z_{\infty}(x)}^{z(x)} (h(s) - h(z_{\infty}(x)) ds \right) dx \ge 0.$$
 (3.14)

Since, by the definition (3.3) of h

$$\int_{z_1}^{z_2} (h(s) - h(z_1)) ds = z_2(h(z_2) - h(z_1)) - f(z_2) + f(z_1), \qquad (3.15)$$

we conclude

$$\begin{split} W[z|z_{\infty}] - \widetilde{W}[z|z_{\infty}] &= \int (V(x) + h(z_{\infty}))(z - z_{\infty}) \, dx \\ &= \int_{\{h(0^+) \ge C_z - V(x)\}} z(V(x) + h(0^+) - C_z) \, dx \ge 0 \,, \end{split}$$

where (3.7) and (3.12) were used for the last equality. Therefore  $W[z|z_{\infty}] \ge 0$  follows and  $W[z|z_{\infty}] = \widetilde{W}[z|z_{\infty}]$  if  $h(0^+) = -\infty$ .

**Remark 3.3** Let  $h(0^+) = -\infty$  and take a function  $\Phi = \Phi(\gamma)$  with  $\Phi(0) = 0$  and  $\Phi'(\gamma) > 0$  for  $\gamma \in \mathbb{R}$ . We define the functional

$$\widetilde{W}_{\Phi}[z|z_{\infty}] = \int \left( \int_{z_{\infty}(x)}^{z(x)} \Phi(h(s) - h(z_{\infty}(x)) ds \right) dx \ge 0.$$
 (3.16)

and compute its time-derivative along the solution z(t) of (3.1):

$$\frac{d}{dt}W_{\Phi}[z|z_{\infty}](t) = -\int z |\nabla(V + h(z))|^2 \Phi'(h(z) - h(z_{\infty})) dx.$$
 (3.17)

Thus,  $W_{\Phi}$  is another relative entropy for (3.1).

## 4 A Lyapunov functional

Consider now a solution  $\langle u, v \rangle$  of (1.1) such that

$$\int u_0 \, dx = M_u \ge 0 \,, \tag{4.1}$$

$$\int v_0 \, dx = M_v \ge 0 \,, \tag{4.2}$$

(with  $M_u$ ,  $M_v$  satisfying (3.9) and  $M_u + M_v > 0$ ), and define the relative entropy

$$\mathcal{W}[\langle u, v \rangle | \langle u_{\infty}, v_{\infty} \rangle] = W[u|u_{\infty}] + W[v|v_{\infty}] + \frac{\beta}{2} |\nabla \phi|_{2}^{2}. \tag{4.3}$$

Similarly to the case studied in [1], [3], we obtain

**Lemma 4.1** For  $d \ge 3$ , if u and v are smooth and decay sufficiently fast as  $|x| \to +\infty$ , and if f satisfies (1.2) we have

$$\begin{split} &\frac{d}{dt} \Big( \mathcal{W}[\langle u, v \rangle | \langle u_{\infty}, v_{\infty} \rangle](t) \Big) = -2J - \beta^2 \int (u+v) |\nabla \phi|^2 \, dx \\ &-2\beta \int \Big[ f(u) - f(v) \Big](u-v) \, dx + 2\beta \int \Delta \phi \nabla \phi \cdot \nabla V \, dx + \frac{1}{2} \frac{d\beta}{dt} |\nabla \phi|_2^2 \,, \, (4.4) \end{split}$$

where

$$J = \frac{1}{2} \int u |\nabla h(u) + \nabla V|^2 dx + \frac{1}{2} \int v |\nabla h(v) + \nabla V|^2 dx.$$
 (4.5)

**Proof:** Assuming a sufficient decay of  $\phi$  in  $x \in \mathbb{R}^d$  (with  $d \ge 3$ ) as  $|x| \to +\infty$ , we obtain

$$\frac{d}{dt} |\nabla \phi|_2^2(t) = 2 \int (-\Delta \phi)_t \phi \, dx = 2 \int (u_t - v_t) \phi \, dx \,, \tag{4.6}$$

and thus

$$\frac{d}{dt} \Big( \mathcal{W}[\langle u, v \rangle | \langle u_{\infty}, v_{\infty} \rangle](t) \Big) - \frac{1}{2} \frac{d\beta}{dt} |\nabla \phi|_{2}^{2}(t) 
= \int (V + h(u) + \beta \phi) u_{t} dx + \int (V + h(v) - \beta \phi) v_{t} dx .$$
(4.7)

Then, replacing  $u_t$  and  $v_t$  by their expressions in (1.1) and integrating by parts, we obtain

$$\frac{d}{dt} \left( \mathcal{W}[\langle u, v \rangle | \langle u_{\infty}, v_{\infty} \rangle](t) \right) - \frac{1}{2} \frac{d\beta}{dt} |\nabla \phi|_2^2(t)$$

$$= -\int \nabla (V + h(u) + \beta \phi) \cdot \left[ \nabla f(u) + u \nabla V + \beta u \nabla \phi \right] dx$$
$$-\int \nabla (V + h(v) - \beta \phi) \cdot \left[ \nabla f(v) + v \nabla V - \beta v \nabla \phi \right] dx.$$

The evaluation of the cross-terms between u or v and  $\phi$  goes as follows

$$-\int \beta \nabla \phi \cdot \left[ \nabla f(u) + u \nabla V \right] dx - \int \nabla (V + h(u)) \cdot \beta u \nabla \phi \, dx$$

$$+\int \beta \nabla \phi \cdot \left[ \nabla f(v) + v \nabla V \right] dx + \int \nabla (V + h(v)) \cdot \beta v \nabla \phi \, dx$$

$$= -2\beta \int \nabla \phi \cdot \left[ \nabla f(u) + u \nabla V \right] dx$$

$$+2\beta \int \nabla \phi \cdot \left[ \nabla f(v) + v \nabla V \right] dx$$

using  $z\nabla h(z) = \nabla f(z)$  since sh'(s) = f'(s). Collecting the terms and using the Poisson equation, we first obtain

$$-2\beta \int \nabla \phi \cdot \left[ \nabla f(u) - \nabla f(v) \right] dx$$

$$= 2\beta \int \Delta \phi \left[ f(u) - f(v) \right] dx$$

$$= -2\beta \int (u - v) \left[ f(u) - f(v) \right] dx,$$

and then

$$-2\beta \int \nabla \phi \cdot (u\nabla V - v\nabla V) \, dx = 2\beta \int (\nabla V \cdot \nabla \phi) \Delta \phi \, dx \,, \tag{4.8}$$

so 
$$(4.4)$$
 follows.

Later on we shall use the identity

$$\int \Delta \phi \nabla \phi \cdot \nabla V \, dx = \frac{1}{2} \int |\nabla \phi|^2 \Delta V \, dx - \int \nabla \phi^{\top} (D^2 V) \nabla \phi \, dx \,, \tag{4.9}$$

where  $D^2V$  denotes the Hessian of V and " $^{\top}$ " stands for transposition.

## 5 Another relative entropy

In this section (only) we shall assume  $h(0^+) = -\infty$ ,  $h(\infty) = \infty$ , which hold in the Maxwell and Fermi-Dirac cases.

We define the "t-local Maxwellian" functions  $\bar{u} = \bar{u}(t)$  and  $\bar{v} = \bar{v}(t)$  respectively by

$$\bar{u}(x,t) = h^{-1}(C_u(t) - V(x) - \beta(t)\bar{\phi}(x,t)), 
\bar{v}(x,t) = h^{-1}(C_v(t) - V(x) + \beta(t)\bar{\phi}(x,t)), 
-\Delta\bar{\phi} = \bar{u} - \bar{v}, 
\int \bar{u}(x,t) dx = M_u, 
\int \bar{v}(x,t) dx = M_v.$$
(5.1)

Note that, due to the dependence of  $\beta$  on t, the normalization constants  $C_u$  and  $C_v$  depend on t.

The potential  $\bar{\phi}$  then solves the nonlinear elliptic problem

$$-\Delta \bar{\phi} = h^{-1} (C_u - V - \beta \bar{\phi}) - h^{-1} (C_v - V + \beta \bar{\phi}),$$

$$\int h^{-1} (C_u - V - \beta \bar{\phi}) dx = M_u,$$

$$\int h^{-1} (C_v - V + \beta \bar{\phi}) dx = M_v.$$
(5.2)

**Remark 5.1** The problem (5.2) has the following variational formulation:  $\bar{\phi}$  minimizes the functional  $\mathcal{E}[\phi]$  on  $\mathcal{D}^{1,2}(\mathbb{R}^d) = \{\phi \in L^{2d/(d-2)}(\mathbb{R}^d) : \nabla \phi \in L^2(\mathbb{R}^d)\}$ , where

$$\begin{split} \mathcal{E}[\phi] = & \frac{1}{2} \int |\nabla \phi|^2 \, dx \ + \frac{1}{\beta} \int G\bigg(D_1[\phi] - V - \beta \phi\bigg) \, dx - \frac{M_u}{\beta} D_1[\phi] \\ & + \frac{1}{\beta} \int G\bigg(D_2[\phi] - V + \beta \phi\bigg) \, dx - \frac{M_v}{\beta} D_2[\phi] \, . \end{split}$$

Here G is a primitive of  $h^{-1}$ , i.e.  $G' = h^{-1}$ , and  $D_1[\phi]$ ,  $D_2[\phi] \in \mathbb{R}$  are determined from the normalizations

$$\int h^{-1} \left( D_1[\phi] - V - \beta \phi \right) dx = M_u ,$$

$$\int h^{-1} \left( D_2[\phi] - V + \beta \phi \right) dx = M_v .$$

A simple computation gives (5.2) as the Euler-Lagrange equations of  $\mathcal{E}$ . In the linear diffusion case (i.e.  $h(s) = \log s$ ,  $h^{-1}(\sigma) = e^{\sigma}$ ), this variational problem has been studied in [7], [4]), and has been shown to have "good" properties (boundedness from below, weak lower semicontinuity and strict convexity). The problem is under investigation in the nonlinear case.

Consider now the functional

$$\Sigma[u,v] = W[u|\bar{u}] + W[v|\bar{v}] + \frac{\beta}{2} \left( |\nabla \phi|_2^2 - |\nabla \bar{\phi}|_2^2 \right). \tag{5.3}$$

A simple computation shows that

$$\begin{split} \Sigma[u,v] \; &= \int [u(h(u)-h(\bar{u}))-f(u)+f(\bar{u})] \, dx \\ &+ \int [v(h(v)-h(\bar{v}))-f(v)+f(\bar{v})] \, dx \\ &+ \int (u-\bar{u})(V+h(\bar{u})) \, dx + \int (v-\bar{v})(V+h(\bar{v})) \, dx \\ &+ \frac{\beta}{2} (|\nabla \phi|_2^2 - |\nabla \bar{\phi}|_2^2) \, . \end{split}$$

The integrands in the first two terms on the right hand side can be expressed using (3.15). On the other hand, by the definition of  $\bar{u}$  and  $\bar{v}$ ,

$$\int (u - \bar{u})(V + h(\bar{u})) dx + \int (v - \bar{v})(V + h(\bar{v})) dx$$

$$= \int (u - \bar{u})(C_u - \beta \bar{\phi}) dx + \int (v - \bar{v})(C_v + \beta \bar{\phi}) dx$$

$$= \int (-\Delta(\phi - \bar{\phi}))(-\beta \bar{\phi}) dx$$

$$= -\beta \int \nabla \phi \cdot \nabla \bar{\phi} dx + \beta |\nabla \bar{\phi}|_2^2.$$

Thus the representation

$$\Sigma[u,v] = \int \left( \int_{\bar{u}}^{u} (h(s) - h(\bar{u})) ds + \int_{\bar{v}}^{v} (h(s) - h(\bar{v})) ds \right) dx + \frac{\beta}{2} |\nabla \phi - \nabla \bar{\phi}|_{2}^{2} \ge 0$$
(5.4)

holds and the inequality is strict unless  $\langle u, v \rangle = \langle \bar{u}, \bar{v} \rangle$ .

Remark 5.2 Since for solutions of (5.2),

$$\frac{d}{dt} \left( \int (\bar{u}(V + h(\bar{u})) - f(\bar{u})) \, dx + \int (\bar{v}(V + h(\bar{v})) - f(\bar{v})) \, dx + \frac{\beta}{2} |\nabla \bar{\phi}|_{2}^{2} \right) 
= \int (h(\bar{u}) + V + \beta \bar{\phi}) \frac{\partial \bar{u}}{\partial t} \, dx + \int (h(\bar{v}) + V - \beta \bar{\phi}) \frac{\partial \bar{v}}{\partial t} \, dx + \frac{1}{2} \frac{d\beta}{dt} |\nabla \bar{\phi}|_{2}^{2} 
= \frac{1}{2} \frac{d\beta}{dt} |\nabla \bar{\phi}|_{2}^{2}$$
(5.5)

by the definition of  $\bar{u}$  and  $\bar{v}$ , for any solution of (1.1),

$$\frac{d}{dt} \left( \mathcal{W}[\langle u, v \rangle | \langle u_{\infty}, v_{\infty} \rangle] - \Sigma[u, v] \right) = \frac{1}{2} \frac{d\beta}{dt} |\nabla \bar{\phi}|_{2}^{2}, \tag{5.6}$$

and we conclude

$$\lim_{t \to +\infty} (\mathcal{W}[\langle u, v \rangle | \langle u_{\infty}, v_{\infty} \rangle](t) - \Sigma[u, v](t)) = 0.$$
 (5.7)

Thus  $\Sigma[u,v]$  is another relative entropy of (1.1).

## 6 Exponential decay in the bipolar case

The method used in [3] extends (formally) to the system (1.1) for which we assume from now on the existence of a smooth solution for  $t \in [0, +\infty)$ , which decays sufficiently fast for large |x|. We also assume in the following that V and f are chosen such that

$$W[z|z_{\infty}] \le \frac{K}{2} \int z |\nabla h(z) + \nabla V|^2 dx$$
(6.1)

for all sufficiently regular nonnegative functions z on  $\mathbb{R}^d$  with  $\int z dx = \int z_\infty dx$ , where K > 0 is independent of z. In the following, we shall refer to this inequality as the *Generalized Sobolev inequality* (see [6], [5]). Note that the Gross logarithmic Sobolev inequality is an example of the Generalized Sobolev inequality for f(s) = s, i.e. for  $h(s) = \log s$ , and  $V(x) = \frac{1}{2}|x|^2$ .

**Theorem 6.1** Let  $d \ge 3$  and consider f satisfying (1.2). Assume that f and  $V, V(x) \to +\infty$  as  $|x| \to +\infty$ , are such that the Generalized Sobolev inequality (6.1) holds. Consider a sufficiently regular, global solution of (1.1) (which

decays sufficiently fast for |x| large) corresponding to initial data  $u_0, v_0 \ge 0$  and assume that  $M_u$ ,  $M_v$  (as defined in (4.1), (4.2)) satisfy (3.9). Moreover, assume that there are constants  $c_1 \in \mathbb{R}$  and  $\omega > 0$  such that

- (i)  $2D^2V(x) \text{Tr}(D^2V(x))I \ge c_1I$  for all  $x \in \mathbb{R}^d$ ,
- (ii)  $\beta_t(t) \leq -2\omega\beta(t)$  for all  $t \geq 0$ .

Then there exists a constant  $\tilde{\lambda} > 0$ , explicitly computable in terms of K,  $c_1$ ,  $\omega$  such that

$$W[\langle u, v \rangle | \langle u_{\infty}, v_{\infty} \rangle](t) \leq e^{-\widetilde{\lambda}t} W[\langle u_{0}, v_{0} \rangle | \langle u_{\infty}, v_{\infty} \rangle]$$
(6.2)

for each solution  $\langle u,v \rangle$  of (1.1) with initial data  $\langle u_0,v_0 \rangle$  and all  $t \geq 0$ .

Remark 6.2 If we assume charge neutrality  $M_u = M_v$ , i.e.  $\int (u_0 - v_0) dx = 0$ , and  $|\nabla \phi(0)|_2^2 < \infty$  (which follows from the finiteness of  $\mathcal{W}[\langle u_0, v_0 \rangle] | \langle u_\infty, v_\infty \rangle$ ), then the results in Theorem 6.1 also hold true in the one- and two-dimensional cases d = 1, d = 2 (since  $\lim_{|x| \to +\infty} |\nabla \phi(x,t)| = 0$  under the electroneutrality condition).

Remark 6.3 The potentials  $V(x) = (1+|x|^2)^{\alpha/2}$  with  $0 < \alpha \le 2$  do satisfy assumptions (i) on confinement, while  $V(x) = (1+|x|^2)^{\alpha/2}$  with  $\alpha > 2$  does not. Also note that Generalized Sobolev inequalities were so far proven only for uniformly convex potentials in the case of nonlinear functions f = f(s). At least quadratic growth of V(x) as  $|x| \to \infty$  seems necessary for (6.1) to hold.

**Remark 6.4** If  $\beta(t) = e^{-(d-2)t}$  as it is the case when  $\beta$  is obtained by the mean of time-dependent rescalings, we recover the results of [3] for f(s) = s. For the system (2.1)-(2.2), the (algebraic) rate of convergence of course depends on m because of the dependence of R on t.

**Remark 6.5** As it is well known, cf [3, 5, 6], results on exponential decay of the relative entropy imply (via Csiszár–Kullback inequalities) the exponential convergence to steady states of (1.1) and convergence to self-similar solutions of (2.1) with an algebraic decay rate in the  $L^1$ -norms.

**Proof:** For any positive  $\lambda$ 

$$\begin{split} &-\left(\frac{d}{dt}\mathcal{W}[\langle u,v\rangle|\langle u_{\infty},v_{\infty}\rangle] + \lambda\mathcal{W}[\langle u,v\rangle|\langle u_{\infty},v_{\infty}\rangle]\right) \\ &= \lambda\bigg(KJ - W[u|u_{\infty}] - W[v|v_{\infty}]\bigg) + (2 - \lambda K)J + B + 2E + F + C\;, \eqno(6.3) \end{split}$$

where

$$B = \beta^2 \int (u+v) |\nabla \phi|^2 dx,$$

$$E = \beta \int \left[ f(u) - f(v) \right] (u-v) dx,$$

$$F = -\frac{1}{2} (\beta_t + \lambda \beta) |\nabla \phi|_2^2,$$

$$C = -2\beta \int \Delta \phi \nabla \phi \cdot \nabla V dx.$$

Observe that if we define

$$G_1 = \beta \int u (\nabla h(u) + \nabla V) \cdot \nabla \phi \, dx, \quad G_2 = \beta \int v (\nabla h(v) + \nabla V) \cdot \nabla \phi \, dx,$$

then

$$G_1 - G_2 = \beta \int \left( u(\nabla h(u) + \nabla V) - v(\nabla h(v) + \nabla V) \right) \cdot \nabla \phi \, dx = E + \frac{1}{2}C.$$

Now set

$$f_1 = \sqrt{u} (\nabla h(u) + V) , \quad g_1 = \beta \sqrt{u} \nabla \phi ,$$

$$f_2 = \sqrt{v} (\nabla h(v) + V) , \quad g_2 = \beta \sqrt{v} \nabla \phi ,$$

$$a_1 = |f_1|_2 , \quad b_1 = |g_1|_2 , \quad a_2 = |f_2|_2 , \quad b_2 = |g_2|_2 .$$

By the Cauchy-Schwarz inequality we have

$$2|G_1-G_2|=2\left|\int (f_1g_1-f_2g_2)\,dx\right|\leq 2(a_1b_1+a_2b_2)$$
.

But

$$0 \leq (a_1b_2 - a_2b_1)^2 = (a_1^2 + a_2^2)(b_1^2 + b_2^2) - (a_1b_1 + a_2b_2)^2 \,,$$

$$2\gamma(a_1b_1 + a_2b_2) \leq 2\sqrt{\gamma^2(a_1^2 + a_2^2)}\sqrt{b_1^2 + b_2^2}$$
  
$$\leq \gamma^2(a_1^2 + a_2^2) + (b_1^2 + b_2^2)$$
  
$$= 2\gamma^2 J + B,$$

so that taking  $\gamma = \sqrt{1 - \lambda K/2}$  with  $\lambda K < 2$  we obtain

$$\sqrt{1 - \lambda K/2} |2E + C| \le (2 - \lambda K)J + B.$$

Using (6.3) we arrive at

$$-\left(\frac{d}{dt}\mathcal{W}[\langle u,v\rangle|\langle u_{\infty},v_{\infty}\rangle] + \lambda\mathcal{W}[\langle u,v\rangle|\langle u_{\infty},v_{\infty}\rangle]\right)$$

$$\geq \sqrt{1-\lambda K/2}|2E+C|+2E+C+F$$

$$= (2E+C)\left(1+\operatorname{sgn}(2E+C)\sqrt{1-\lambda K/2}\right)+F.$$
(6.4)

By the assumption (i) of Theorem 6.1 and (4.9),  $C \ge c_1 \beta |\nabla \phi|_2^2$ . By assumptions (i) and (ii) of Theorem 6.1,  $F \ge (\omega - \lambda/2)\beta |\nabla \phi|_2^2$ .

Therefore if  $2E+C \ge 0$ , then  $\tilde{\lambda} = \min(2/K, 2\omega)$  gives  $-\left(\frac{d}{dt}W + \lambda W\right) \ge 0$  for  $0 < \lambda \le \tilde{\lambda}$ . Otherwise, since  $E \ge 0$ ,  $C \le 2E + C \le 0$  (then, in particular,  $c_1 < 0$ ) and

$$-\left(\frac{d}{dt}\mathcal{W} + \lambda \mathcal{W}\right) \ge \left[c_1\left(1 - \sqrt{1 - \lambda K/2}\right) + \omega - \lambda/2\right] \beta |\nabla \phi|_2^2.$$

Hence, there exists a  $\lambda > 0$  such that the expression in the brackets is positive for  $0 < \lambda < \lambda$ , which implies (6.2).

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