John Forbes Nash, Jr.

Tel qu'en lui-même enfin l'éternité le change

• 1945: published his first paper with his father, *Sag and tension calculations for wire spans using catenary formulas* Electr. Engineering

- 1945: published his first paper with his father, *Sag and tension calculations for wire spans using catenary formulas* Electr. Engineering
- 1950 1954: eight papers on game theory (including his PhD thesis) and one paper on real algebraic geometry

- 1945: published his first paper with his father, *Sag and tension calculations for wire spans using catenary formulas* Electr. Engineering
- 1950 1954: eight papers on game theory (including his PhD thesis) and one paper on real algebraic geometry
- 1954 1966: eight papers on analysis (the imbedding problem for Riemannian manifolds and the elliptic and parabolic regularity result), plus one paper published much later (1995)

- 1945: published his first paper with his father, *Sag and tension calculations for wire spans using catenary formulas* Electr. Engineering
- 1950 1954: eight papers on game theory (including his PhD thesis) and one paper on real algebraic geometry
- 1954 1966: eight papers on analysis (the imbedding problem for Riemannian manifolds and the elliptic and parabolic regularity result), plus one paper published much later (1995)
- 1994 : Nobel prize in economics (shared with John Harsanyi and Reinhard Selten)

- 1945: published his first paper with his father, *Sag and tension calculations for wire spans using catenary formulas* Electr. Engineering
- 1950 1954: eight papers on game theory (including his PhD thesis) and one paper on real algebraic geometry
- 1954 1966: eight papers on analysis (the imbedding problem for Riemannian manifolds and the elliptic and parabolic regularity result), plus one paper published much later (1995)
- 1994 : Nobel prize in economics (shared with John Harsanyi and Reinhard Selten)
- 2015: Abel prize in mathematics (shared with Louis Nirenberg)



• Albert Tucker: linear programming and operations research. The intrusion of mathematics in management.

- Albert Tucker: linear programming and operations research. The intrusion of mathematics in management.
- John von Neumann and Oskar Morgenstern as refugees. The tradition of Mitteleuropa and the Vienna Circle. Human beings as optimizers

- Albert Tucker: linear programming and operations research. The intrusion of mathematics in management.
- John von Neumann and Oskar Morgenstern as refugees. The tradition of Mitteleuropa and the Vienna Circle. Human beings as optimizers
- The problem of strategic behaviour: game theory. A game is a situation where the global outcome (a) depends on individual decisions, and (b) affects differently the decision-makers. The problem is to find a "solution", i.e. to predict what the individual decisions will be (chess).

- Albert Tucker: linear programming and operations research. The intrusion of mathematics in management.
- John von Neumann and Oskar Morgenstern as refugees. The tradition of Mitteleuropa and the Vienna Circle. Human beings as optimizers
- The problem of strategic behaviour: game theory. A game is a situation where the global outcome (a) depends on individual decisions, and (b) affects differently the decision-makers. The problem is to find a "solution", i.e. to predict what the individual decisions will be (chess).
- The case of two decision makers was well understood (von Neumann's minimax theorem). von Neumann and Morgenstern were engaged in a program seeking to find a "solution" for n-person games. The solution they proposed (*Theory of games and economic behaviour*) never gained credence

- Albert Tucker: linear programming and operations research. The intrusion of mathematics in management.
- John von Neumann and Oskar Morgenstern as refugees. The tradition of Mitteleuropa and the Vienna Circle. Human beings as optimizers
- The problem of strategic behaviour: game theory. A game is a situation where the global outcome (a) depends on individual decisions, and (b) affects differently the decision-makers. The problem is to find a "solution", i.e. to predict what the individual decisions will be (chess).
- The case of two decision makers was well understood (von Neumann's minimax theorem). von Neumann and Morgenstern were engaged in a program seeking to find a "solution" for n-person games. The solution they proposed (*Theory of games and economic behaviour*) never gained credence
- the young students around: John Milnor, Lloyd Shapley, Gary Becker, Harold Kuhn, David Gale
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()
 ()

$$u_n(\bar{x}_1, ..., \bar{x}_N) \ge u_n(\bar{x}_1, ... \bar{x}_{n-1}, x_n, \bar{x}_{n+1}, ... \bar{x}_N)$$
 for $1 \le n \le N$

$$u_n(\bar{x}_1, ..., \bar{x}_N) \ge u_n(\bar{x}_1, ... \bar{x}_{n-1}, x_n, \bar{x}_{n+1}, ... \bar{x}_N)$$
 for $1 \le n \le N$

• Nash proved that, if the action sets X_n are convex and compact, and if the u_n are usc and concave wrt x_n, then an equilibrium exists

$$u_n(\bar{x}_1,...,\bar{x}_N) \ge u_n(\bar{x}_1,...\bar{x}_{n-1},x_n,\bar{x}_{n+1},...\bar{x}_N)$$
 for $1 \le n \le N$

- Nash proved that, if the action sets X_n are convex and compact, and if the u_n are usc and concave wrt x_n, then an equilibrium exists
- This is nowadays the standard tool in economics. No one believes in cooperation any more.

$$u_n(ar{x}_1,...,ar{x}_N) \ge u_n(ar{x}_1,...ar{x}_{n-1},x_n,ar{x}_{n+1},...ar{x}_N)$$
 for $1 \le n \le N$

- Nash proved that, if the action sets X_n are convex and compact, and if the u_n are usc and concave wrt x_n, then an equilibrium exists
- This is nowadays the standard tool in economics. No one believes in cooperation any more.
- Individual rationality (Nash equilibrium) may lead to outcomes which are bad for everyone.

• We are on track for an increase in mean temperatures $> 5^{\circ}C$ by the end of the century. As a matter of comparison, this is exactly what separates us from the last ice age, when most of Europe was under glaciers. Temperatures around the Mediterranean are set to increase by $> 10^{\circ}C$ in summertime

- We are on track for an increase in mean temperatures $> 5^{\circ}C$ by the end of the century. As a matter of comparison, this is exactly what separates us from the last ice age, when most of Europe was under glaciers. Temperatures around the Mediterranean are set to increase by $> 10^{\circ}C$ in summertime
- Let us consider N nations undertaking a climate policy. The cost of such a policy is c, the benefit is nB, where n is the number of nations participating.

- We are on track for an increase in mean temperatures $> 5^{\circ}C$ by the end of the century. As a matter of comparison, this is exactly what separates us from the last ice age, when most of Europe was under glaciers. Temperatures around the Mediterranean are set to increase by $> 10^{\circ}C$ in summertime
- Let us consider N nations undertaking a climate policy. The cost of such a policy is c, the benefit is nB, where n is the number of nations participating.
- If everyone participates, benefit is NB >> c for everyone. Evidently, it is to everyone's benefit. Will everyone participate ?

• If France participates, benefit for France is NB and cost is c, so the balance is NB - c

- 一司

- If France participates, benefit for France is NB and cost is c, so the balance is NB c
- If France does not participate, benefit for France is (N-1) B but cost is zero. If (N-1) B > NB c, or c > B, France will find it to its advantage not to participate. It lets the others do the work, and benefits from the result, It is a free rider.



- If France participates, benefit for France is NB and cost is c, so the balance is NB c
- If France does not participate, benefit for France is (N-1)B but cost is zero. If (N-1)B > NB c, or c > B, France will find it to its advantage not to participate. It lets the others do the work, and benefits from the result, It is a free rider.
- Everyone does the same calculation, everyone tries to free ride on the others, so no one participates. This is exactly what has been going on for twenty years, and which will happen again in Paris this December (COP 21).

- If France participates, benefit for France is NB and cost is c, so the balance is NB c
- If France does not participate, benefit for France is (N-1)B but cost is zero. If (N-1)B > NB c, or c > B, France will find it to its advantage not to participate. It lets the others do the work, and benefits from the result, It is a free rider.
- Everyone does the same calculation, everyone tries to free ride on the others, so no one participates. This is exactly what has been going on for twenty years, and which will happen again in Paris this December (COP 21).
- Not participating is a Nash equilibrium, and it is the only one. We are firmly on track for a 5°C increase in mean temperatures (15 in the Arctic)

This is in some sense the reverse: two individuals try to agree on an outcome. We represent the set of possible outcomes as a set A ⊂ R²: individual i seeks to maximize the coordinate x_i. We seek a fair outcome s (A) to the bargaining problem.

Game theory Nash's solution to the bargaining problem

- This is in some sense the reverse: two individuals try to agree on an outcome. We represent the set of possible outcomes as a set A ⊂ R²: individual i seeks to maximize the coordinate x_i. We seek a fair outcome s (A) to the bargaining problem.
- Nash assumed that the solution s (A) ∈ A to the bargaining problem satisfies the following:

- This is in some sense the reverse: two individuals try to agree on an outcome. We represent the set of possible outcomes as a set A ⊂ R²: individual i seeks to maximize the coordinate x_i. We seek a fair outcome s (A) to the bargaining problem.
- Nash assumed that the solution s (A) ∈ A to the bargaining problem satisfies the following:
 - (axiom 1) if $(x_1, x_2) \in A$ and there exists $(y_1, y_2) \in A$ such that $y_1 > x_1$ and $y_2 > x_2$, then $(x_1, x_2) \notin s(A)$

- This is in some sense the reverse: two individuals try to agree on an outcome. We represent the set of possible outcomes as a set A ⊂ R²: individual i seeks to maximize the coordinate x_i. We seek a fair outcome s (A) to the bargaining problem.
- Nash assumed that the solution s (A) ∈ A to the bargaining problem satisfies the following:
 - (axiom 1) if $(x_1, x_2) \in A$ and there exists $(y_1, y_2) \in A$ such that $y_1 > x_1$ and $y_2 > x_2$, then $(x_1, x_2) \notin s(A)$
 - (axiom 2) if A is symmetric, then s(A) is the highest point $(x, x) \in S$

- This is in some sense the reverse: two individuals try to agree on an outcome. We represent the set of possible outcomes as a set A ⊂ R²: individual i seeks to maximize the coordinate x_i. We seek a fair outcome s (A) to the bargaining problem.
- Nash assumed that the solution s (A) ∈ A to the bargaining problem satisfies the following:
 - (axiom 1) if $(x_1, x_2) \in A$ and there exists $(y_1, y_2) \in A$ such that $y_1 > x_1$ and $y_2 > x_2$, then $(x_1, x_2) \notin s(A)$
 - (axiom 2) if A is symmetric, then s(A) is the highest point $(x, x) \in S$
 - (axiom 3) if $A_1 \subset A_2$ and $s(A_2) \subset A_1$, then $s(A_1) = s(A_2)$

- This is in some sense the reverse: two individuals try to agree on an outcome. We represent the set of possible outcomes as a set A ⊂ R²: individual i seeks to maximize the coordinate x_i. We seek a fair outcome s (A) to the bargaining problem.
- Nash assumed that the solution s (A) ∈ A to the bargaining problem satisfies the following:
 - (axiom 1) if $(x_1, x_2) \in A$ and there exists $(y_1, y_2) \in A$ such that $y_1 > x_1$ and $y_2 > x_2$, then $(x_1, x_2) \notin s(A)$
 - (axiom 2) if A is symmetric, then s(A) is the highest point $(x, x) \in S$
 - (axiom 3) if $A_1 \subset A_2$ and $s(A_2) \subset A_1$, then $s(A_1) = s(A_2)$
- He proved that, if A is convex and compact, the only solution point $s(A) \in A$ satisfying these three axioms for all A is the point where x_1x_2 is maximized on A

Nash's solution to the bargaining problem

- This is in some sense the reverse: two individuals try to agree on an outcome. We represent the set of possible outcomes as a set A ⊂ R²: individual i seeks to maximize the coordinate x_i. We seek a fair outcome s (A) to the bargaining problem.
- Nash assumed that the solution s (A) ∈ A to the bargaining problem satisfies the following:
 - (axiom 1) if $(x_1, x_2) \in A$ and there exists $(y_1, y_2) \in A$ such that $y_1 > x_1$ and $y_2 > x_2$, then $(x_1, x_2) \notin s(A)$
 - (axiom 2) if A is symmetric, then s(A) is the highest point $(x, x) \in S$

September 13, 2015

- (axiom 3) if $A_1 \subset A_2$ and $s(A_2) \subset A_1$, then $s(A_1) = s(A_2)$
- He proved that, if A is convex and compact, the only solution point $s(A) \in A$ satisfying these three axioms for all A is the point where x_1x_2 is maximized on A
- This result belongs to normative economics: a solution is sought satisfying certain assumptions (fairness), whereas his earlier one belongs to positive economics (what people actually do).

• How different are smooth closed submanifolds *M* of *Rⁿ* from algebraic varieties ?

- How different are smooth closed submanifolds *M* of *Rⁿ* from algebraic varieties ?
- A submanifold M is defined by a set of equations $f_k(x_1, ..., x_n) = 0$, $1 \le n \le N$ and $1 \le k \le K < N$, without singularities or crossings, with the f_k smooth (C^{∞}) . The question is: does it make much of a difference if the f_k are polynomials ?

- How different are smooth closed submanifolds *M* of *Rⁿ* from algebraic varieties ?
- A submanifold M is defined by a set of equations f_k (x₁, ..., x_n) = 0, 1 ≤ n ≤ N and 1 ≤ k ≤ K < N, without singularities or crossings, with the f_k smooth (C[∞]). The question is: does it make much of a difference if the f_k are polynomials ?
- Nash (1952) Tognoli (1973) : none

- How different are smooth closed submanifolds *M* of *Rⁿ* from algebraic varieties ?
- A submanifold M is defined by a set of equations f_k (x₁, ..., x_n) = 0, 1 ≤ n ≤ N and 1 ≤ k ≤ K < N, without singularities or crossings, with the f_k smooth (C[∞]). The question is: does it make much of a difference if the f_k are polynomials ?
- Nash (1952) Tognoli (1973) : none
 - If $\dim M < \frac{n-1}{2}$, then M can be C^{∞} approximated by a nonsingular real algebraic set

- How different are smooth closed submanifolds *M* of *Rⁿ* from algebraic varieties ?
- A submanifold M is defined by a set of equations f_k (x₁, ..., x_n) = 0, 1 ≤ n ≤ N and 1 ≤ k ≤ K < N, without singularities or crossings, with the f_k smooth (C[∞]). The question is: does it make much of a difference if the f_k are polynomials ?
- Nash (1952) Tognoli (1973) : none
 - If $\dim M < \frac{n-1}{2}$, then M can be C^∞ approximated by a nonsingular real algebraic set
 - any compact smooth manifold is diffeomorphic to a smooth connected component of a algebraic variety

• Consider the classical problem in the calculus of variations

$$\min_{u\in H} \int_{\Omega} F(x, u(x), Du(x)) dx$$

where *H* is a suitable class of functions, incorporating boundary conditions. Suppose *F* is C^{∞} . Does the problem have a C^{∞} solution *u*? This is Hilbert's 19th problem (1900)

Regularity of minimizers

Consider the classical problem in the calculus of variations

$$\min_{u\in H}\int_{\Omega}F\left(x,u\left(x\right),Du\left(x\right)\right)dx$$

where *H* is a suitable class of functions, incorporating boundary conditions. Suppose *F* is C^{∞} . Does the problem have a C^{∞} solution *u*? This is Hilbert's 19th problem (1900)

• From 1900 to 1950 (Tonelli, Fondamenti del calcolo degli variazioni) one was able to show that, under suitable growth and convexity assumptions on F, there were weak solutions, typically $u \in W^{k,p}$

Regularity of minimizers

Consider the classical problem in the calculus of variations

$$\min_{u \in H} \int_{\Omega} F(x, u(x), Du(x)) dx$$

where *H* is a suitable class of functions, incorporating boundary conditions. Suppose *F* is C^{∞} . Does the problem have a C^{∞} solution *u*? This is Hilbert's 19th problem (1900)

- From 1900 to 1950 (Tonelli, Fondamenti del calcolo degli variazioni) one was able to show that, under suitable growth and convexity assumptions on F, there were weak solutions, typically $u \in W^{k,p}$
- To prove that u is in fact smooth, there was a two-step procedure:
 (a) show that u satisfies the Euler equation, and (b) show that this implies that u is smooth

Calculus of variations

An example

Consider the problem for $u: \mathbb{R}^N \to \mathbb{R}^K$

 $\int_{\Omega} F(Du) dx$ where $F \in C^{\infty}(\mathbb{R}^{KN})$, $|F(p)| \leq c |p|^2$ and the derivatives $A^n_k(p) := \partial F / \partial p^h_n$ satisfy the growth and ellipticity conditions:

$$|A_k^n(p)| \le c |p|, \quad \left| \frac{\partial A_k^n}{\partial p_m^j}(p) \right| \le c, \quad \frac{\partial A_k^n}{\partial \rho_m^j}(p) \, \xi_n^k \xi_m^j \ge c \, |\xi|^2$$

If u is a minimizer of F, the any derivative $v_i := D_i u$ satisfies the elliptic system:

$$\int_{\Omega} \frac{\partial A_{k}^{n}}{\partial p_{m}^{j}} \left(Du \right) D_{m} \left(v^{j} \right) D_{n} \varphi^{k} dx = 0 \quad \forall \varphi \in W^{1,2} \left(\Omega; R^{K} \right)$$

By bootstrapping this equation, it can be shown that if $u \in C^1$, then $v \in C^1$, and then $u \in C^\infty$ The problem is to start.

Calculus of variations

The Nash - de Giorgi regularity result

• In the scalar case (K = 1), the system reduces to a single equation for the derivative $v_n := \partial u / \partial x^n$:

$$\frac{\partial}{\partial x^{j}} \left(\frac{\partial^{2} F}{\partial p_{i} \partial p_{j}} \left(Du \right) \frac{\partial v}{\partial x^{i}} \right) = 0$$

If u is a weak solution, the coefficients $\frac{\partial A_k^n}{\partial p_m^j} (Du(x))$ are at best L^{∞} (not continuous). So we have an elliptic linear equation with L^{∞} coefficients. Nash, and independently de Giorgi, showed that the solution is Hölder continuous.

Calculus of variations

The Nash - de Giorgi regularity result

• In the scalar case (K = 1), the system reduces to a single equation for the derivative $v_n := \partial u / \partial x^n$:

$$\frac{\partial}{\partial x^{j}}\left(\frac{\partial^{2}F}{\partial p_{i}\partial p_{j}}\left(Du\right)\frac{\partial v}{\partial x^{i}}\right)=0$$

If *u* is a weak solution, the coefficients $\frac{\partial A_k^n}{\partial p_m^j}$ (Du(x)) are at best L^{∞} (not continuous). So we have an elliptic linear equation with L^{∞} coefficients. Nash, and independently de Giorgi, showed that the solution is Hölder continuous.

• In the vector case (K > 1), de Giorgi gave an example of a function F(x, Du) with all imaginable blessings, with solution $u(x) = x/|x|^{\gamma}$. This was extended by Giaquinta and Giusti to a function F(u, Du) with minimizer u(x) = x/|x|

Is Riemannian geometry real ?

In his thesis Über die Hypothesen, die der Geometrie zugrunde legen (1854), Bernhard Riemann defined an intrinsic geometry on manifolds by a quadratic form $\sum g_{ij}(x) \xi^i \xi^j$ on the tangent space at x. The question immediately arose: does that bring anything new ? Can every such Riemannian manifold be realized as a submanifold of Euclidian space ? Note that, in 1827, Carl Friedrich Gauss had found an obstruction: the curvature is preserved by any isometry. It is the famous theorema egregium. As a consequence, for instance, a sphere of radius R cannot be compressed isometrically into a ball of radius r < R (look at the curvature of extreme points)

Isometric embedding

The smooth case

Locally, the problem was solved by Janet. The global problem was solved by Nirenberg, in the particular case of a two-dimensional sphere (which can be imbedded as a convex hypersurface in \mathbb{R}^3), and in the general case by Nash: any compact Riemannian manifold can be imbedded isometrically into an Euclidian space of sufficiently high dimension. An isometry is understood as a one-to-one map $\varphi: M \to \mathbb{R}^N$ which preserves the given quadratic form g(x) on T_xM :

$$\sum_{j,k=1}^{K} \left(\frac{\partial \varphi^{n}}{\partial x^{j}} \left(x \right) \xi^{j}, \frac{\partial \varphi^{n}}{\partial x^{k}} \left(x \right) \xi^{k} \right)_{R^{N}} = \sum_{n=1}^{K} g_{jk} \left(x \right) \xi^{j} \xi^{k}$$
$$\sum_{n=1}^{N} \frac{\partial \varphi^{n}}{\partial x^{j}} \left(x \right) \frac{\partial \varphi^{n}}{\partial x^{k}} \left(x \right) = g_{jk} \left(x \right)$$

Isometric embedding

The hard inverse function theorem

Nash's proof goes by showing that the set of Riemannian structures on M (ie the set of fields g(x)) which can be isometrically embedded is both open and closed. The latter is relatively easy, the former is quite difficult. Consider the map $\Phi(u) = F(x, u, Du)$, with $u : \mathbb{R}^N \to \mathbb{R}^K$. Let us try to apply the IVT to show the image is open. Differentiating at u_0 , we get

 $\Phi'(u_0) v = F_x + F_u v + F_p D v$

So $\Phi'(u)$ maps C^k into C^{k-1} . This derivative is not recovered by inversion: $\Phi'(u) v = w$ with $w \in C^{k-1}$ does not imply that $v \in C^k$ except in very special cases. There is a global loss of derivatives, and the usual IVT does not apply. Nash constructed a "hard" IVT to solve the embedding problem. Simultaneously, Kolmogorov in the USSR constructed such an IVT to solve the resonance problem in celestial mechanics. (see the talk by Séré for the state of the art)

The non-smooth case

We will now consider C^1 embeddings $\varphi: M \to R^N$. Since φ is C^1 only, the Riemannian structure (including curvature) no longer makes sense, only the metric is left. Such an embedding will be called isometric if the length of any path c(t), $0 \le t \le 1$, on M, coïncides with the length of its image $\varphi(c(t))$ in R^N .

Theorem (Nash-Kuiper)

Let $f: M \to R^N$ be any map which is contracting:

$$||f(x) - f(y)|| \le ||x - y||$$

Then, for any $\varepsilon > 0$, there exists a C^1 embedding $\varphi : M \to \mathbb{R}^N$ such that $\|f(x) - \varphi(x)\| \le \varepsilon$ on M

The non-smooth case

The NK theorem has remarkably counterintuitive consequences: a sphere of radius R can be sent isometrically into a ball of radius r < R (which is not possible for C^2), and a piece of paper of format A4 can be put into one's pocket without folding.

This result was the first in a line of research with has been extremely active

• Gromov's h-principle (if there are no topological obstructions, there are no holonomy obstructions) and convex integration

The non-smooth case

The NK theorem has remarkably counterintuitive consequences: a sphere of radius R can be sent isometrically into a ball of radius r < R (which is not possible for C^2), and a piece of paper of format A4 can be put into one's pocket without folding.

This result was the first in a line of research with has been extremely active

- Gromov's h-principle (if there are no topological obstructions, there are no holonomy obstructions) and convex integration
- the existence of non-energy preserving solutions of the Euler equations in fluid mechanics

The nature of genius

September 13, 2015 17 / 17

- < P

æ