

Discussion of Eric Moulines talk "Some results on adaptive MCMC Algorithms"

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the Results

- ▶ I would like to congratulate the authors for this very impressive and subtle paper!
- ▶ it develops theory for establishing **ergodicity** and **SLLN** in very general scenarios
- ▶ the theory is extremely powerful and allows to address **the two most important and challenging Adaptive/Interacting algorithms** in the field.

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- ▶ In case of the original **Adaptive Metropolis** algorithm of Haario et al.,
- ▶ the theory **implies** convergence of **marginal distributions** to π .
- ▶ These conclusions have been verified for $\mathcal{X} = \mathbb{R}^d$ in the **geometrically ergodic** setting, for **super-exponentially** decaying targets, improving the recent result of Saksman and Vihola (2010).
- ▶ The analysis of the Interacting Tempering Algorithm of Kou et al is even more impressive,
- ▶ Interacting Tempering has been analyzed for the first time in this generality,
- ▶ In particular, in the **geometrically ergodic** setting
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Technical Conditions for ergodicity

- ▶ The Theory is very delicate and is building on the following crucial conditions.
- ▶ **A1:** For any $\theta \in \Theta$, there exists π_θ , s.t. $\pi_\theta = P_\theta \pi_\theta$.
- ▶ **A2(a):** For any $\epsilon > 0$, there exists a non-decreasing sequence $r_\epsilon(n)$, s.t. $\limsup_{n \rightarrow \infty} r_\epsilon(n)/n = 0$ and

$$\limsup_{n \rightarrow \infty} \mathbb{E} \left[\|P_{\theta_{n-r_\epsilon(n)}}^{r_\epsilon(n)}(X_{n-r_\epsilon(n)}, \cdot) - \pi_{\theta_{n-r_\epsilon(n)}}\|_{TV} \right] \leq \epsilon.$$

- ▶ **A2(b):** For any $\epsilon > 0$,

$$\lim_{n \rightarrow \infty} \sum_{j=0}^{r_\epsilon(n)-1} \mathbb{E} [D(\theta_{n-r_\epsilon(n)+j}, \theta_{n-r_\epsilon(n)})] = 0.$$

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$$\forall \delta > 0, \epsilon > 0, \exists M_{\epsilon, \delta} \quad \text{s.t.} \quad \forall n \quad P(M_\epsilon(X_n, \theta_n) \leq M_{\epsilon, \delta}) \geq 1 - \delta.$$

- ▶ **Diminishing Adaptation C(b)**: $\lim_{n \rightarrow \infty} \mathbb{E} [D(\theta_{n-1}, \theta_n)] = 0$.

- ▶ **C(a), C(b) \Rightarrow A2(a), A2(b)** by taking e.g. $r_\epsilon(n) = M_{\epsilon/2, \epsilon/2}$.

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- ▶ Therefore $A2(a), A2(b)$ generalize $C(a), C(b)$ (rather than weaken) and the generalization is in settings where $r_\epsilon(n)$ needs to grow to ∞ as $n \rightarrow \infty$.
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What Adaptive MCMC is designed for?

- ▶ In a **typical Adaptive MCMC setting** the parameter space Θ is **large**
- ▶ there is an **optimal** $\theta_* \in \Theta$ s.t. P_{θ_*} **converges quickly**.
- ▶ there are **arbitrary bad values** in Θ , say if $\theta \in \bar{\Theta} - \Theta$ then P_θ is **not ergodic**.
- ▶ if $\theta \in \Theta_* :=$ a region **close to θ_*** , then P_θ shall **inherit good convergence properties of P_{θ_*}** .
- ▶ When using adaptive MCMC we **hope** θ_n will eventually find the region Θ_* and stay there **essentially forever**. And that the adaptive algorithm \mathcal{A} will inherit the good convergence properties of Θ_* in the limit.
- ▶ We are looking for a Theorem:
You can actually run your Adaptive MCMC algorithm \mathcal{A} , and it will do what it is supposed to do! (under verifiable conditions)

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- ▶ In a **typical Adaptive MCMC setting** the parameter space Θ is **large**
- ▶ there is an **optimal** $\theta_* \in \Theta$ s.t. P_{θ_*} **converges quickly**.
- ▶ there are **arbitrary bad values** in Θ , say if $\theta \in \bar{\Theta} - \Theta$ then P_θ is **not ergodic**.
- ▶ if $\theta \in \Theta_* :=$ a region **close to θ_*** , then P_θ shall **inherit good convergence properties of P_{θ_*}** .
- ▶ When using adaptive MCMC we **hope** θ_n will eventually find the region Θ_* and stay there **essentially forever**. And that the adaptive algorithm \mathcal{A} will inherit the good convergence properties of Θ_* in the limit.
- ▶ We are looking for a Theorem:
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a new class: AdapFail Algorithms

- ▶ an adaptive algorithm $\mathcal{A} \in \text{AdapFail}$, if with positive probability, it is asymptotically less efficient than ANY MCMC algorithm with fixed θ .
- ▶ more formally, AdapFail can be defined e.g. as follows: $\mathcal{A} \in \text{AdapFail}$, if

$$\forall \epsilon_* > 0, \exists 0 < \epsilon < \epsilon_*, \exists \delta > 0, \text{ s.t. } \inf_{\theta \in \Theta} \lim_{n \rightarrow \infty} P\left(M_\epsilon(X_n, \theta_n) > M_\epsilon(\tilde{X}_n, \theta)\right) > \delta.$$

- ▶ **QuasiLemma**: Assume the geometrically ergodic setting and assume Θ is big enough to contain arbitrary slowly converging kernels.
If containment doesn't hold for \mathcal{A} then $\mathcal{A} \in \text{AdapFail}$.
- ▶ If A2(a), A2(b) hold but C(a), C(b) do not hold, then $\mathcal{A} \in \text{AdapFail}$, but it deteriorates slowly enough (due to more restrictive A2(b)), so that marginal distributions (still) converge, and SLLN (still) holds.

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some QuasiConjectures

- ▶ If **containment does not hold** for \mathcal{A} then the **CLT does not hold** for \mathcal{A} .
(Can one prove that $\sigma_{\text{as}} > K$ for arbitrary large K ?)
- ▶ the Adaptive Metropolis $\notin \text{AdapFail}$,
(looking forward to talks by Matti and Yves that may be related)
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Design of Algorithms

- ▶ We have substantial insight into ergodicity of adaptive MCMC
- ▶ is it possible to use this to **design** algorithms that are **robust** and **easier to analyze**?
- ▶ Ex. for the Adaptive Metropolis, consider the following slight modification [Roberts, Rosenthal (2009)] with proposal distribution

$$Q_n(x, \cdot) = (1 - \beta)\mathcal{N}(x, (2.38)^2\Sigma_n/d) + \beta\mathcal{N}(x, (0.1/d)Id).$$

- ▶ the above modification appears more tractable and **C(a)**, **C(b)** are known to hold for both, **exponentially** and **super-exponentially** decaying tails (Bai et al 2009).
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